Water Power Technologies Office 2019 Peer Review





Advanced WEC Dynamics and Controls

2.1.2.701

Marine and Hydrokinetics Program

Oct. 9, 2019

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Sandia National Labs

Project Overview



Project Summary	Project Information	
Wide body of research has shown massive potential for control to improve WEC performance (more power & reduced loads) This is a few size of the few size	Project Principal Investigator(s) Ryan Coe & Giorgio Bacelli Sandia National Labs	
 This projects focus is realizing those benefits for WEC developers by creating a tractable engineering workflow 	WPTO Lead	
	Bill McShane	
Project Objective & Impact		
The goal of this project has been to deliver actionable methods for WEC developers to apply in order to improve the performance of their devices via control. This goal has been achieved and extended upon as our research has led us to better understand the need to incorporate the knowledge available from WEC control design into the large WEC design	Project Partners/Subs	
	US Navy Michigan Tech. Oregon State University	
	Project Duration	
process.	Oct. 2016Sept. 2019	

Alignment with the Program



Marine and Hydrokinetics (MHK) Program Strategic Approaches

Data Sharing and Analysis

Foundational and Crosscutting R&D

Technology-Specific Design and Validation

Reducing
Barriers to
Testing

Alignment with the MHK Program



Foundational and Crosscutting R&D

- Drive innovation in components, controls, manufacturing, materials and systems with early-stage R&D specific to MHK applications
- Develop, improve, and validate numerical and experimental tools and methodologies needed to improve understanding of important fluidstructure interactions
- Improve MHK resource assessments and characterizations needed to optimize devices and arrays, and understand extreme conditions
- Collaboratively develop and apply quantitative metrics to identify and advance technologies with high ultimate techno-economic potential for their market applications

- Sandia leverages expertise from aerospace, defense, and robotics control to deliver methodologies for WEC device and control design capable of delivering dramatic improvements in performance and economic viability.
- To deliver a robust framework for WEC device and control testing and design, Sandia has developed and validated numerous methodologies and experimental techniques. The methods provide WEC developers with a tractable path for WEC and control design. Experimental methods have increased the effectiveness of wave tank testing, enabling WEC developers to accomplish more in less tank time.

Alignment with the MHK Program



Technology-Specific Design and Validation

- Validate performance and reliability of systems by conducting in-water tests of industry-designed prototypes at multiple relevant scales
- Improve methods for safe and cost efficient installation, grid integration, operations, monitoring, maintenance, and decommissioning of MHK technologies
- Support the development and adoption of international standards for device performance and insurance certification
- Evaluate current and potential future needs for MHK-specific IO&M infrastructure (vessels, port facilities, etc.) and possible approaches to bridge gaps

- Sandia's Advanced WEC Dynamics and Controls project has produced the most popular dataset on MHK-DR.
- Sandia's improved testing methods are being used heavily for the update of IEC 62600-103 ("Best practices and recommended procedures for the testing of preprototype scale devices").

Project Budget



FY17	FY18	FY19 (Q1 & Q2 Only)	Total Project Budget (FY17-FY19 Q1 & Q2)	
Costed	Costed	Costed	Total Costed	Total Authorized
\$1,381K	\$1,132K	\$470K	\$2,983K	\$3,528K

- Leverage synergies/funding from
 - MARINET2
 - Sandia internal funding (SWEPT Lab)

Management and Technical Approach



- Problem: Clear potential for improvements based on WEC control since 1970s, but limited real-world benefits
- Goal: Holistic approach to realize these gains and provide a basis for co-design
- Strategy: Leverage methods and tools proven successful in other applications to provide a tractable work flow for WEC control design

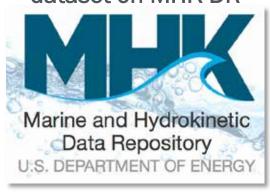
End-User Engagement and Dissemination Strategy



Annual workshop & 4 webinars



Most popular public dataset on MHK-DR



Broad ranging research collaborations



3 patent applications (1 granted)



Private developer collaborations



40+ project publications

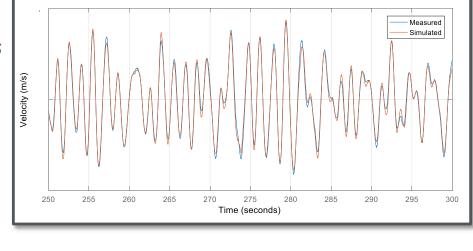


Technical Accomplishments





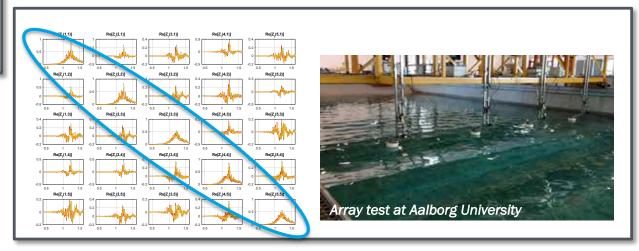
Testing
practices
deliver better
results in less
time

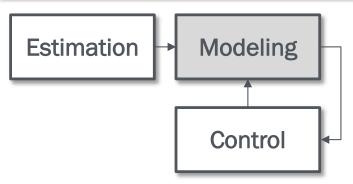


Models better than 90% accurate

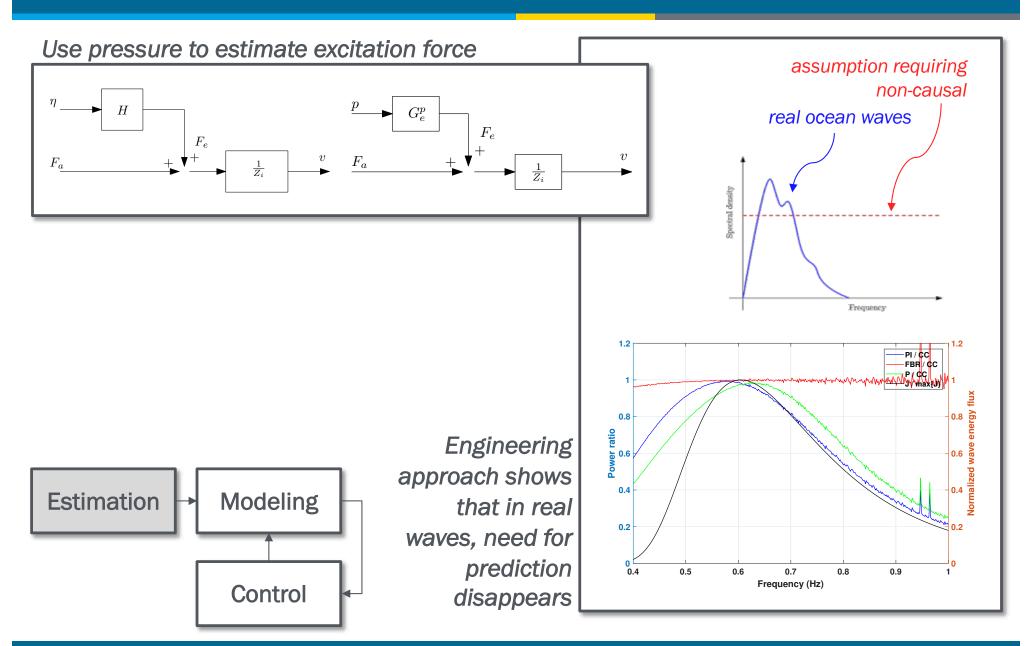
SWEPTLAB 9/19/2016 11-14-57-17

Works just as well on multi-device & multi-DOF systems





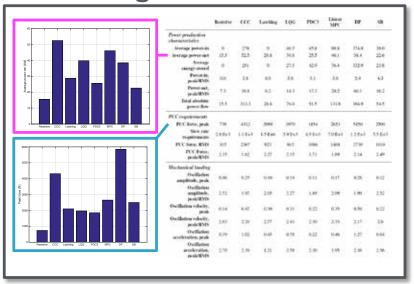
Technical Accomplishments (Cont.)



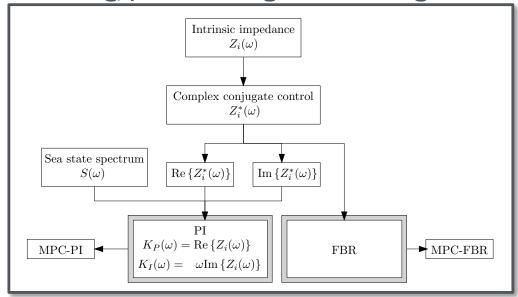
Technical Accomplishments (Cont.)



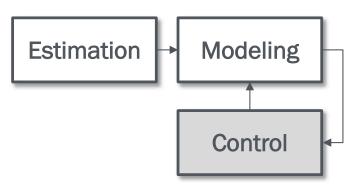
Control design focused on LCOE

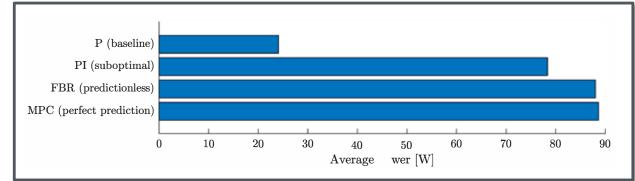


Feedback approach based on impedance matching, provides insight for co-design

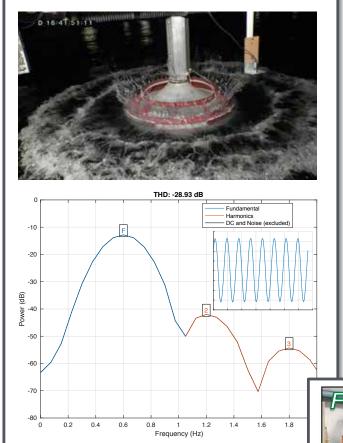


Nearly optimal performance w/o prediction



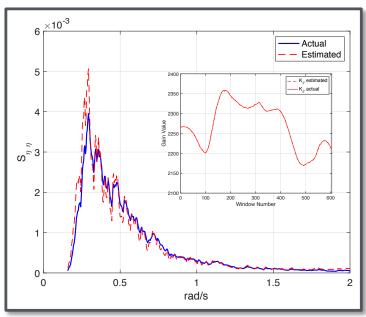


Progress Since Project Summary Submittal



Just how nonlinear are WEC hydrodynamics?

Self-tuning controller for changing weather



Are these methods really device-agnostic?





Future Work



- Problem: WEC PTO design is <u>linchpin</u> enabling efficiency gains and load reduction from advanced controls to be realized in terms of LCOE (<u>absorbed</u> power -> <u>generated</u> power)
- **Goal:** Develop method for <u>co-design</u> of WEC PTO and control systems utilizing predictionless control to deliver 100% power increase in full-scale WEC

