

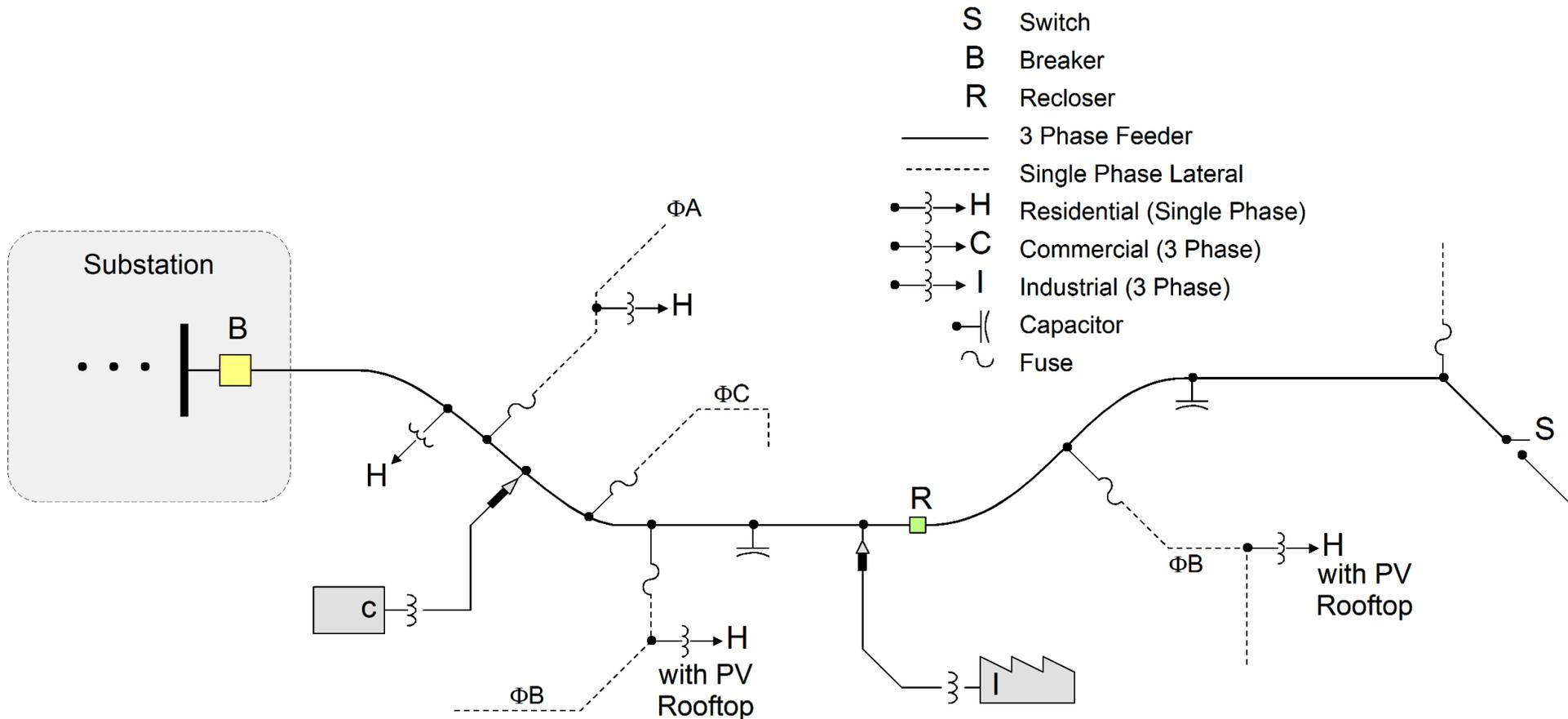
Distributed Dynamic State Estimator: Extension to Distribution Feeders

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Workshop on
Challenges for Distribution Planning, Operational and Real-time Planning Analytics
U.S. Department of Energy, Solar Energy Technologies Office
May 16 – 17, 2019

DS-SE Challenges



Issues, Challenges & Opportunities

Available Measurements in Distribution Feeders

Substation Data

Recloser Data

Capacitor Control Data

Smart Meter data (secondary)

Customer Owned Distributed Resources with Metering

State Estimation is Extended to Customer Systems

Need to integrate existing measurements that may be at varying time scales

Typically not Enough for Full Observability

Feeder Sections May Be not Observable

Need to augment measurements set (virtual, derived, pseudo)

Implementation Approaches Become Important

Multiphase Modeling is a Necessity

Many More Power Devices than Transmission Systems

Measurement data at disparate time scales (very important obstacle)

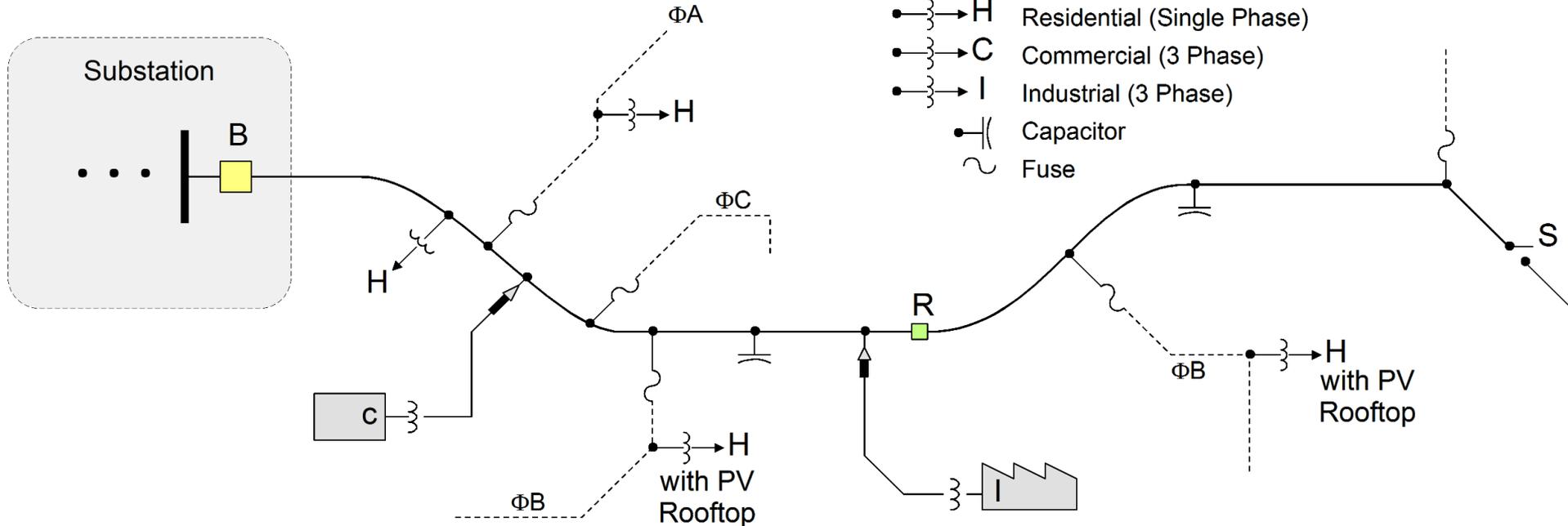
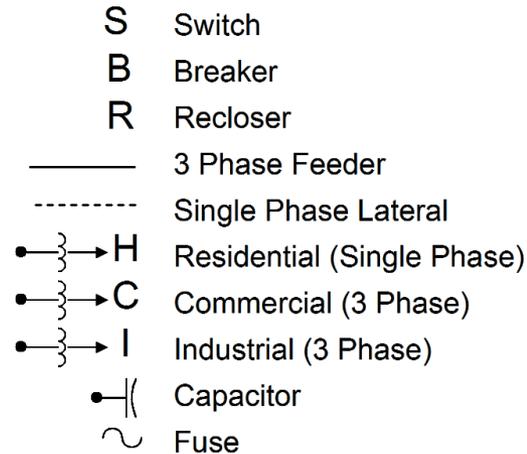
Object Oriented DS-SE Formulation

Use Existing Measurements
Supplement with

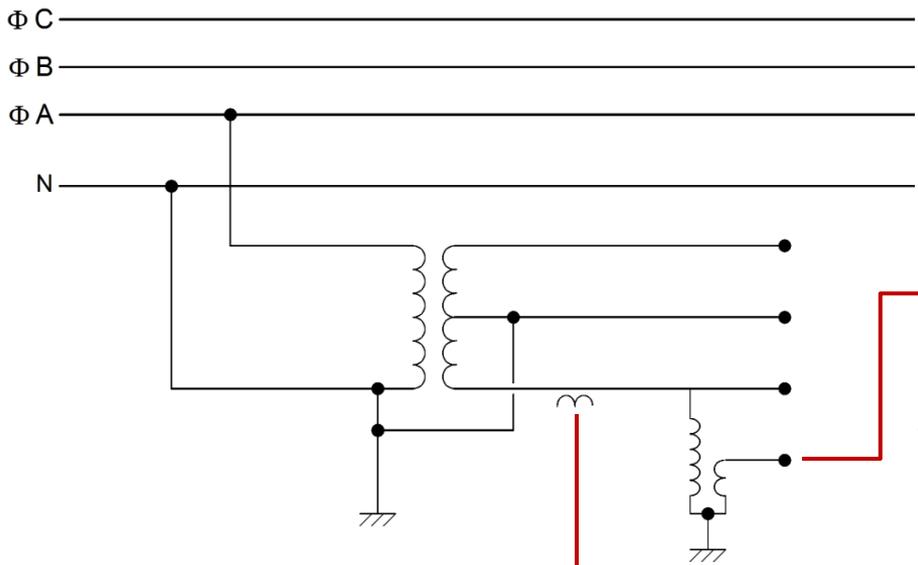
Virtual, Derived, and Pseudo-measurements

Distributed State Estimation:
Arbitrarily partition DS into Sections
Need: At Least One GPS Sync Meas
At Each Section

Formulation



Object Oriented DS-SE



Across (Voltage) Measurement:

$$\tilde{z}_j(t) = \tilde{x}_j(t) + \eta_j$$

Through (Current, Torque, etc.) Measurement:
Measurement $z_j(t)$ represents a quality associated with one row of the Object oriented model

$$\tilde{z}_j(t) = \text{row k of Object Oriented Model} + \eta_j$$

Object Oriented Model

$$\begin{bmatrix} \tilde{I}(t) \\ 0 \\ \tilde{I}(t_m) \\ 0 \end{bmatrix} = Y_{eq} \begin{bmatrix} \tilde{V}(t) \\ \tilde{Y}(t) \\ \tilde{V}(t_m) \\ \tilde{Y}(t_m) \end{bmatrix} + \begin{bmatrix} \tilde{V}^T(t) & \tilde{Y}^T(t) & \tilde{V}^T(t_m) & \tilde{Y}^T(t_m) \end{bmatrix} \cdot F_{eq} \cdot \begin{bmatrix} \tilde{V}(t) \\ \tilde{Y}(t) \\ \tilde{V}(t_m) \\ \tilde{Y}(t_m) \end{bmatrix} - B_{eq}$$

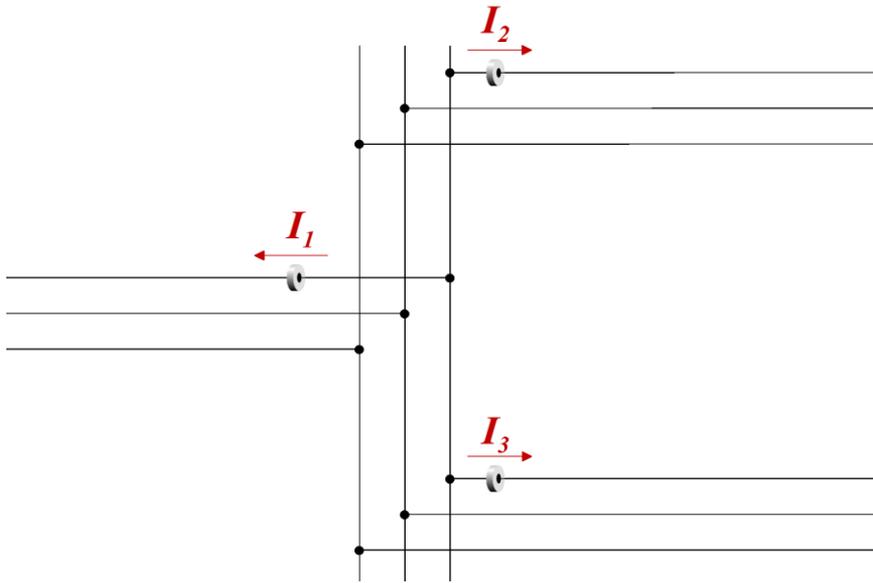
Row k

QSE states are
Phasors, Speed, etc

where
$$B_{eq} = \sum_i A_i \cdot \begin{bmatrix} \tilde{V}(t-i \cdot h) \\ \tilde{Y}(t-i \cdot h) \end{bmatrix} + \sum_i B_i \cdot \begin{bmatrix} \tilde{I}(t-i \cdot h) \\ 0 \end{bmatrix} + C$$

Distributed State Estimation

Virtual Measurements - Examples



Any Equation of a Model Used in the State Estimation

Example: The Equation for the Transformer Internal Voltage

$$0 = \tilde{I}_1 + \tilde{I}_2 + \tilde{I}_3$$



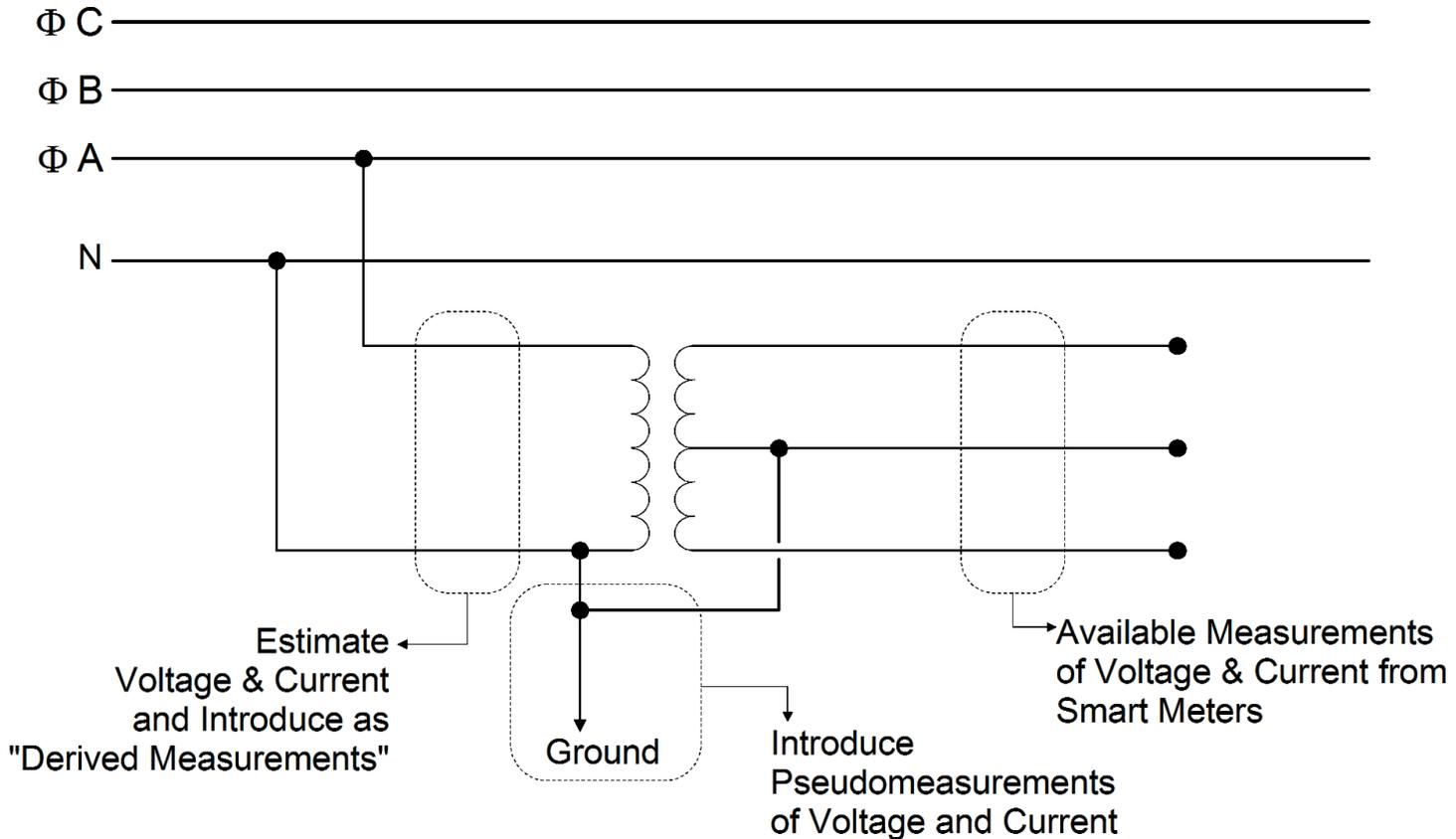
Virtual Measurement

$z_m = 0$ value

$\sigma_m = 0$ standard deviation

Distributed State Estimation

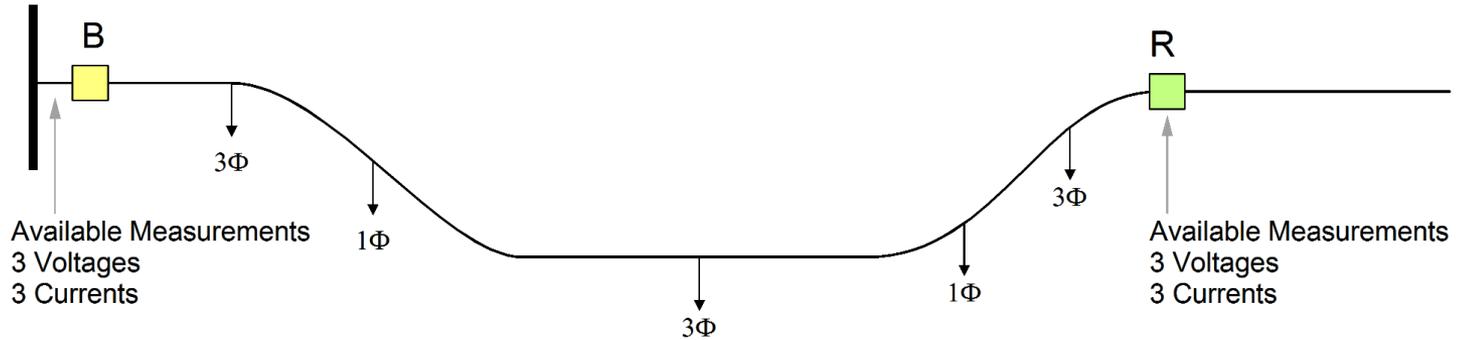
Derived and Pseudo-Measurements - Examples



Distributed State Estimation

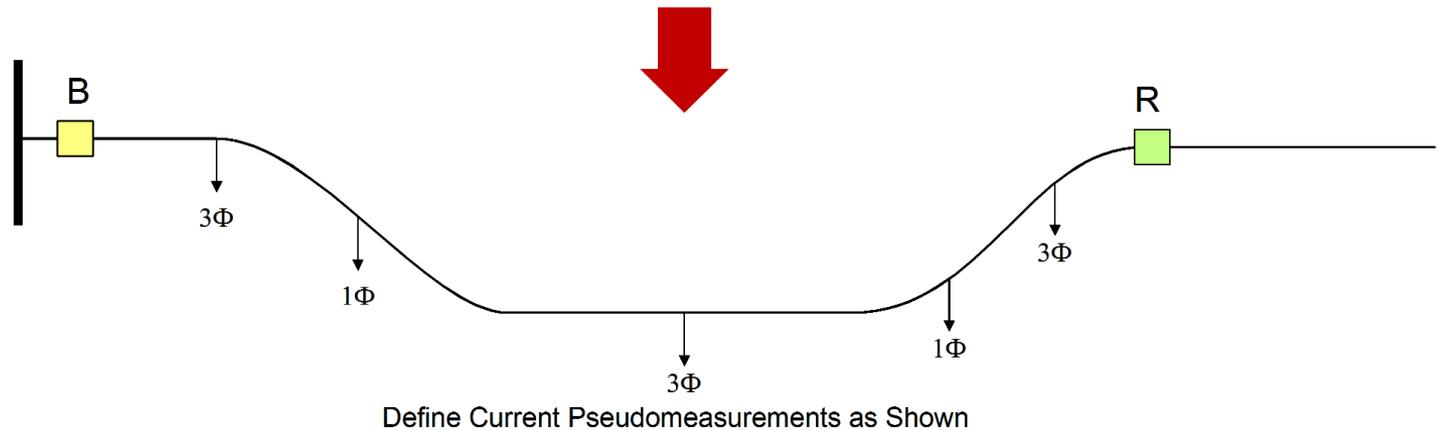
Pseudo-Measurements - Examples

In a Feeder, there may be sections without instrumentation



Pseudo-Measur. Can Provide the Link Towards Full Observability

An example is shown



Pseudomeasurement Values : Distribute the Current Difference from Breaker to Recloser to the Loads / Phases

Uncertainty : High

Distributed SE Measurement Set

Non-Synchronized Measurements

Non-GPS Synchronized Relays provide phasors referenced on “phase A Voltage”. The phase A Voltage phase is ZERO.

The SuperC provides a reliable and accurate estimate of the phase A voltage phasor.

$$\tilde{A}_{sync} = \tilde{A}_{meas} e^{j\alpha}$$

$$\begin{aligned} \tilde{A}_{sync} &= \tilde{A}_{meas} e^{j\alpha} = \\ &A_{real} \cos \alpha - A_{imag} \sin \alpha + \\ &j(A_{real} \sin \alpha + A_{imag} \cos \alpha) \end{aligned}$$

α is a synchronizing unknown variable

$\cos(\alpha)$ and $\sin(\alpha)$ are unknown variables in the state estimation algorithm

There is one α variable for each non-synchronized relay

DS-SE: Algorithm

$$\text{Min } J = \sum_{v \in \text{phasor}} \frac{\tilde{\eta}_v^* \tilde{\eta}_v}{\sigma_v^2} + \sum_{v \in \text{non-syn}} \frac{\eta_v \eta_v}{\sigma_v^2}$$

Solution

$$x^{v+1} = x^v + A[z - h(x)]$$

where: $A = [H^T W H]^{-1} [H^T W]$

Efficiency

Demonstrated the ability to execute the state estimator 60 times per second for substantial size substations.

There is still space for improved computational efficiency.

Demonstration Projects

Application to PV Farms (1.16 MW Array)



What is Monitoring via State Estimation?

Implementation: Inclusion of Both AC and DC sides

System is Represented with a Set of Differential Equations (DE) in terms of the system state

SYSTEM STATE: Voltages at each node of the system (see example system)

The State Estimator Fits the Streaming Data to the Model of the System via a least square approach.

END RESULT: Best estimate of system state, i.e. voltages at each node

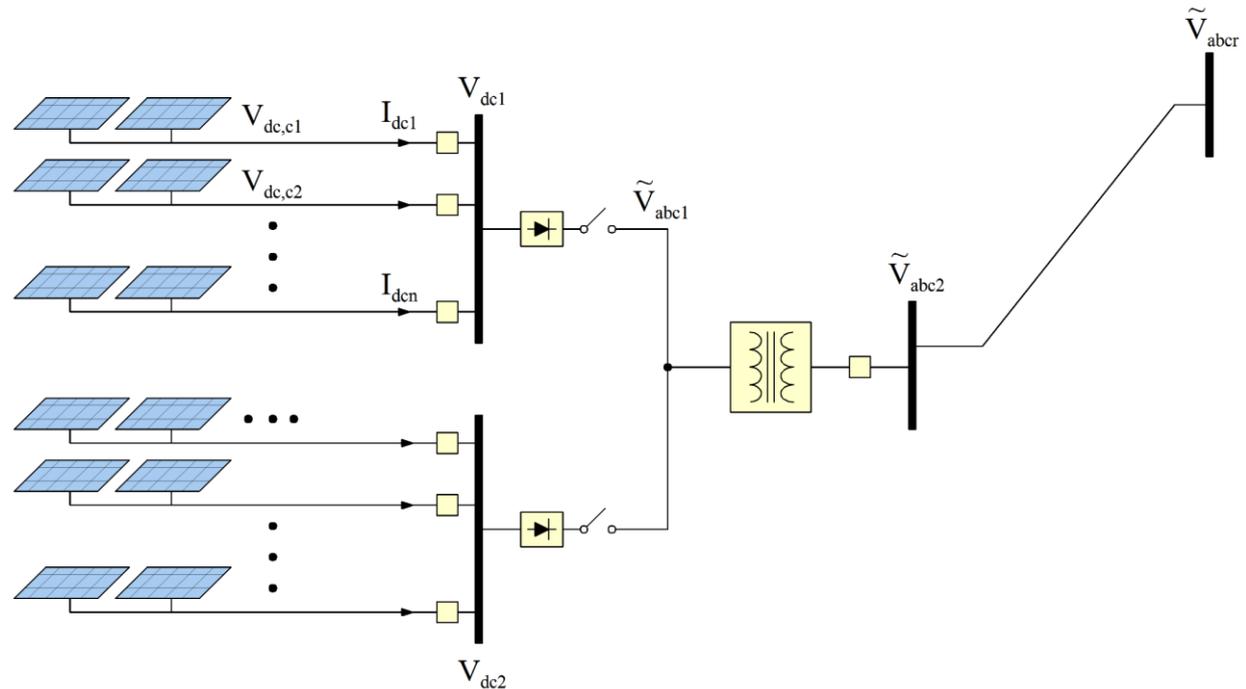
The Estimator is Defined

in Terms of:

- Model
- State
- Measurement Set
- Estimation Method

Observability

Redundancy



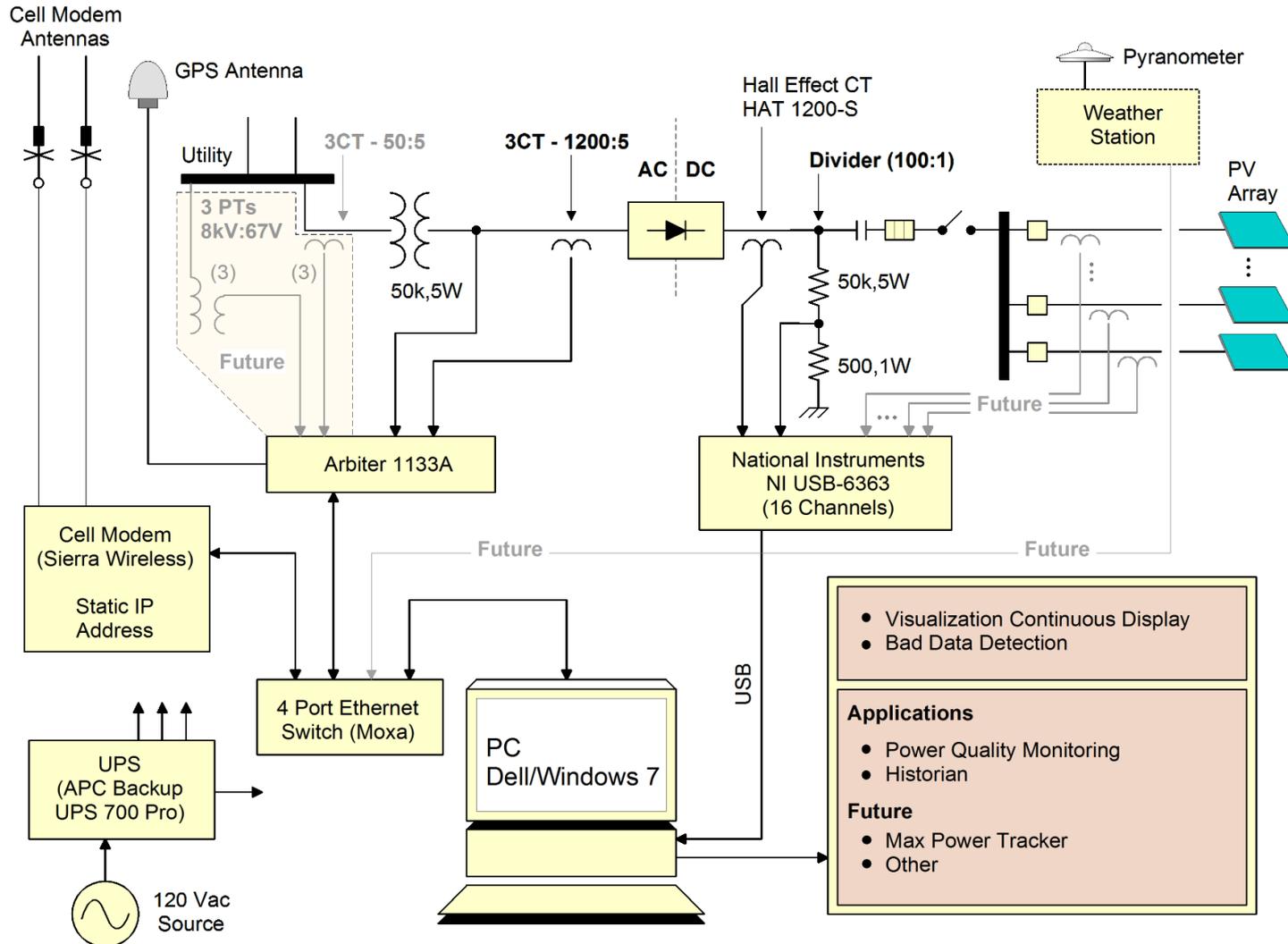
1.16 MW PV Array

4224 Panels (270-280W)
2 Solarex Inverters (500kW each)
10 Combiners per Inverter



Field Demonstration

1.16 PV Array



- Visualization Continuous Display
 - Bad Data Detection
- Applications**
- Power Quality Monitoring
 - Historian
- Future**
- Max Power Tracker
 - Other

Model Overview

PV Interconnection



Switch Gear



PV Panels



Substation

Buckman PV Array WinIGS Model

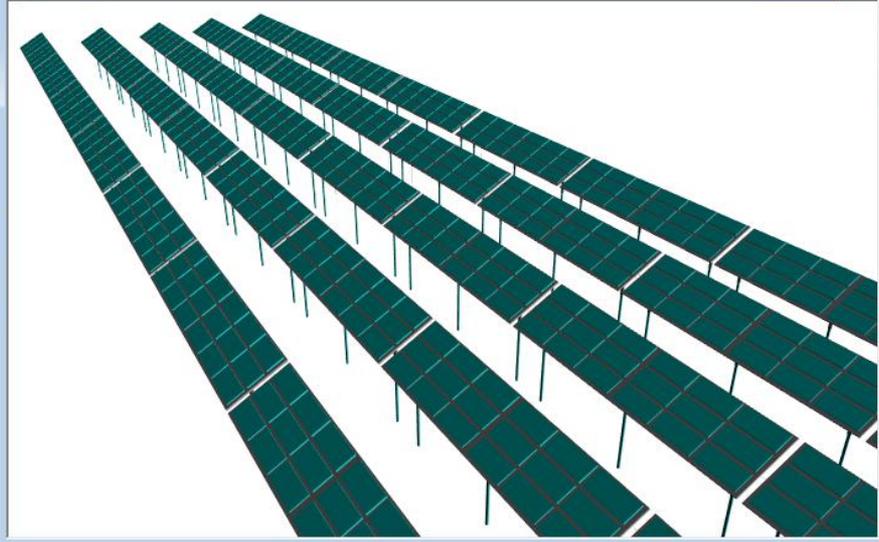
WinIGS-Q

File Edit View Help Window

Run Pause STOP 0.00000 s 0.00000 s 128X

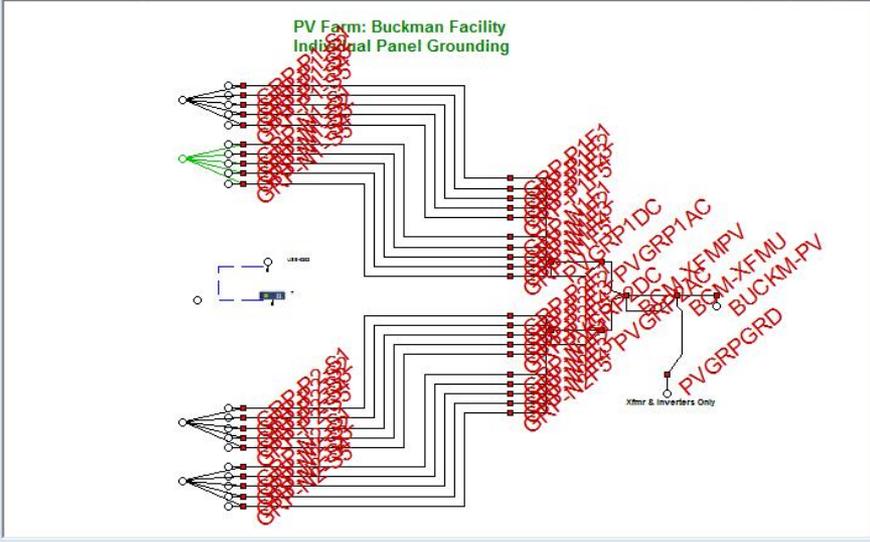
Grounding System 0.5 MW PV Farm Module, Code 139, ID = 32, File = BUCKMAN-DEVELOPMENT.003

Grounding System 0.5 MW PV Farm Module - Case: BUCKMAN-DEVELOPMENT



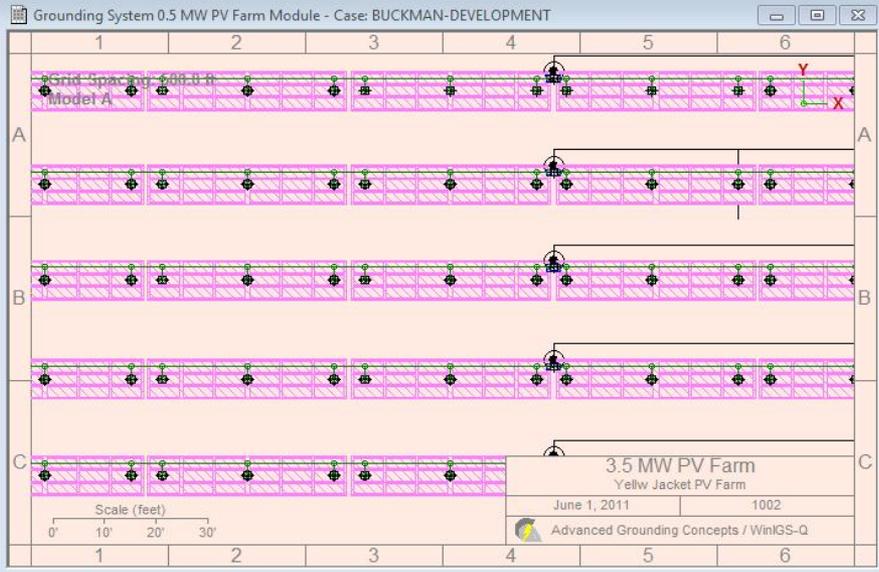
Buckman PV Array - Case: BUCKMAN-DEVELOPMENT

PV Farm: Buckman Facility
Individual Panel Grounding



Grounding System 0.5 MW PV Farm Module - Case: BUCKMAN-DEVELOPMENT

Grid Spacing: 500.0 ft
Model A



3.5 MW PV Farm
Yellow Jacket PV Farm

June 1, 2011 1002

Advanced Grounding Concepts / WinIGS-Q

Scale (feet)
0' 10' 20' 30'

Single Line Diagram - Case: BUCKMAN-DEVELOPMENT



GEN BUCKMAN

BUCKMAN-PV

Active Layer: 0

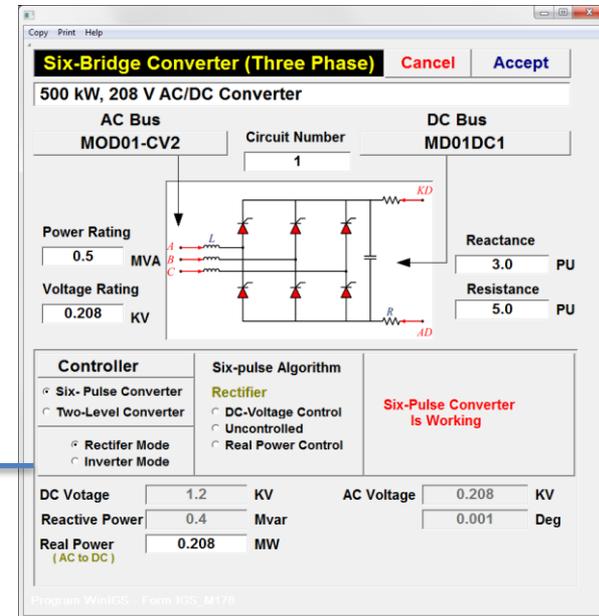
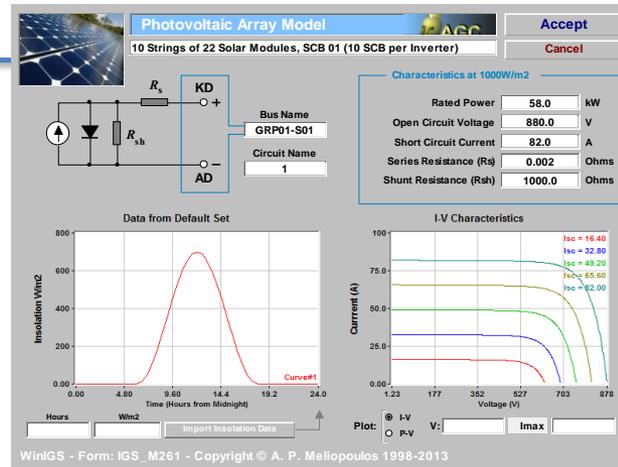
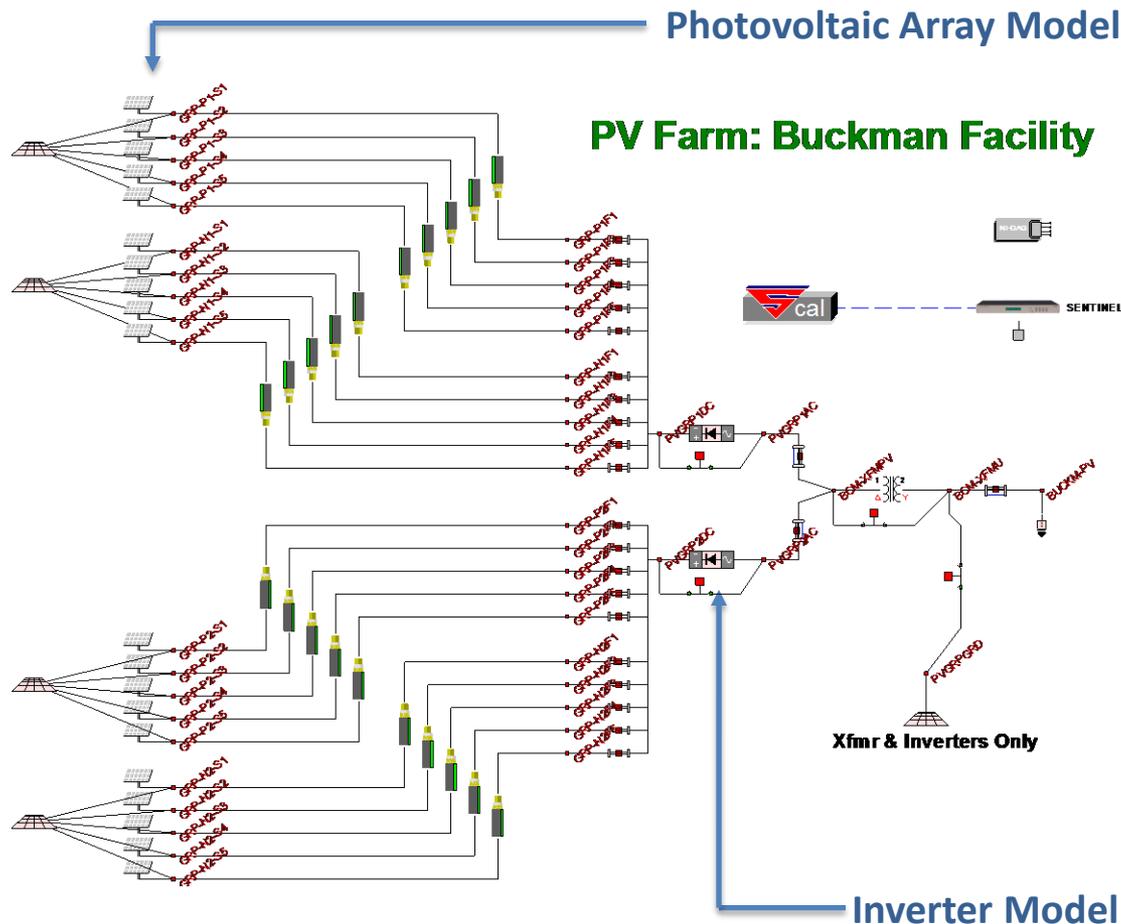
For Help, press F1

Buckman PV Array WinIGS Model

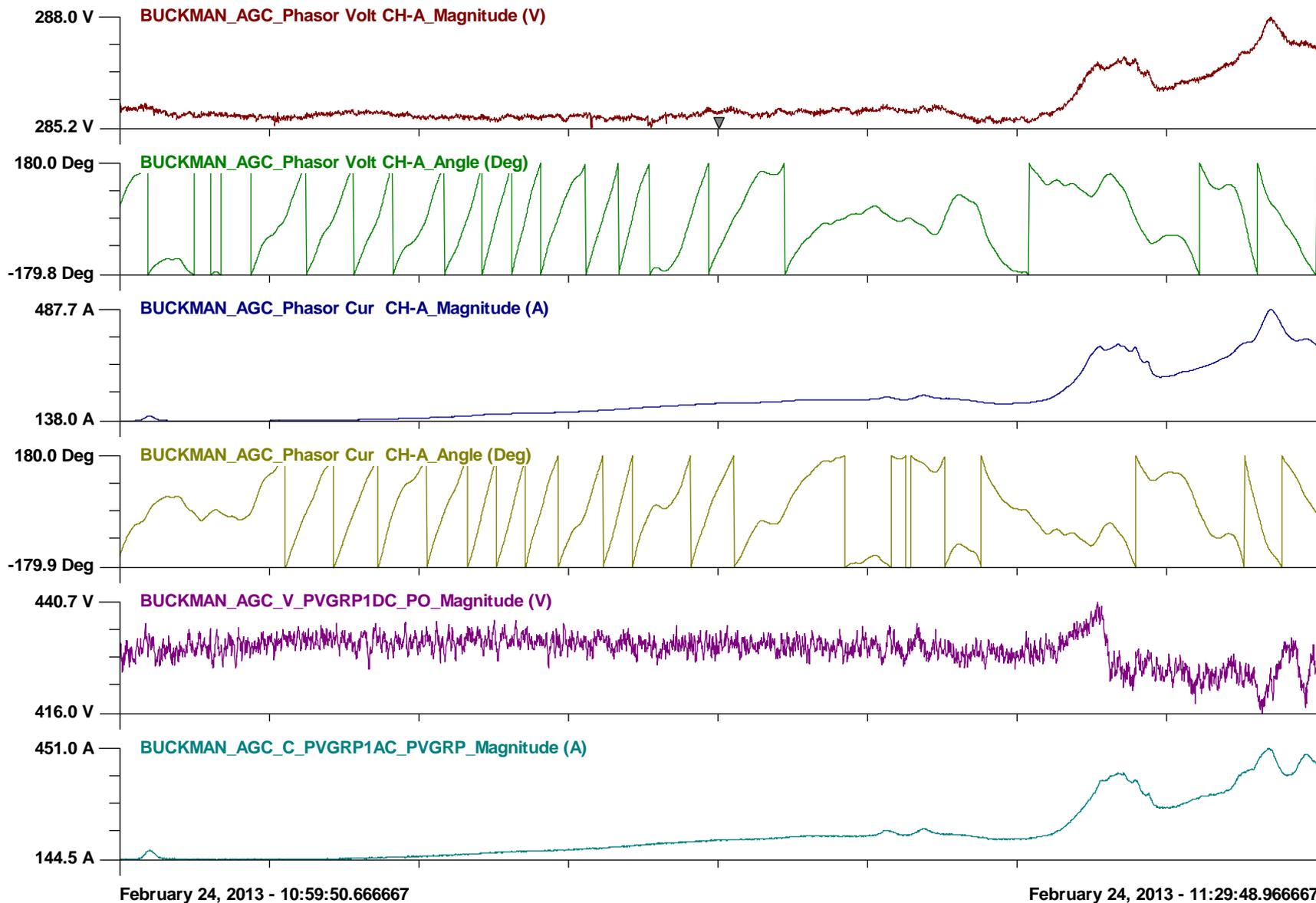


Buckman PV Array WinIGS Model

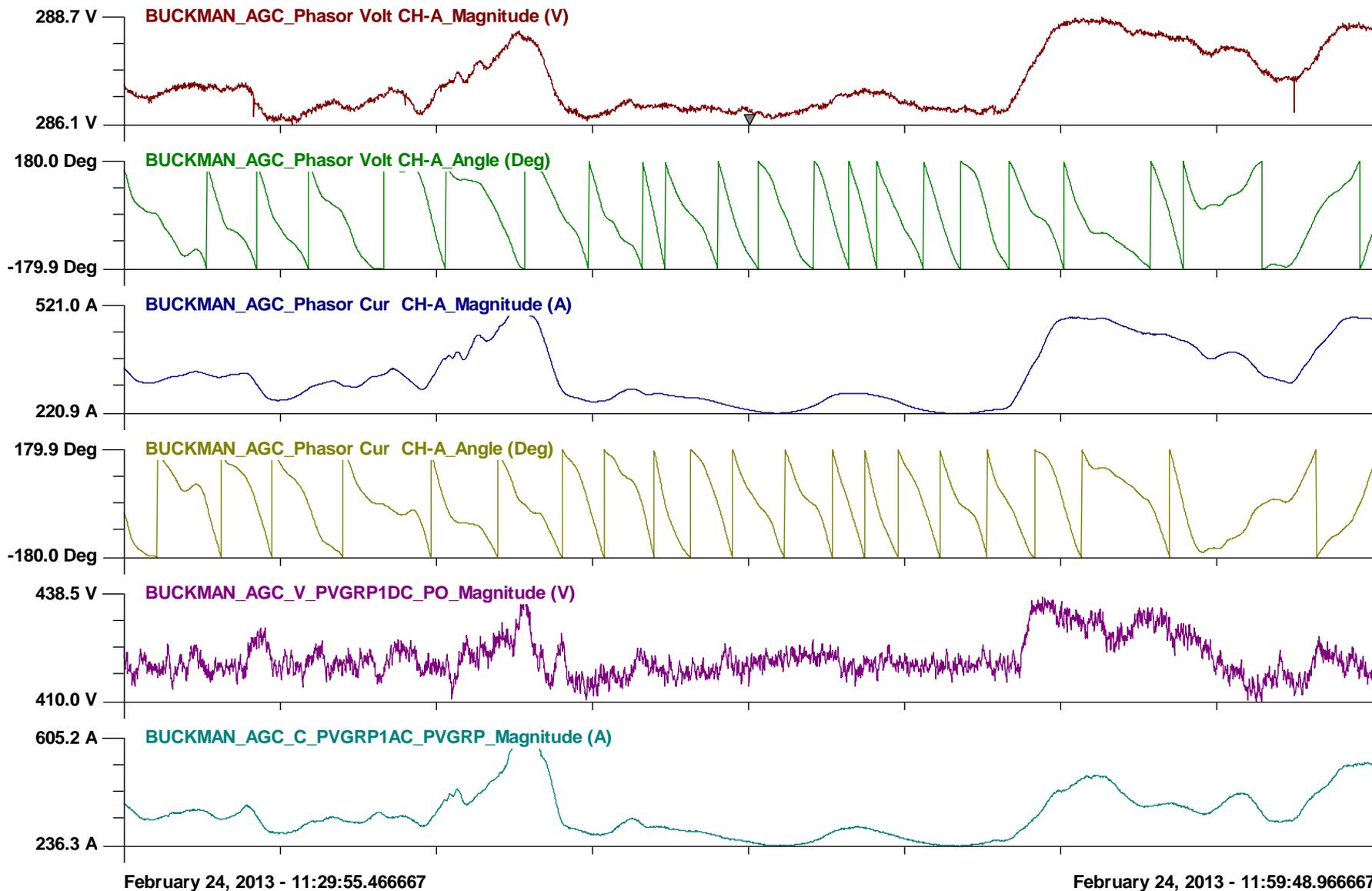
PV Module Model: PV Strings, PV String model, Converter Model



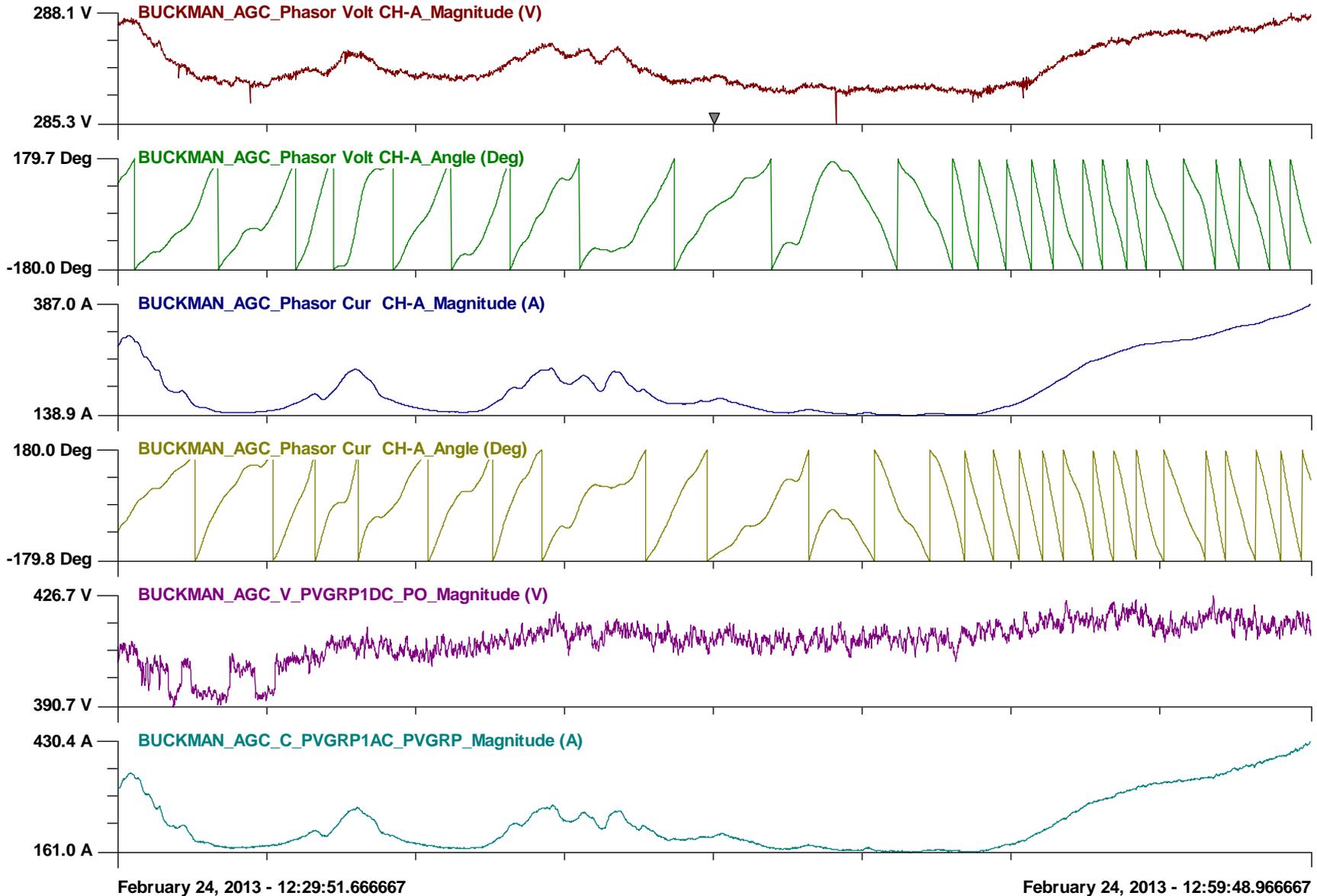
Field Data – 9:00 – 9:30 am (30 Samples / Sec)



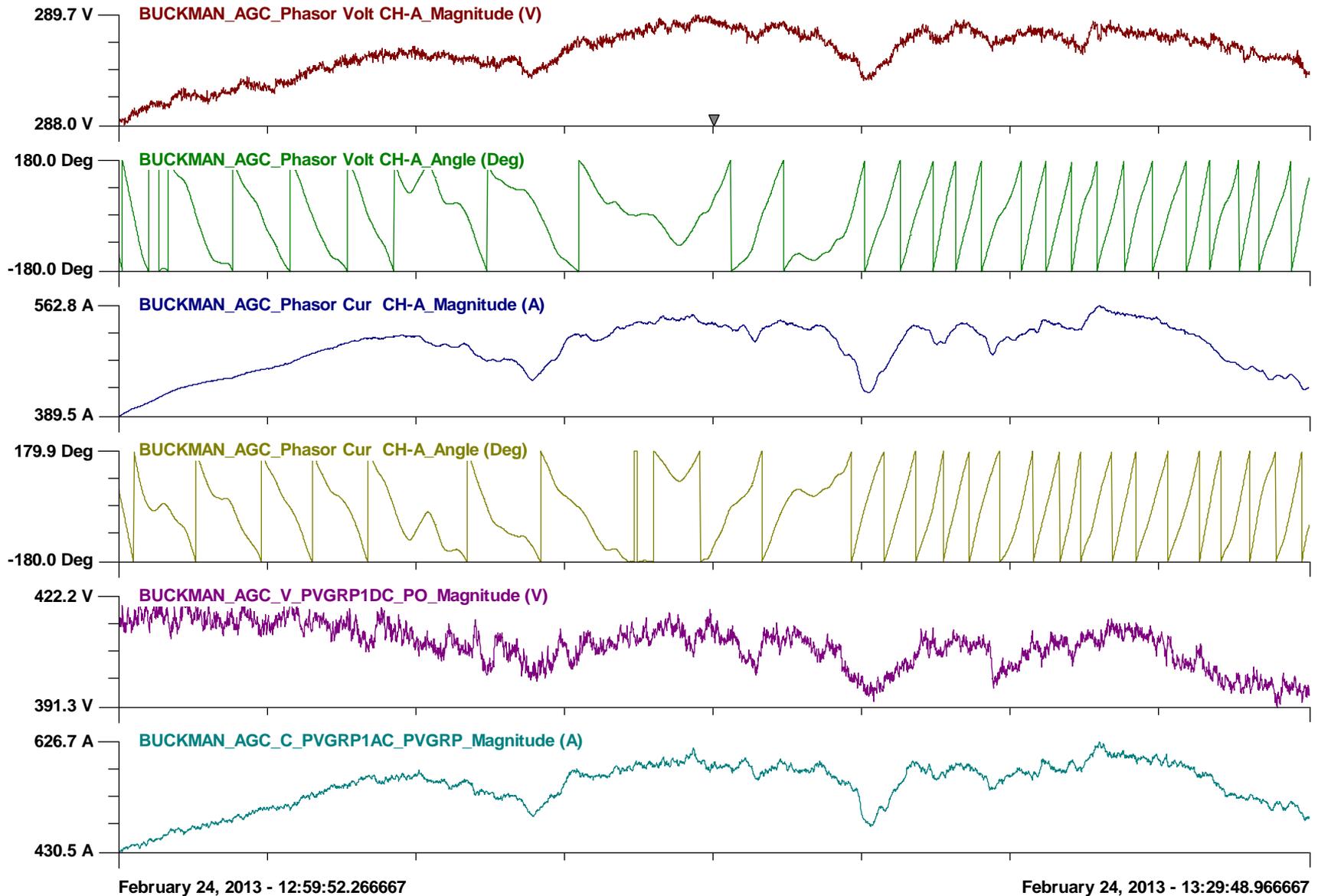
Field Data – 9:30 – 10:00 am (30 Samples / Sec)



Field Data – 10:30 – 11:00 am (30 Samples / Sec)



Field Data – 11:00 – 11:30 am (30 Samples / Sec)



Synchrophasor Field Data Snapshot

Cal SuperCalibrator - PDC Link

Substation: YJC_BUCKM

Communication Parameters

Rescan Local IP Address: 192.168.0.102 Local Port Number: 2000 Outstation IP Address: 192.168.0.102 Outstation Port Number: 2003 Outstation ID: 10

Connect Start Disconnect Stop Frame Window Copy CFG Set Rate 60 Buffer Usage 0.00 %

Protocol: TCP UDP-1 UDP-2 TCP/UDP

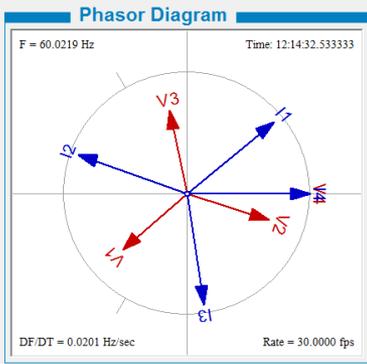
Autostart Adjust Clock

Save Stream to File: buckman

CON LOG XMIT REC

Already Disconnected
Connecting...
Socket Not Connected
Connection refused
TCP Socket Closed
Connecting...
TCP Connected
Requesting Configuration From
Requesting Configuration From
Received Configuration From
Received Configuration From

Program WinIGS-Q - Form IGS_M0



Phasors

	Name	Type	Magnitude	Phase (Degrees)
0	Phasor Volt CH-A	Voltage	288.8389	123.4191
1	Phasor Cur CH-A	Current	435.2258	-58.5011
2	Phasor Volt CH-C	Voltage	289.0181	-116.4568
3	Phasor Cur CH-C	Current	444.2625	62.1891
4	Phasor Volt CH-B	Voltage	288.8625	3.3638
5	Phasor Cur CH-B	Current	441.4685	-179.7037
6	V_PVGRP1DC_PO	Voltage	395.0335	0.0000
7	C_PVGRP1AC_PVGRF	Current	494.9604	0.0000

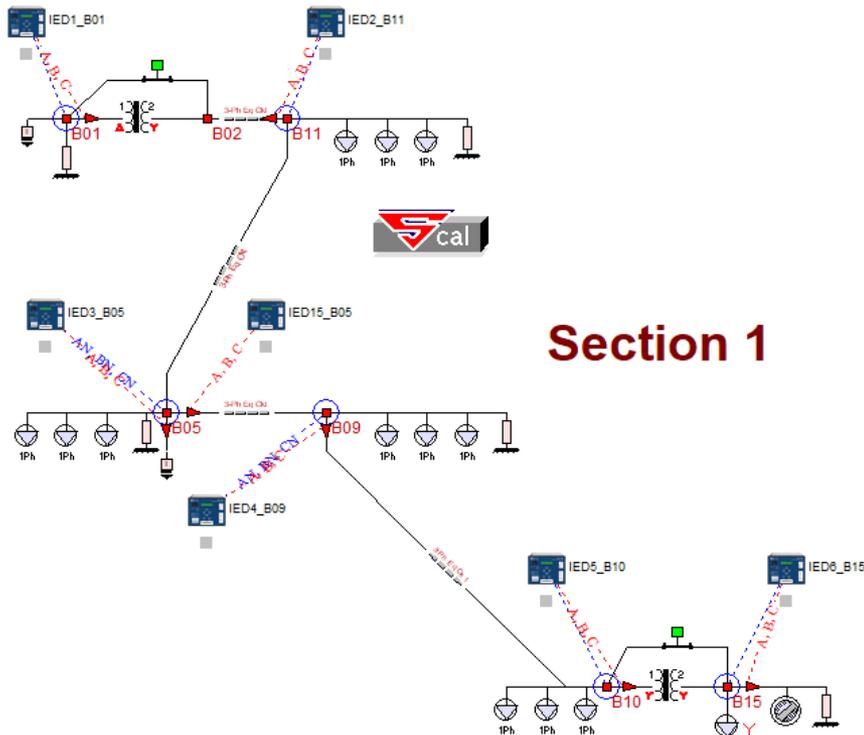
Program WinIGS-Q - Form IGS_M007_DATA_WIN

Demonstration Projects

ENERGIZE Project: Voltage Regulation and Protection Assurance using DER Advanced Grid Functions (lead: SNL)



LOHO13 Feeder – Section 1



Section 1

Measurements from Section 1 (7 IEDs)

IED Name	Voltage Measurements	Current Measurements	# of Measurements
IED1_B01	AN, BN, CN at B01	A, B, C at B01, from B01 to B02 (Tran1)	6
IED2_B11	AN, BN, CN at B11	A, B, C at B11, from B11 to B02 (Line149)	6
IED3_B05	AN, BN, CN at B05	A, B, C at B05, from B05 to B06 (Line59)	6
IED4_B09	AN, BN, CN at B09	A, B, C at B09, from B09 to B10 (Line105)	6
IED5_B10	AN, BN, CN at B10	A, B, C at B10, from B10 to B15 (Tran20)	6
IED6_B15	AN, BN, CN at B15	A, B, C at B15, into the PV Source (PVSy3)	6
IED15_B05		A, B, C at B05, from B05 to B09 (Line135)	3

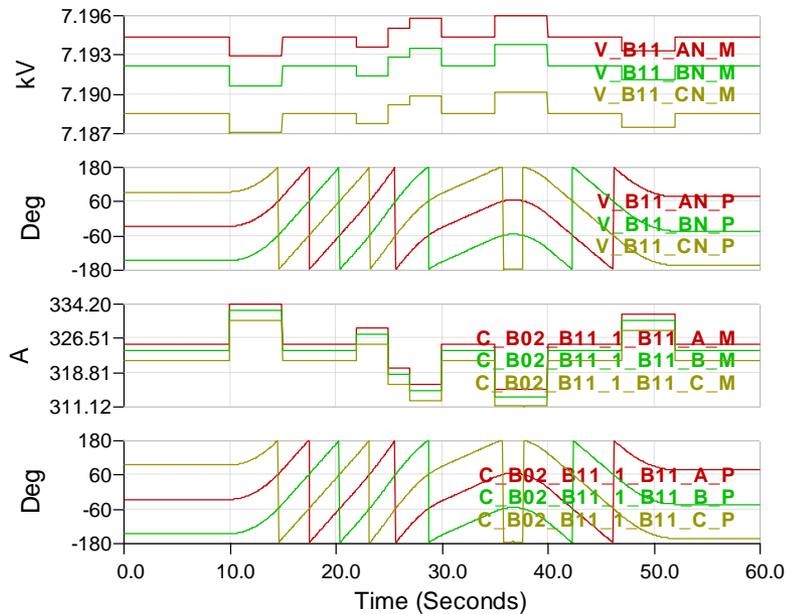
System Configuration:

- 2 three-phase two-winding XFMRs (115/12.47 kV, 12.47/0.48 kV)
- 6 three-phase distribution line segments
- 1 three-phase load (0.48 kV)
- 12 single-phase loads (feed: 7.2 kV)
- Total load consumption: 683.6 kW, 126.71 kVar
- 1 PV source (0.48 kV, 258 kW)

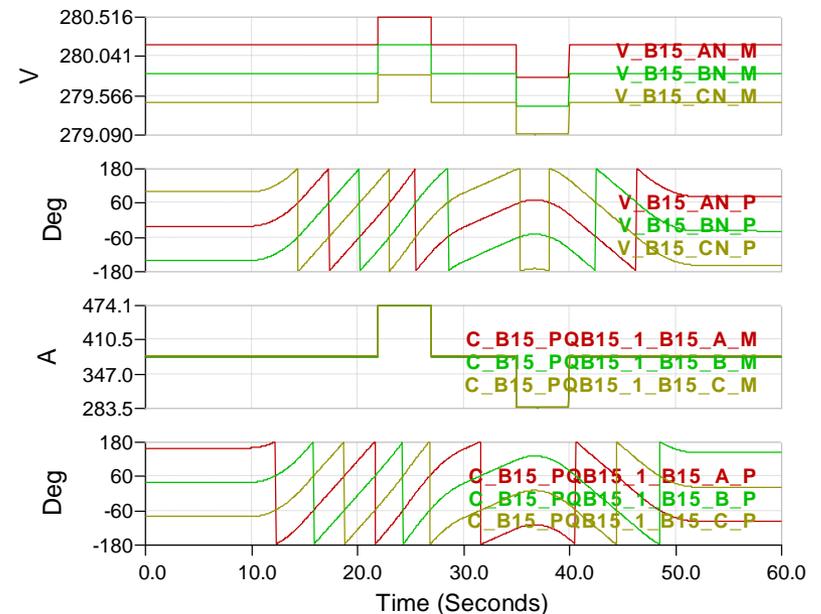
LOHO13 Feeder – Section 1

- Section 1 (7 IEDs installed)

- 18 voltage & 21 current phasor measurements, 78 actual measurements in total.
- 120 type I derived measurements, 30 type II derived measurements, 42 virtual measurements, and 14 pseudo measurements.
- States: 114, Measurements: 284, Redundancy: 249.12%.
- 60-second event, sampling rate: 60 samples/second, PV output changes during the event.



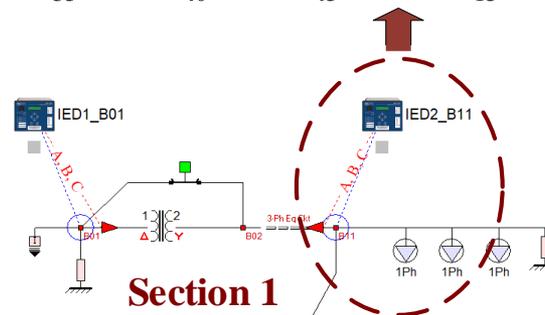
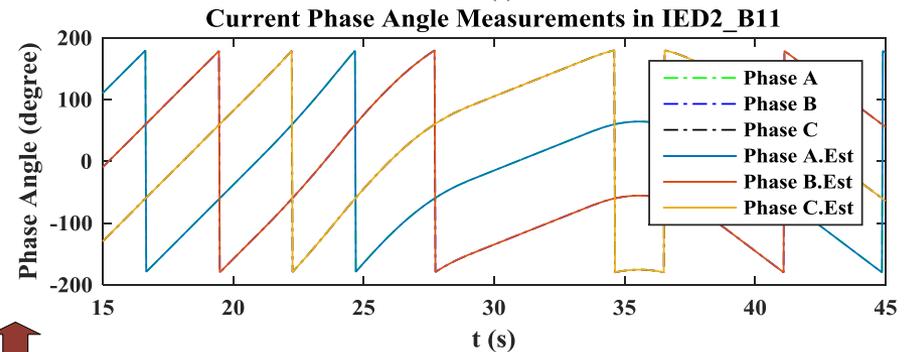
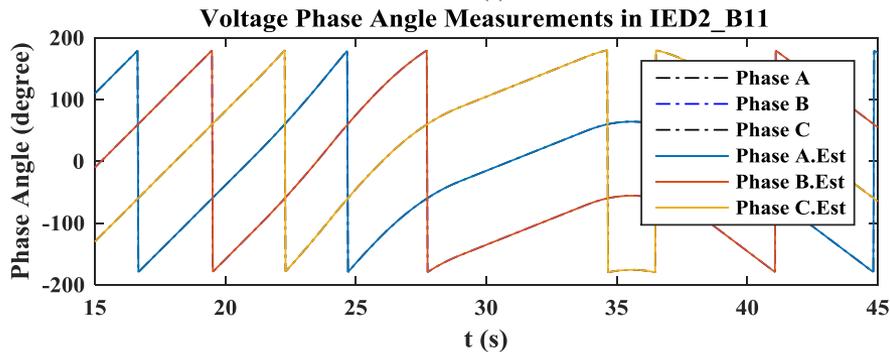
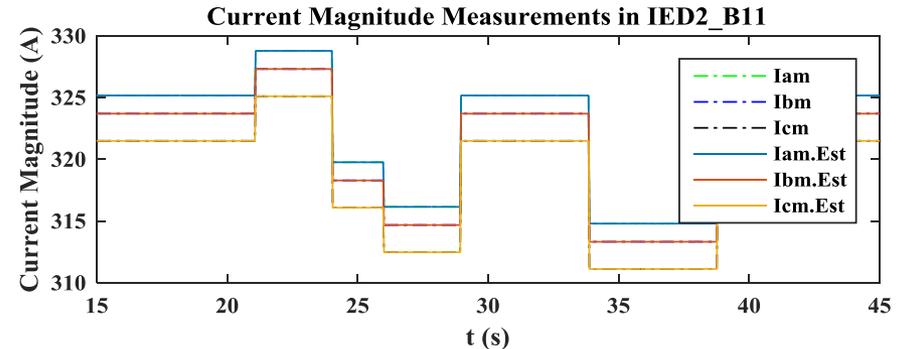
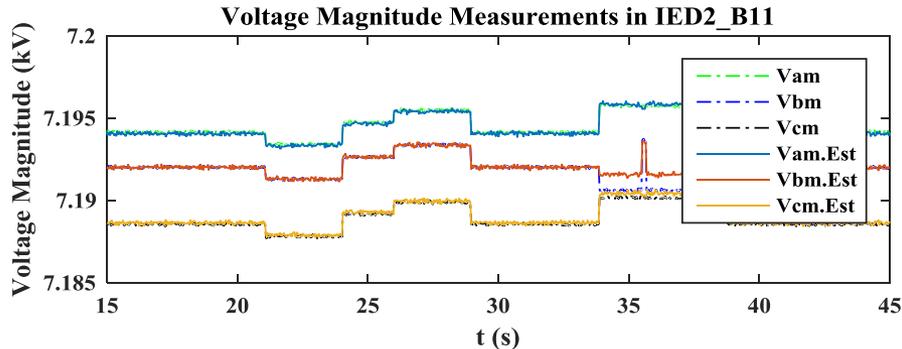
Measurements from IED2_B11 (located at bus B11)



Measurements from IED6_B15 (located at bus B15)

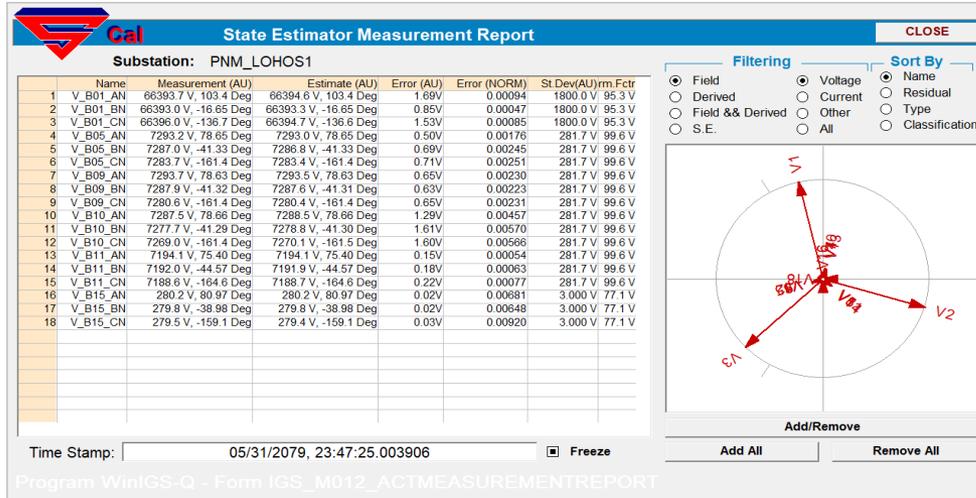
LOHO13 Feeder – Section 1

- State Estimation Results – Measurements & Estimated Measurements

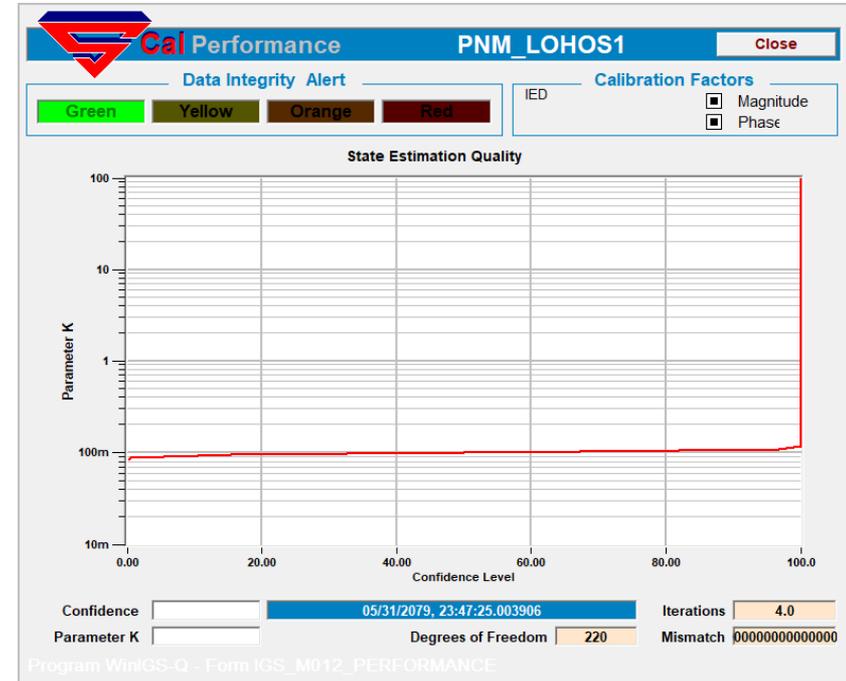


LOHO13 Feeder – Section 1

- State Estimation Results



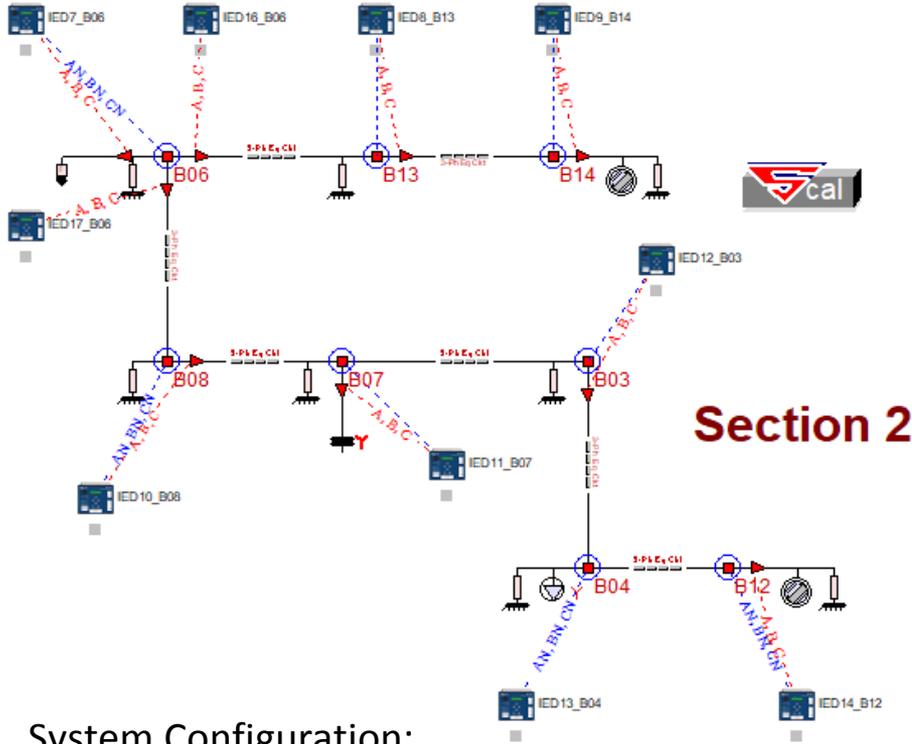
Snapshot of SE Voltage Measurement Report, Section 1



Confidence Level of Section 1

- Estimated measurements track the measurements accurately.
- All errors are small.
- Confidence level of section 1 remains at 100% → the estimated states of this section are trustworthy, the system model of this section is validated.

LOHO13 Feeder – Section 2



System Configuration:

- 8 three-phase distribution line segments
- 1 three-phase load (12.47 kV, 1885 kW, 1292 kVar)
- 1 capacitor bank (12.47 kV, 1800 kVar)
- 2 PV source
 - PV at bus B14 (12.47 kV, 1 MW)
 - PV at Bus B12 (12.47 kV, 10 MW)

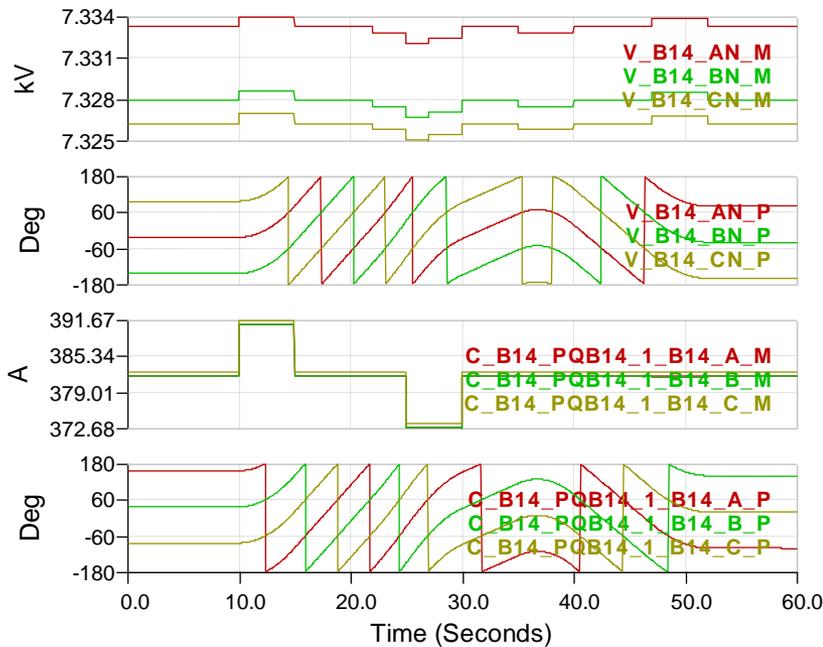
Measurement from Section 2 (10 IEDs)

IED Name	Voltage Measurements	Current Measurements	# of Measurements
IED7_B06	AN, BN, CN at B06	A, B, C at B06, from B06 to B05 (Line59)	6
IED8_B13	AN, BN, CN at B13	A, B, C at B13, from B13 to B14 (Line196)	6
IED9_B14	AN, BN, CN at B14	A, B, C at B14, into the PV Source (PVSy2)	6
IED10_B08	AN, BN, CN at B08	A, B, C at B08, from B08 to B07 (Line97)	6
IED11_B07	AN, BN, CN at B07	A, B, C at B07, into the capacitor bank (Capa1)	6
IED12_B03	AN, BN, CN at B03	A, B, C at B03, from B03 to B04 (Line4)	6
IED13_B04	AN, BN, CN at B04		3
IED14_B12	AN, BN, CN at B12	A, B, C at B12, into the PV Source (PVSy1)	6
IED16_B06		A, B, C at B06, from B06 to B13 (Line167)	3
IED17_B06		A, B, C at B06, from B06 to B08 (Line188)	3

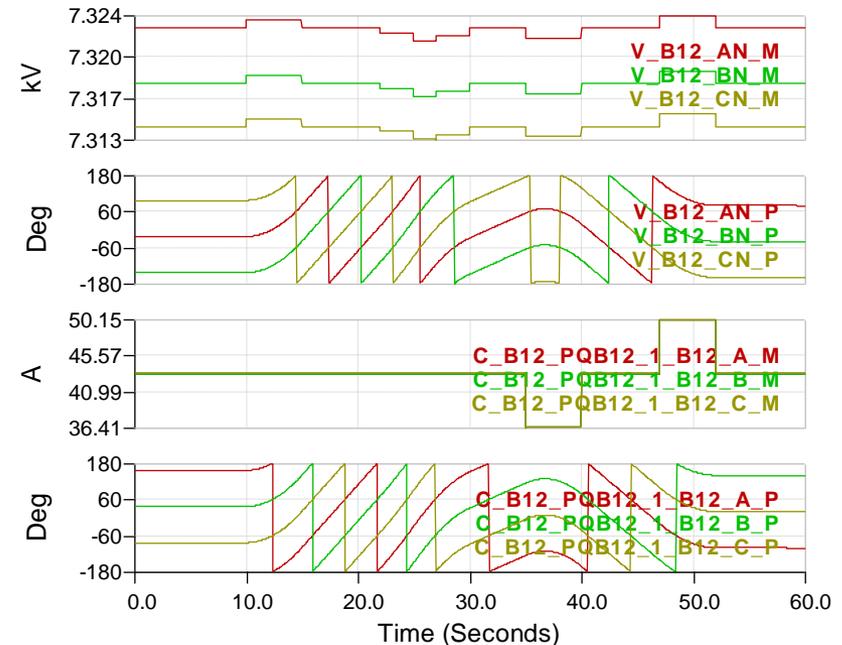
LOHO13 Feeder – Section 2

- Section 2 (10 IEDs installed)

- 24 voltage & 27 current phasor measurements, 102 actual measurements in total.
- 66 type I derived measurements, 14 type II derived measurements, 20 virtual measurements, and 16 pseudo measurements.
- States: 88, Measurements: 218, Redundancy: 247.73%.
- 60-second event, sampling rate: 60 samples/second , PV output changes during the event.



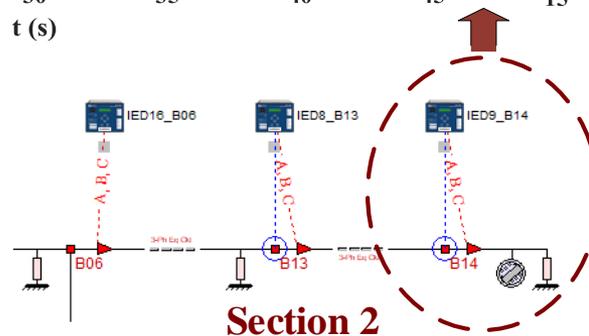
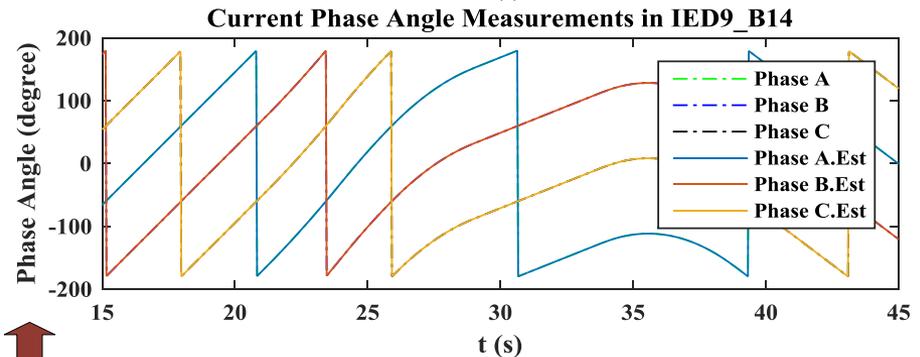
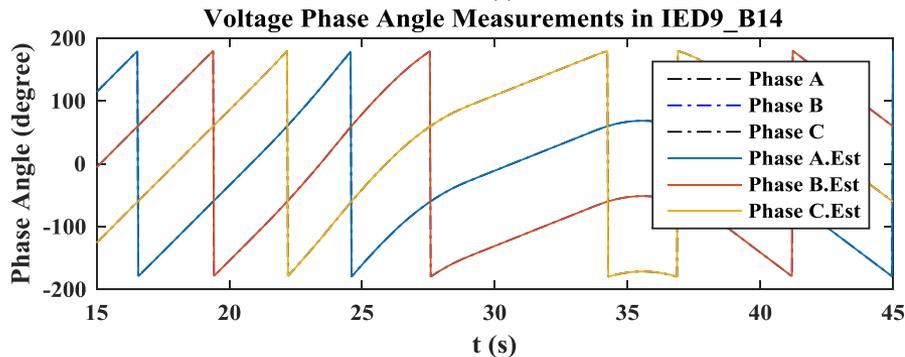
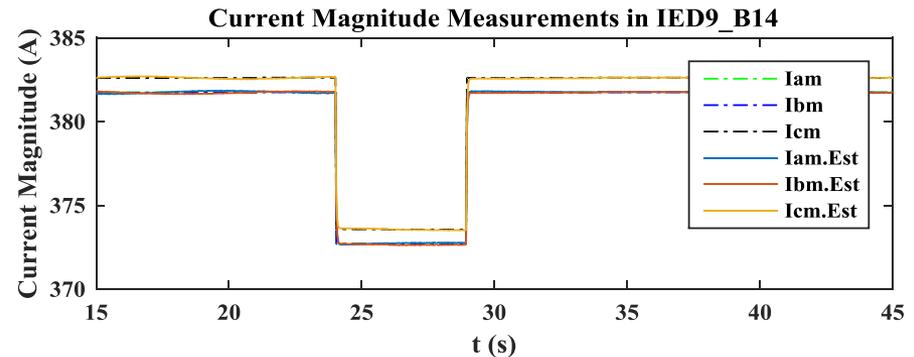
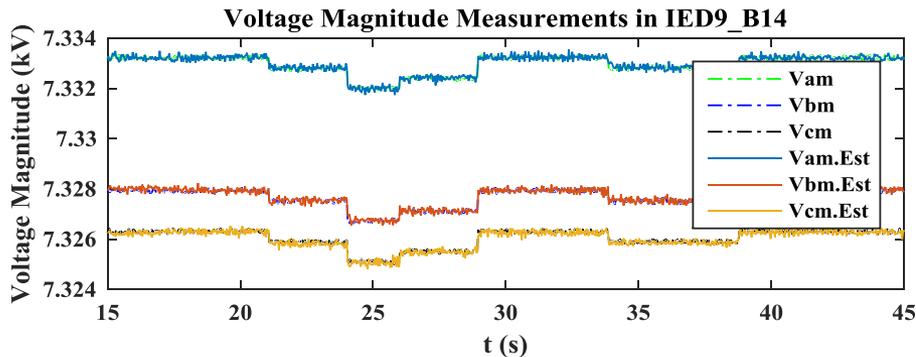
Measurements from IED9_B14 (located at bus B14)



Measurements from IED14_B12 (located at bus B12)

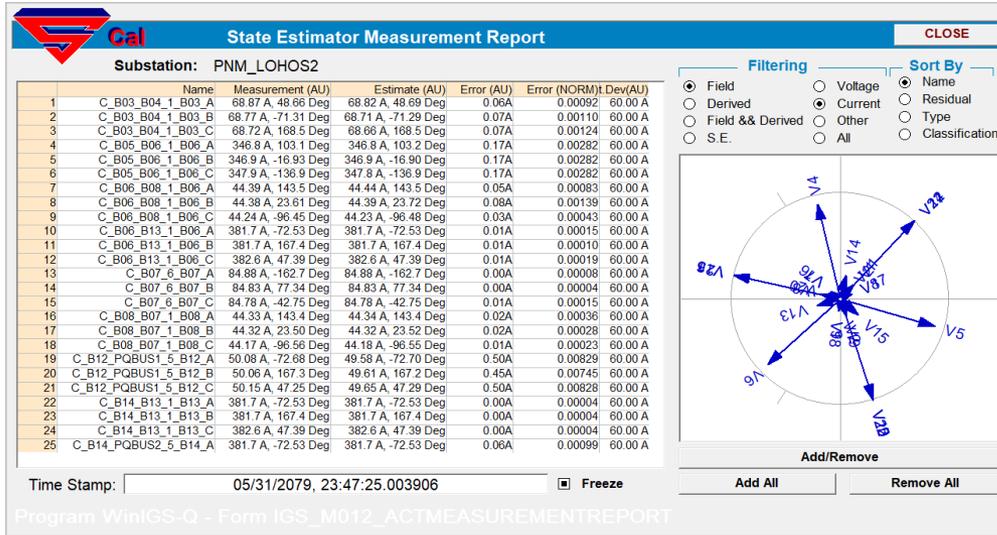
LOHO13 Feeder – Section 2

- State Estimation Results – Measurements & Estimated Measurements



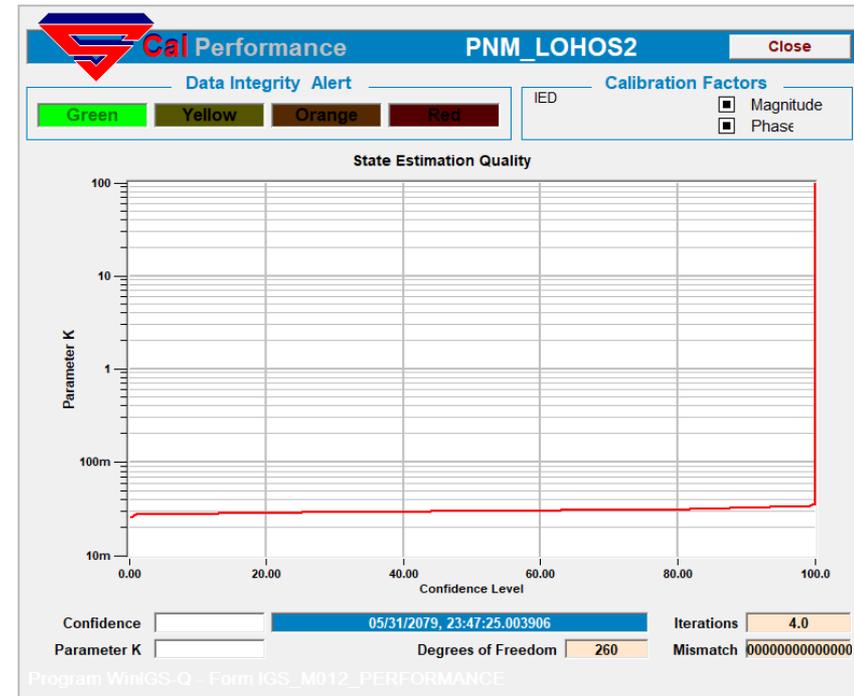
LOHO13 Feeder – Section 2

- State Estimation Results



Snapshot of SE Current Measurement Report, Section 2

- Estimated measurements track the measurements accurately.
- All errors are small.
- Confidence level of section 2 remains at 100% → the estimated states of this section are trustworthy, the system model of this section is validated.



Confidence Level of Section 2

Conclusions: Technology Capabilities

An Object Oriented Implementation of a Distribution System State Estimation Enables Full Observability of the Distribution System and Customer Owned Resources. State Estimation enables: (a) validation of data, and (b) extent the observability of the distribution system beyond the existing instrumentation. The DS-SE enables many applications:

Utility

- Optimize voltage along feeder by
 - cap control
 - distributed resource control, etc.

Customer/Third Party Resources

- Example: PV Model Validation
- Identify Panel Deterioration, Faulty Panels, etc.
- Determine root cause of disturbances

Questions?

