

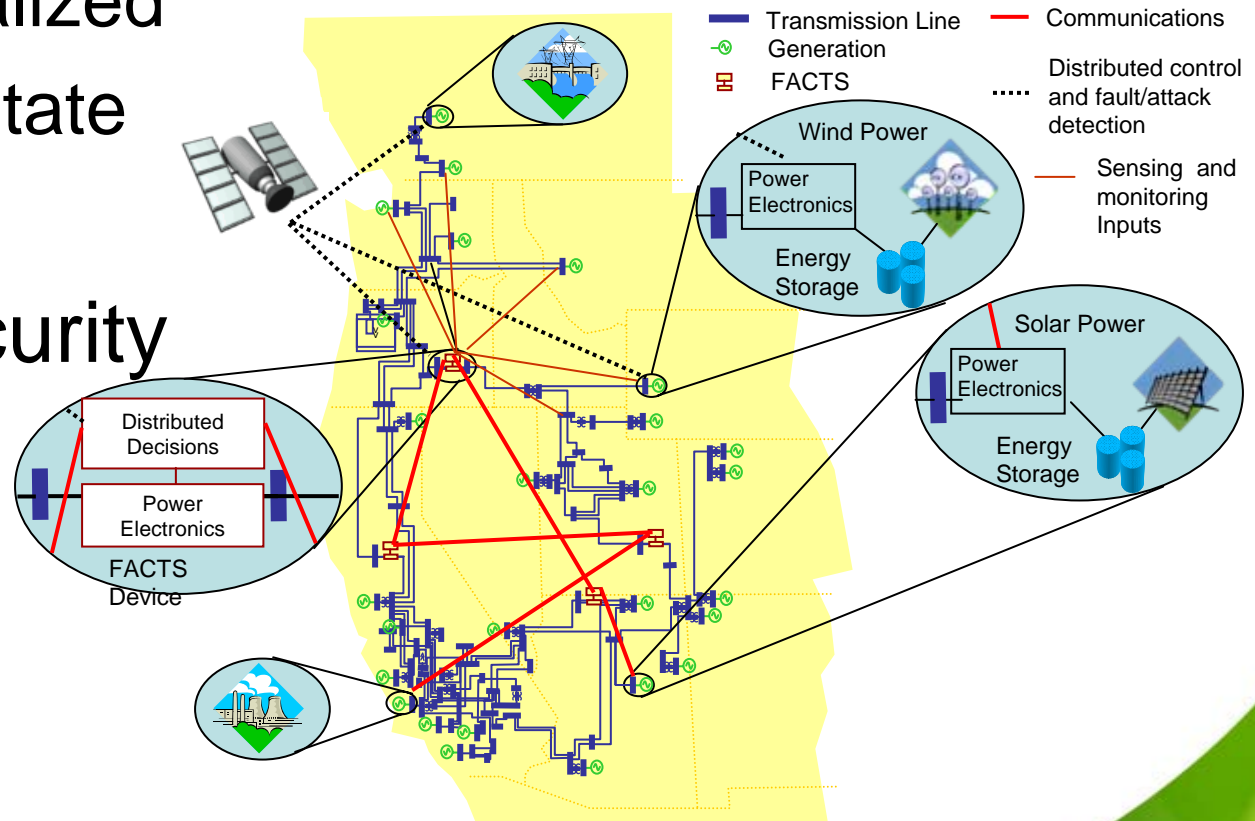
Cyber-Physical Systems Distributed Control: The Advanced Electric Power Grid

Mariesa Crow
University of Missouri-Rolla

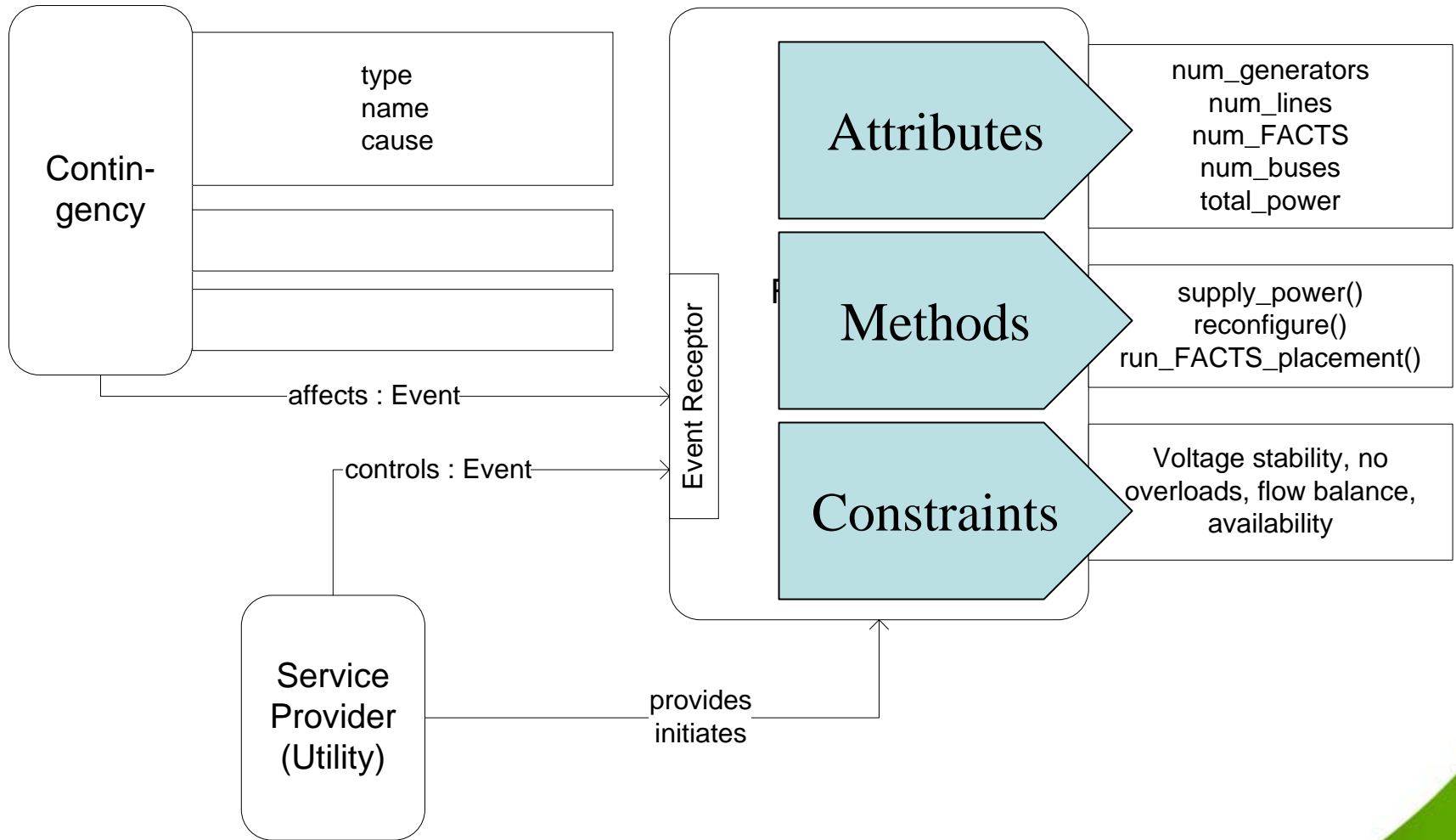
Funded by the Energy Storage Systems Program of the U.S. Department Of Energy
(DOE/ESS) through Sandia National Laboratories (SNL).

Issues

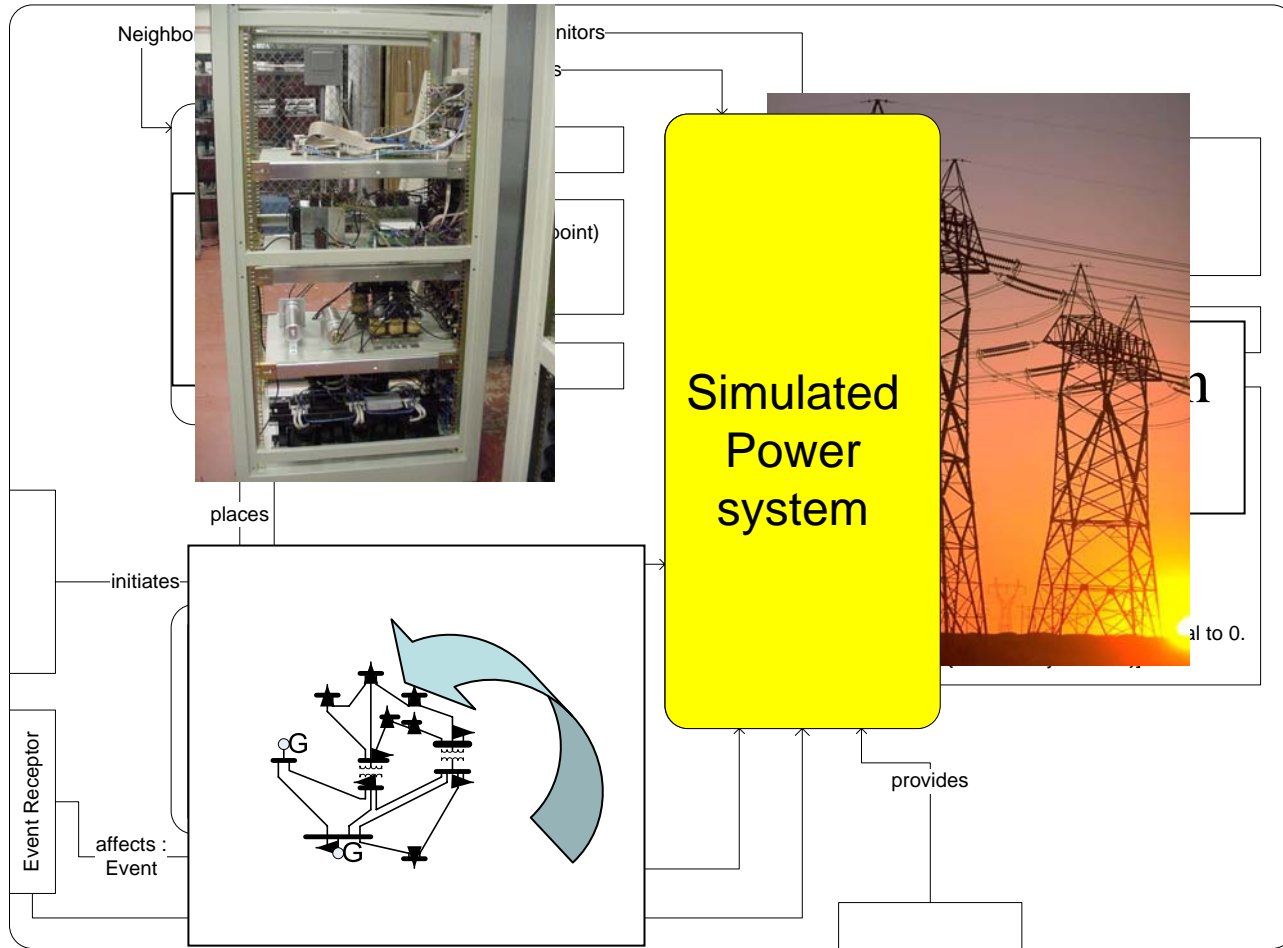
- Hardware-software co-design
- Device placement and control
 - Decentralized
 - Steady-state
 - Dynamic
- Cyber security
- Reliability



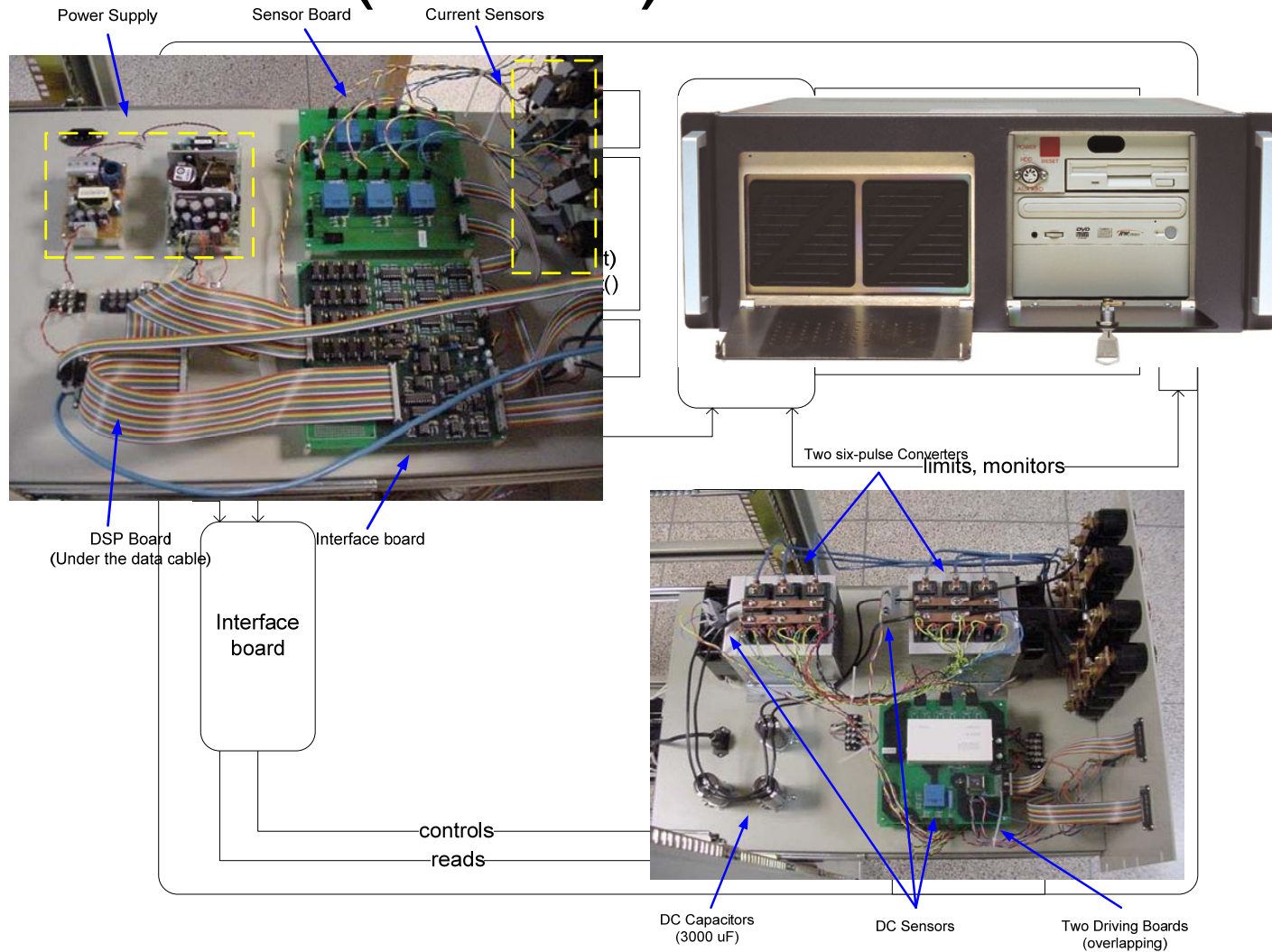
FACTS Power System Model



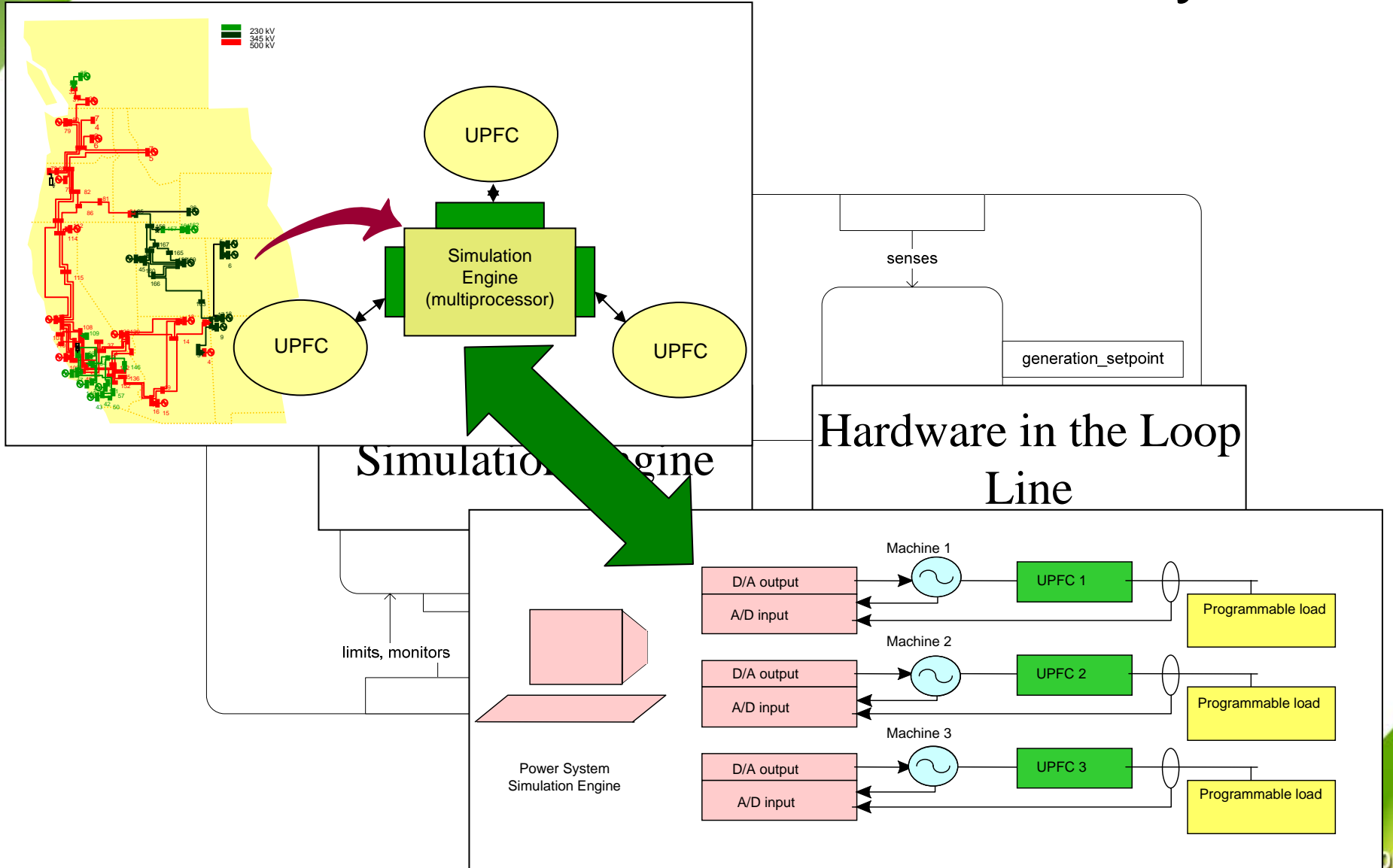
First Decomposition



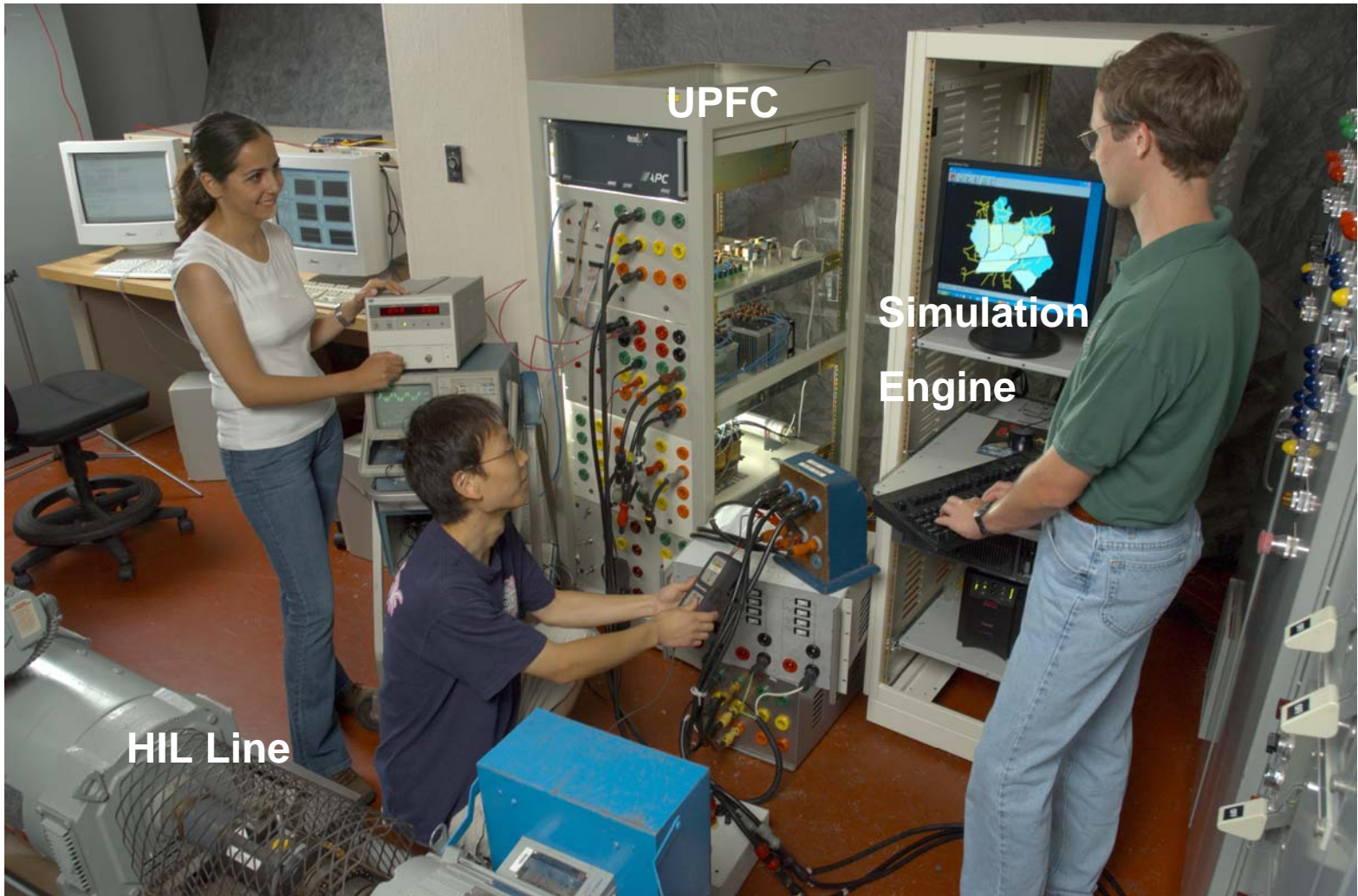
Unified Power Flow Controller (UPFC) FACTS



Simulated Power Transmission System



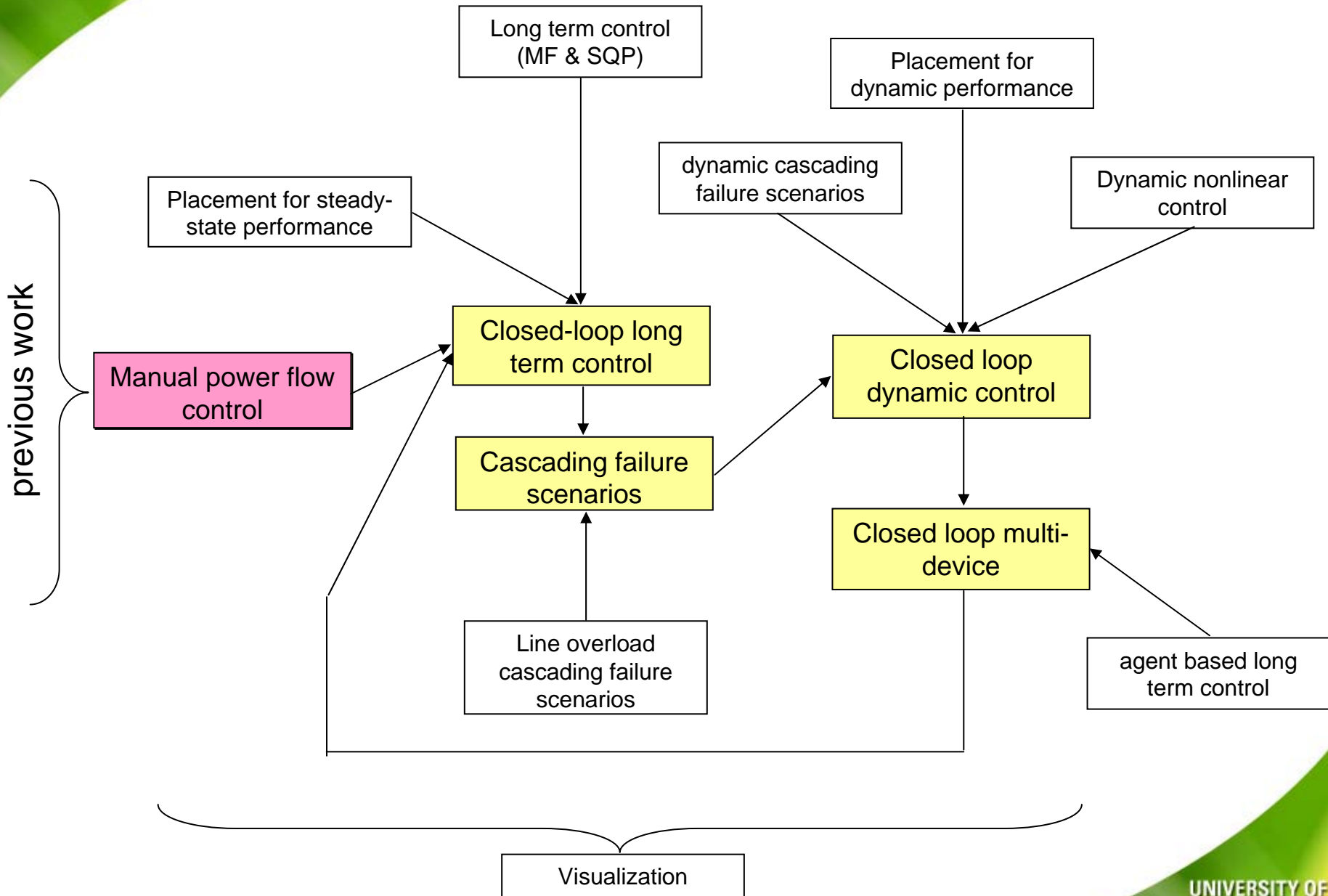
FACTS Interaction Laboratory



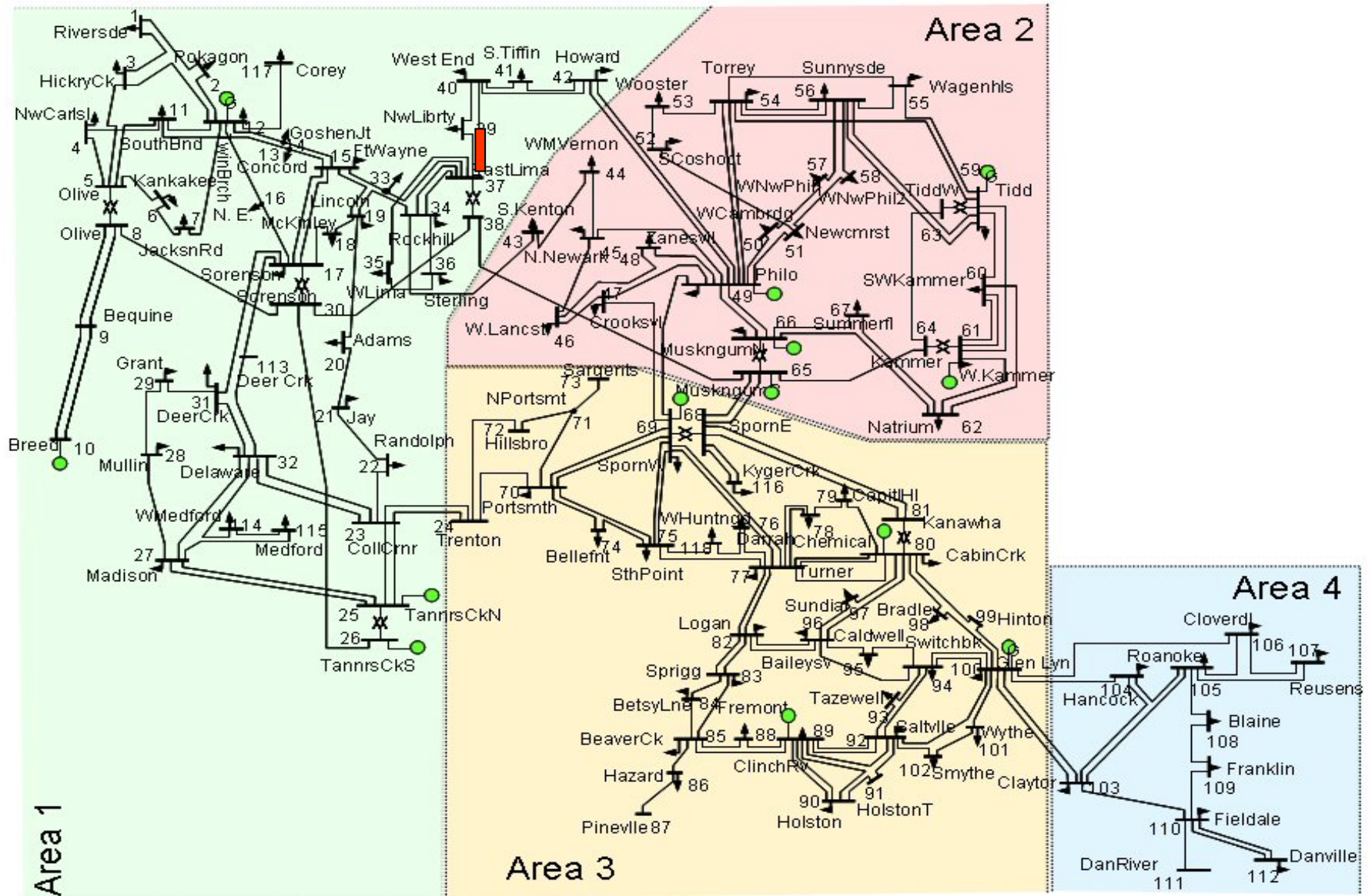
UPFC

Simulation
Engine

HIL Line



IEEE 118 Bus Test System



Area 1

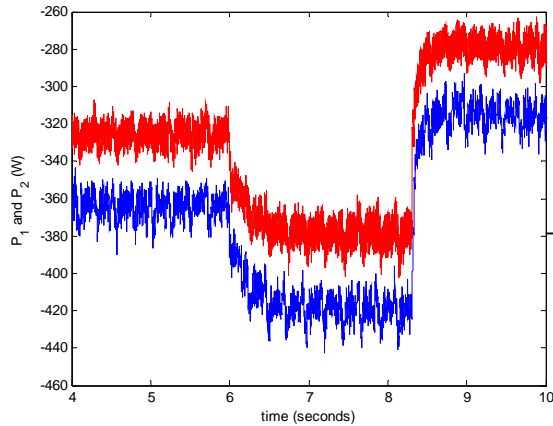
Area 2

Area 3

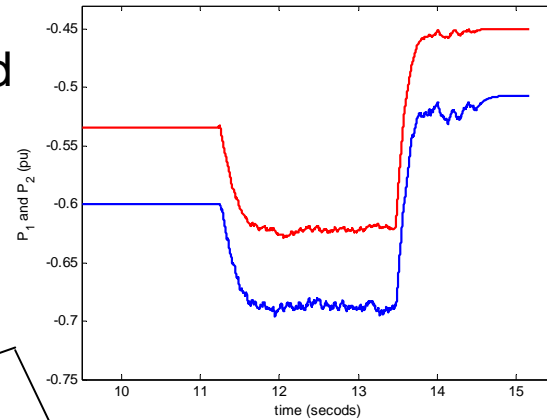
Area 4

Manual Power Flow Control

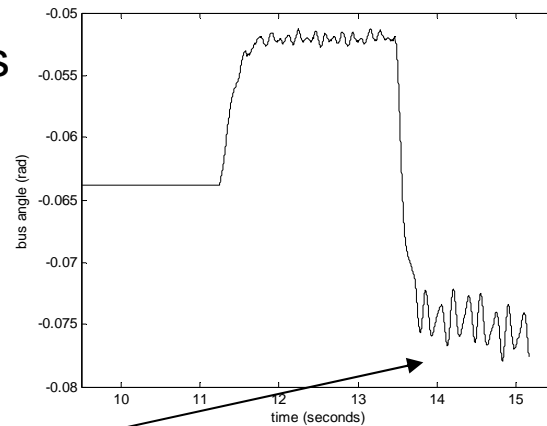
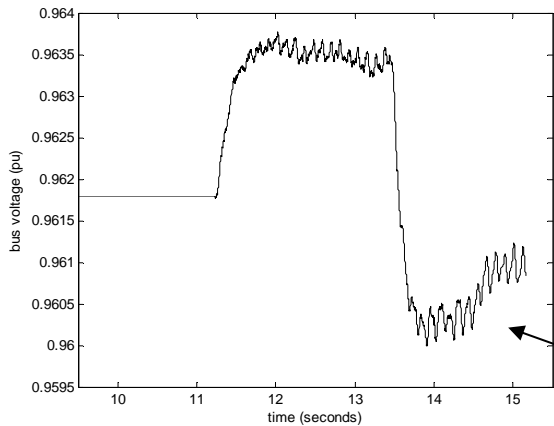
actual UPFC power flows



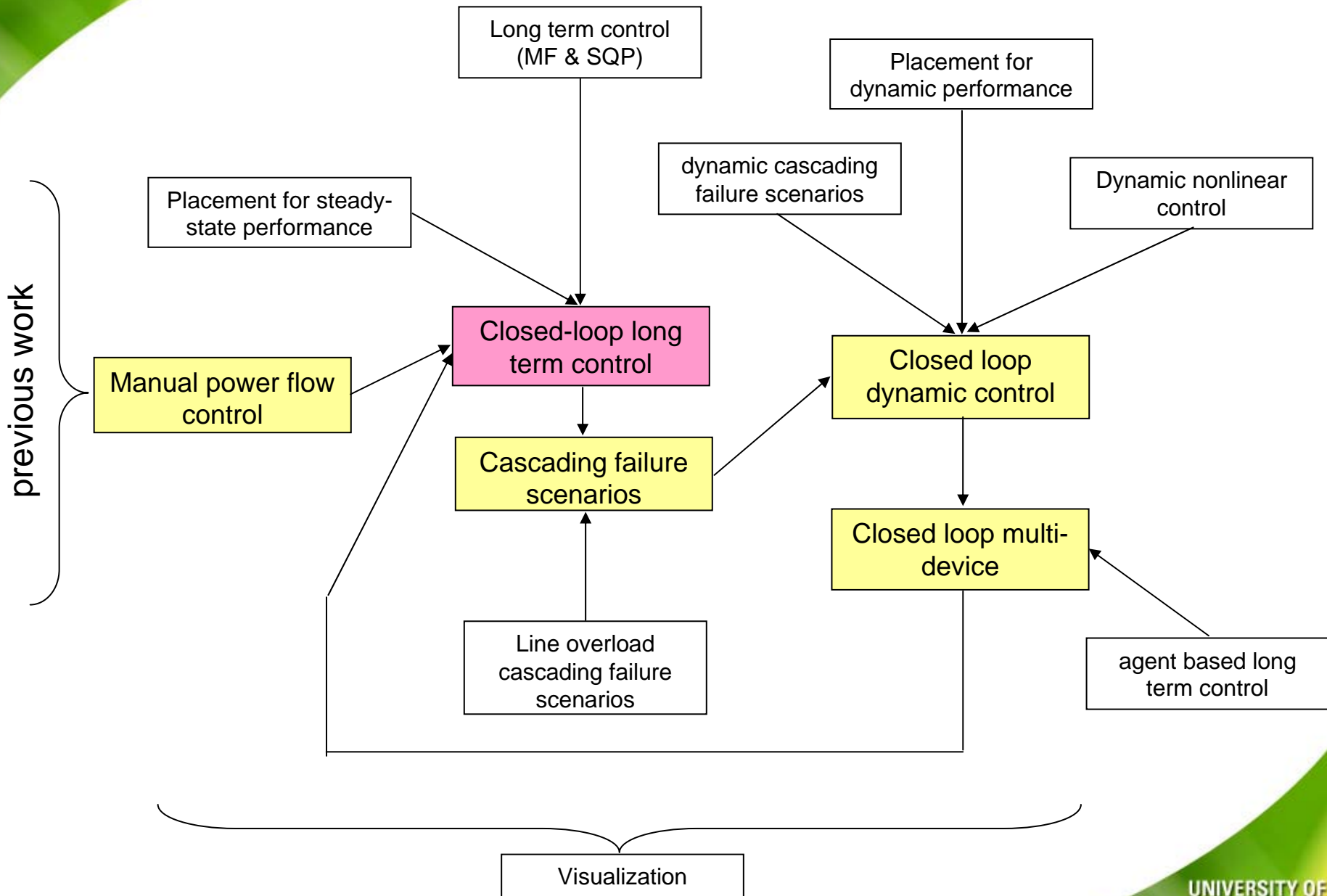
measured and filtered into simulation



simulated bus voltages & angles

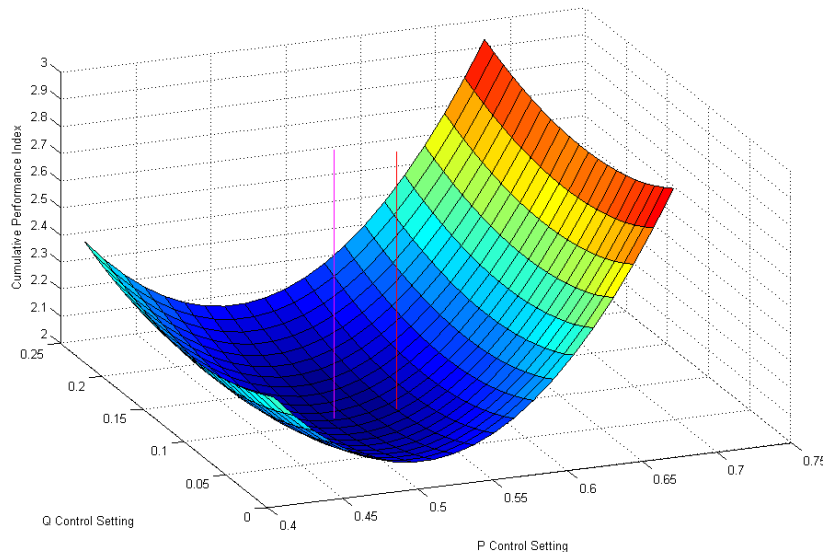


Note induced low frequency oscillations



Closed-loop long term control

- Which setting yield the lowest PI over all possible contingencies?



Minimize

$$PI_{cum} = \sum_{all\ lines} \left(\frac{S_{ij}}{S_{ij}^{max}} \right)^2 + W_V \sum_{i=1}^N \left(\frac{V_i - V_i^{ss}}{\Delta V_i^{lim}} \right)^2$$

Subject to:

Equality constraints:

$$0 = \Delta P_i - \sum_{j=1}^N V_i V_j Y_{ij} \cos(\theta_i - \theta_j - \phi_{ij})$$

$$0 = \Delta Q_i - \sum_{j=1}^N V_i V_j Y_{ij} \sin(\theta_i - \theta_j - \phi_{ij})$$

for $i=1, \dots, N$ and $j=1, \dots, N$

Inequality constraints:

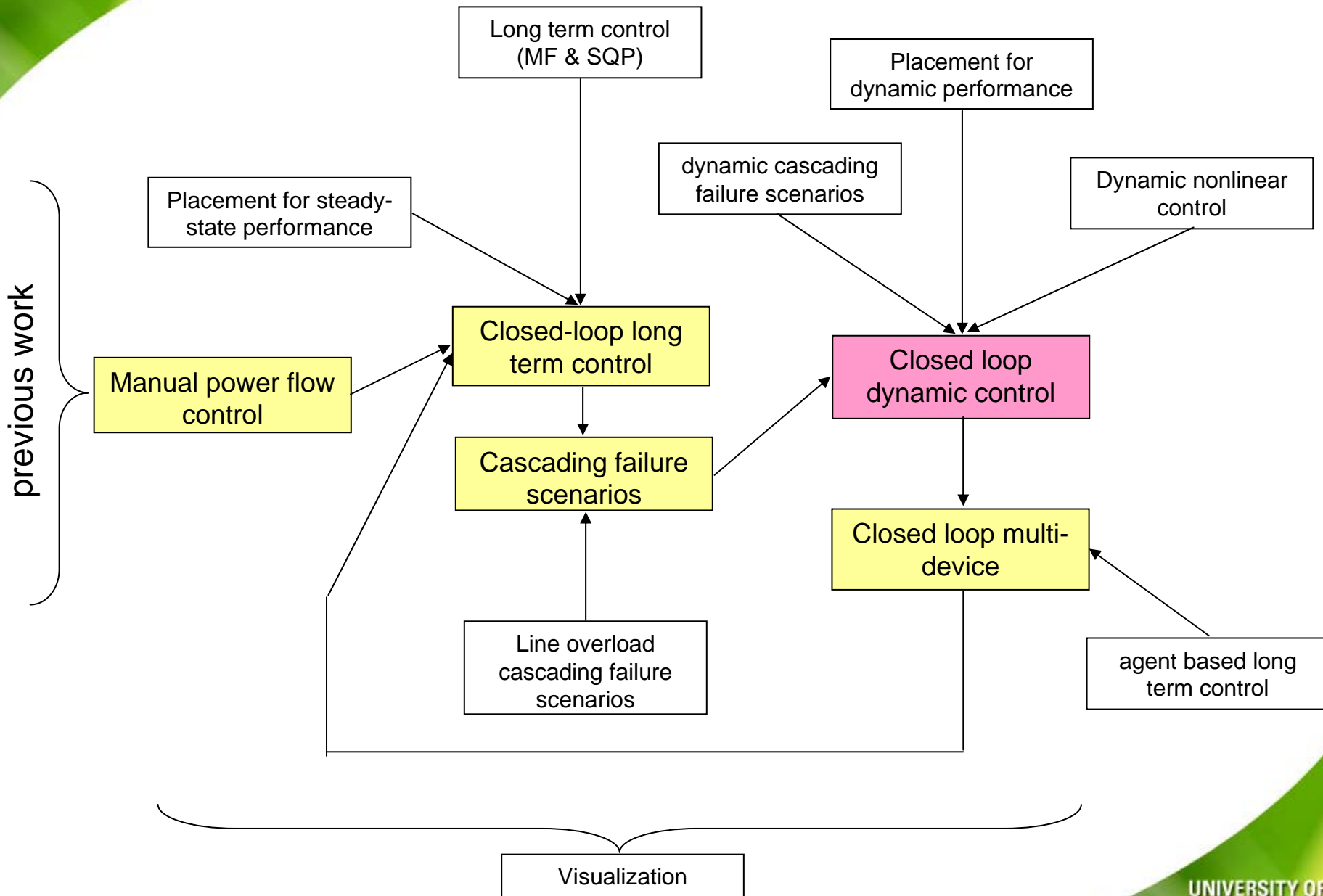
$$P_i^{min} \leq P_i \leq P_i^{max}$$

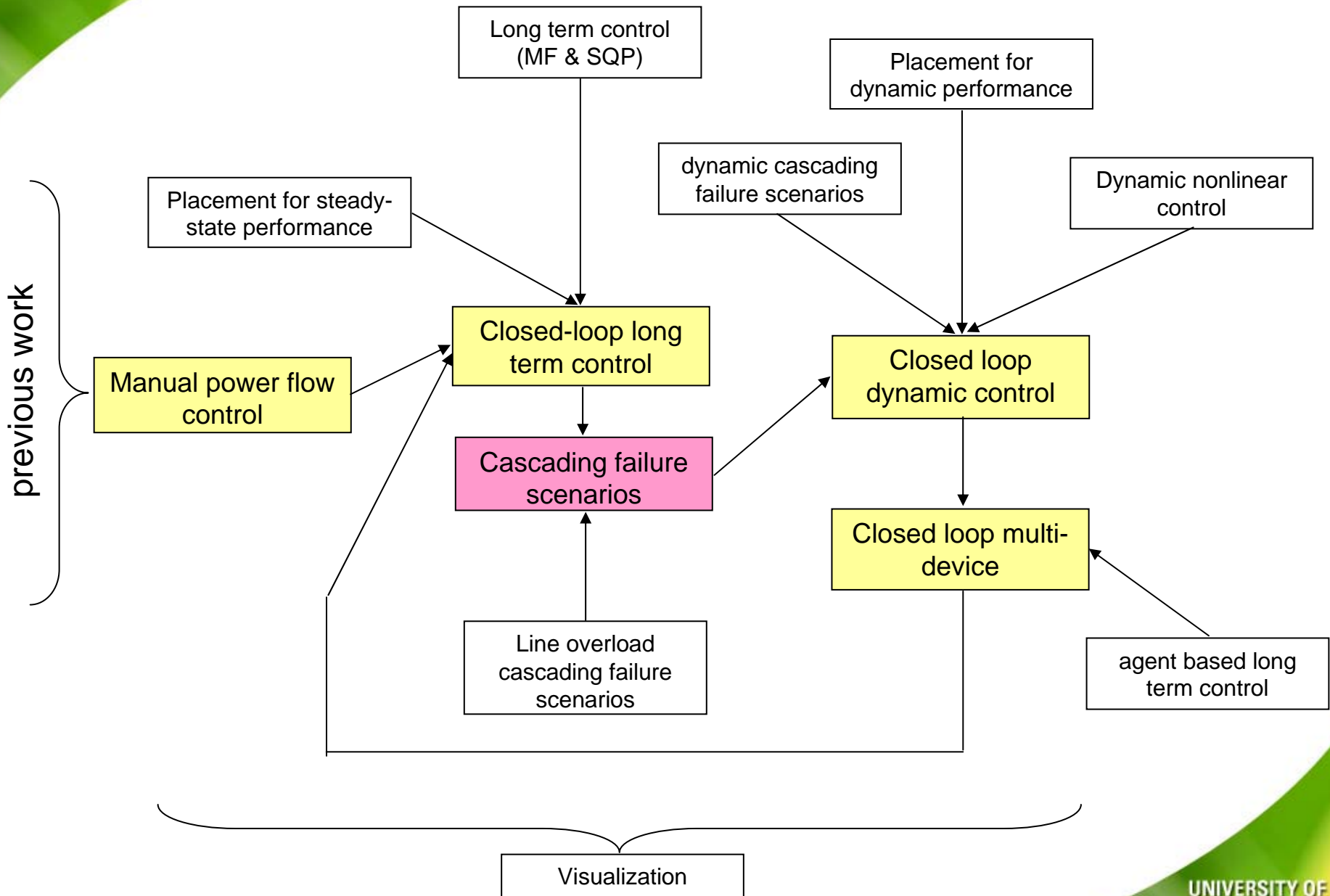
$$Q_i^{min} \leq Q_i \leq Q_i^{max}$$

$$V_i^{min} \leq V_i \leq V_i^{max}$$

UPFC Constraints:

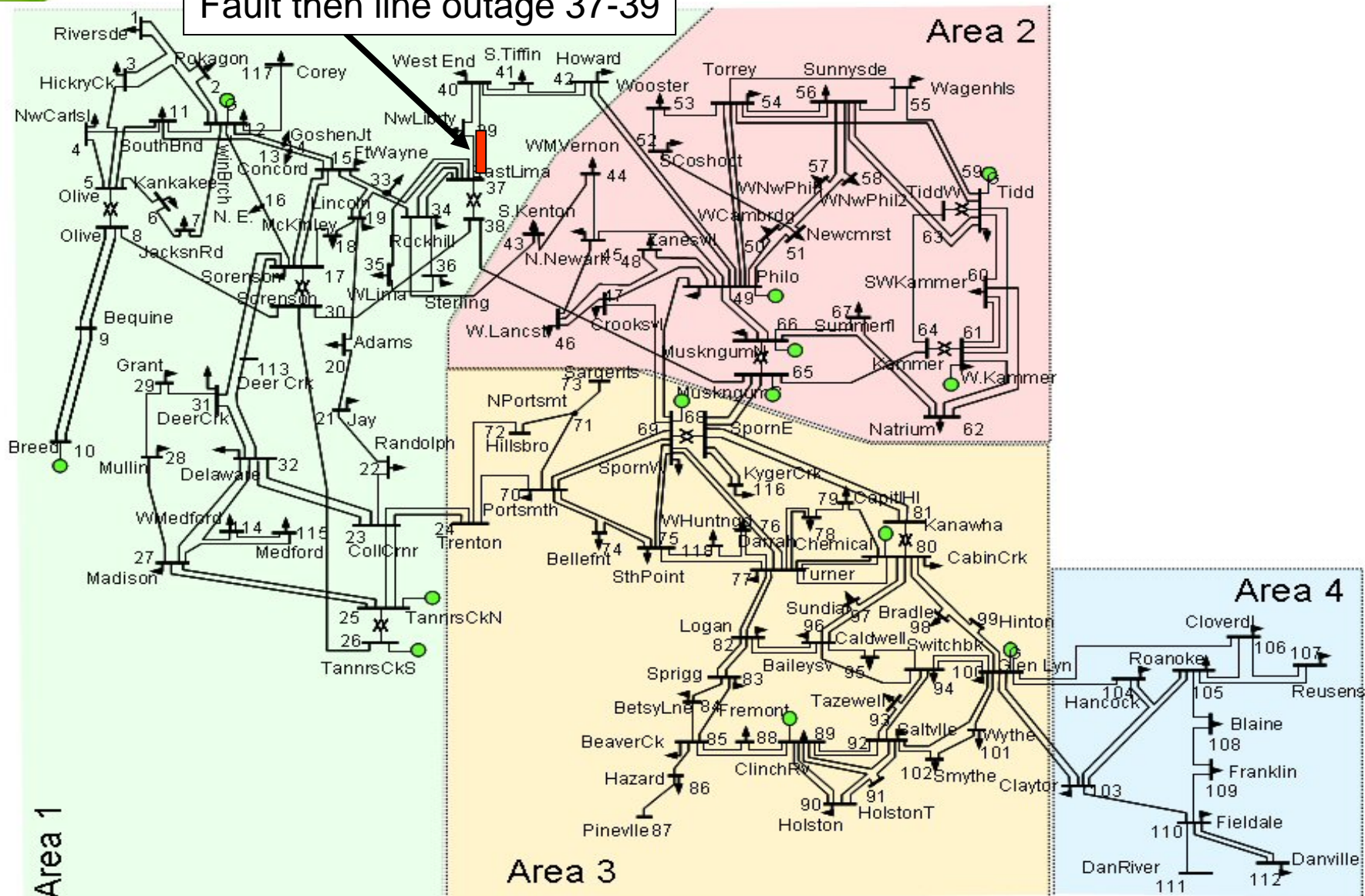
$$\sqrt{P_{SET}^2 + Q_{SET}^2} \leq S_{ij}^{max}$$



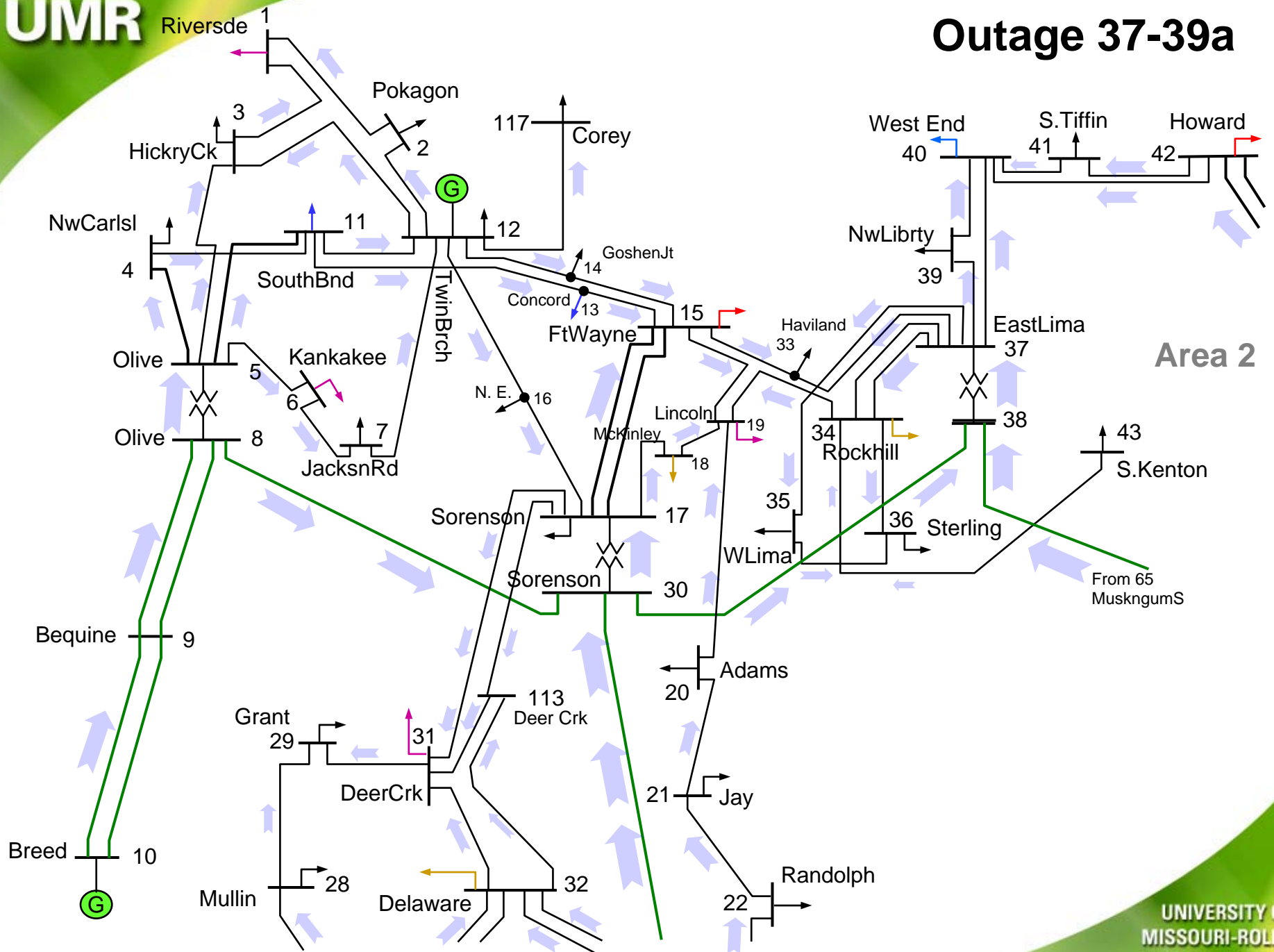


IEEE 118 Bus Test System

Fault then line outage 37-39

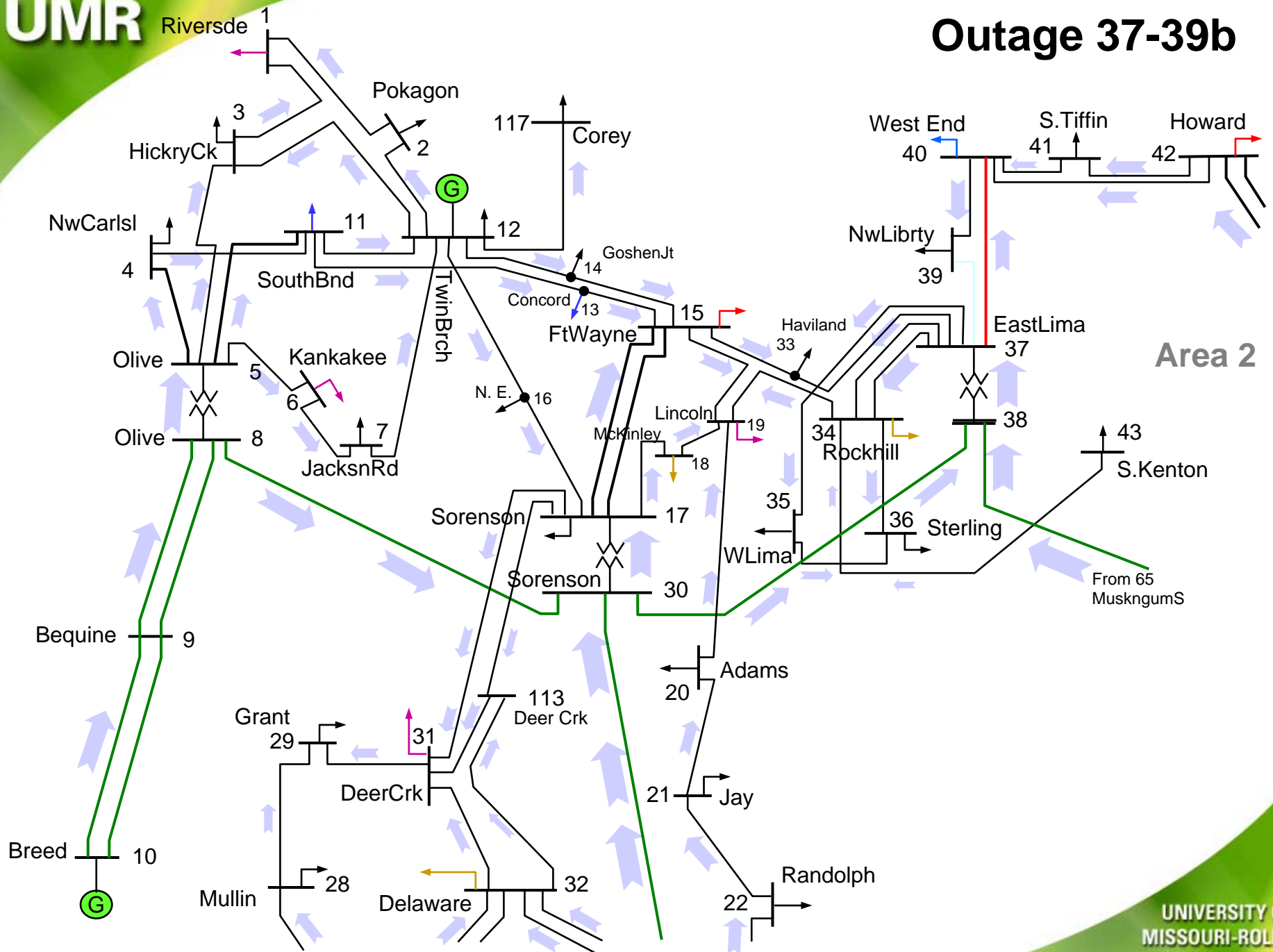


Outage 37-39a

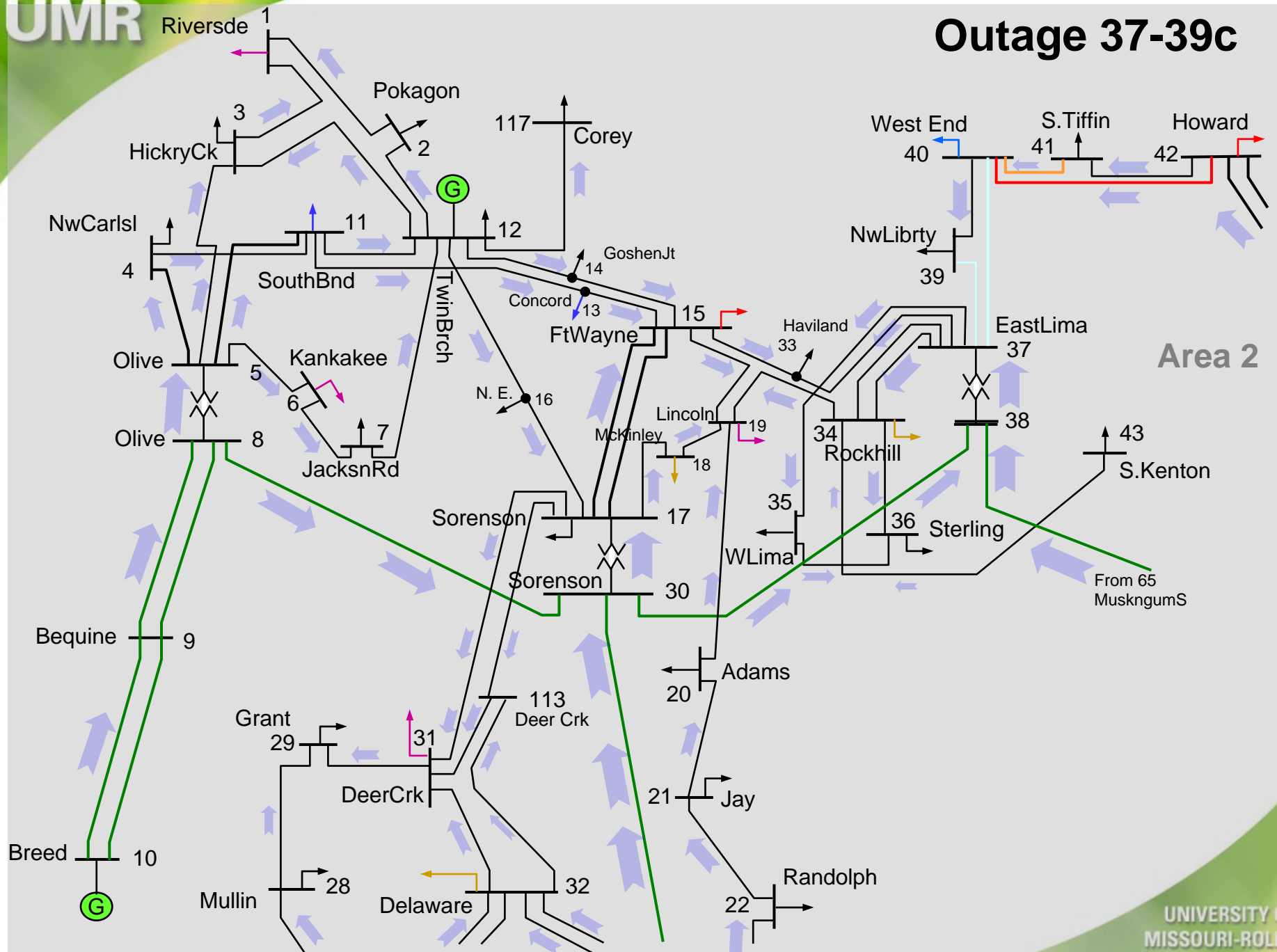


Area 2

Outage 37-39b

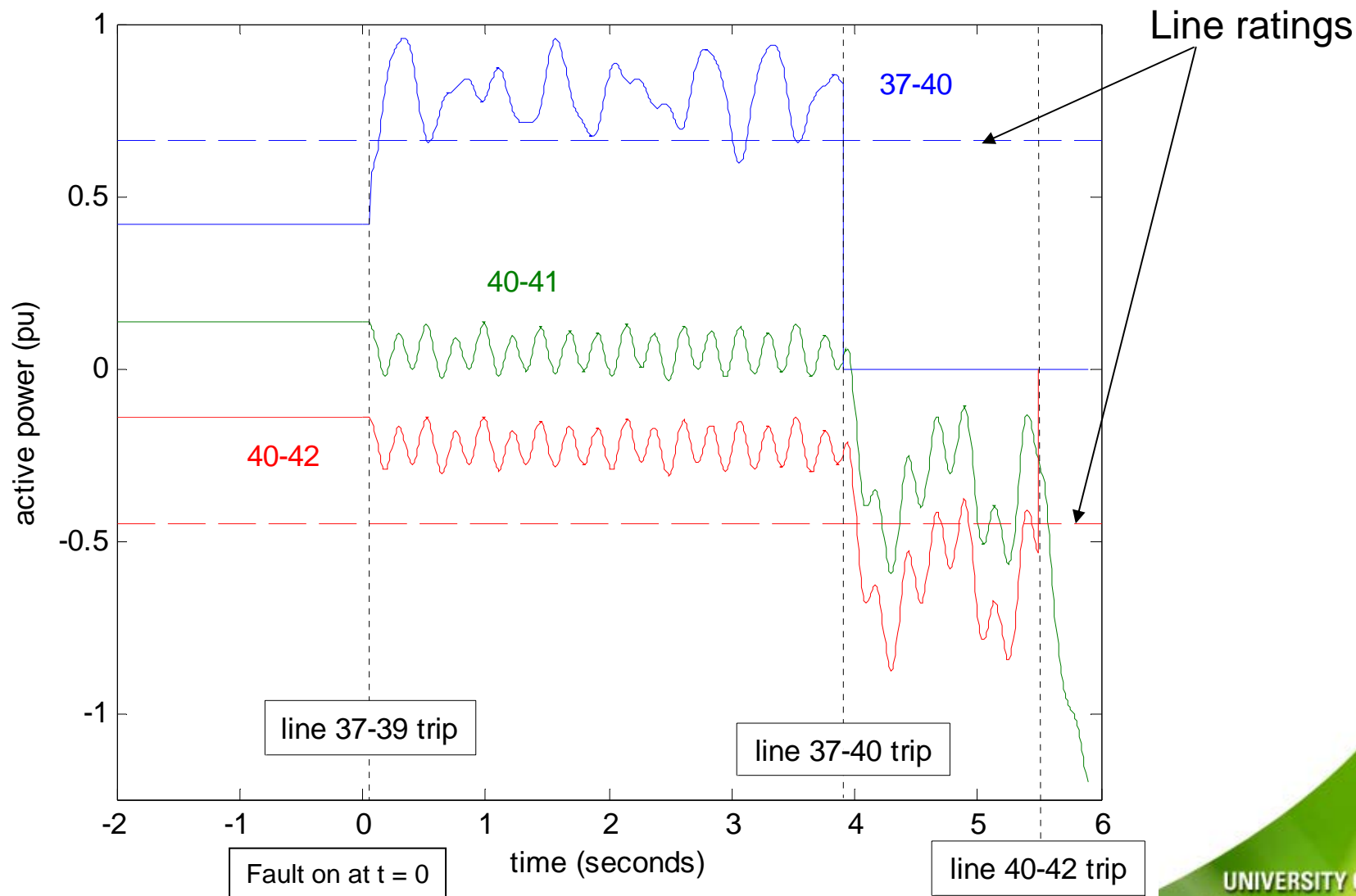


Outage 37-39c



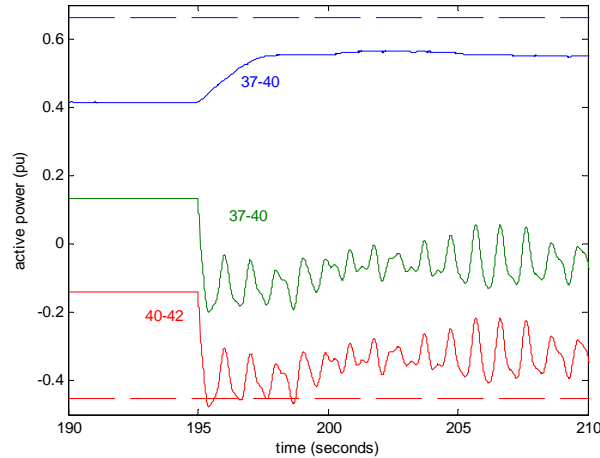
Area 2

Simulation of cascading failure

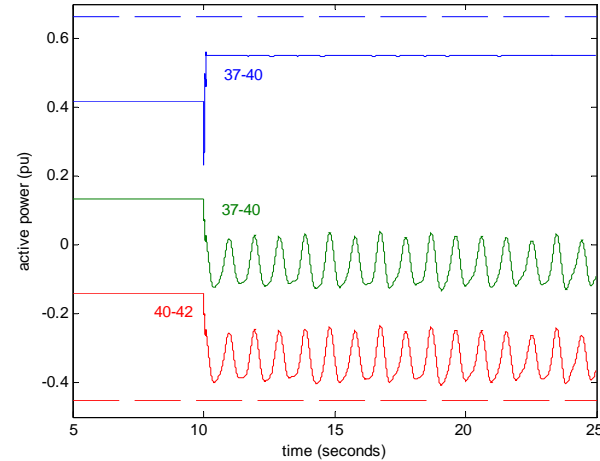


Comparison

experimental



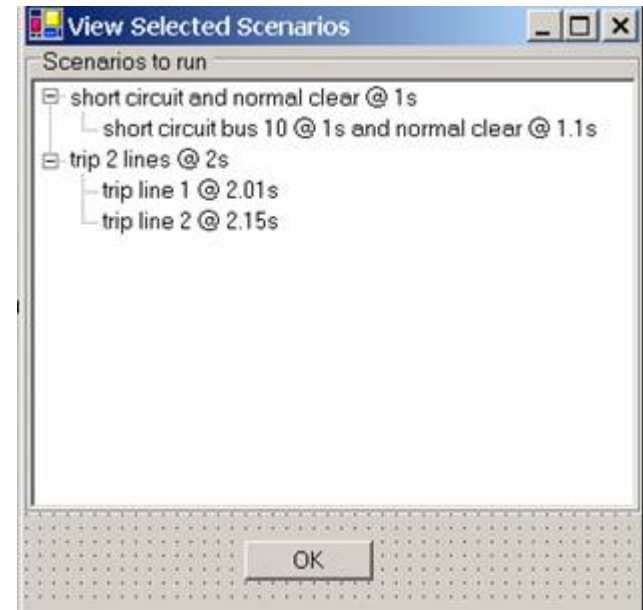
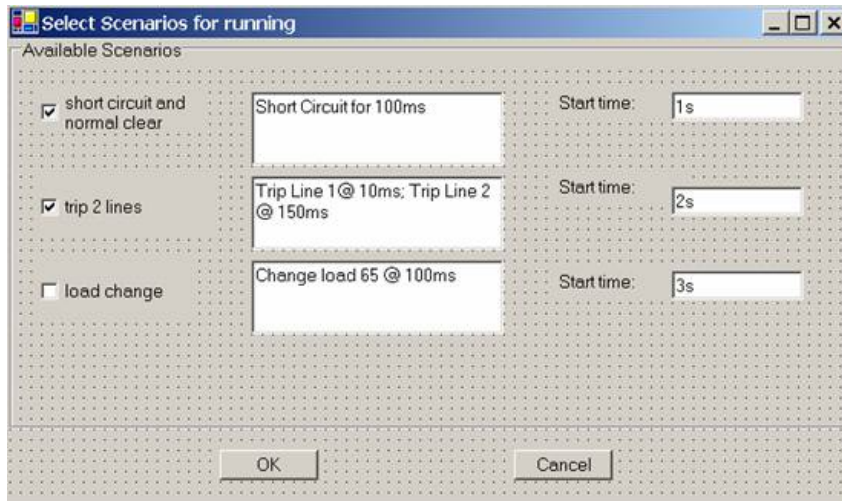
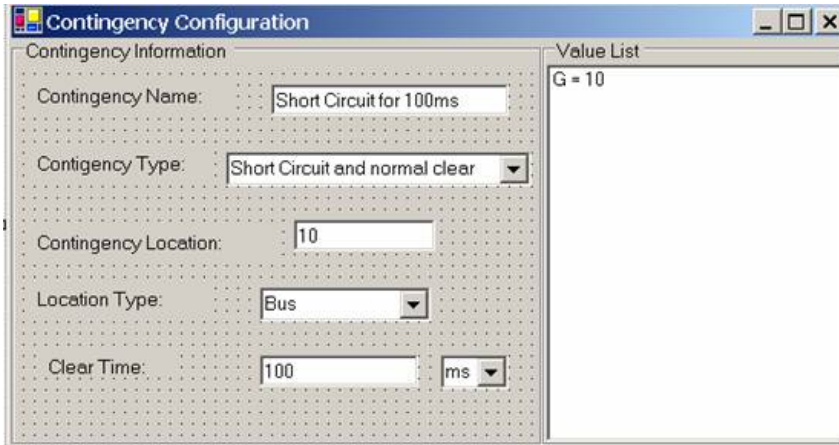
simulation

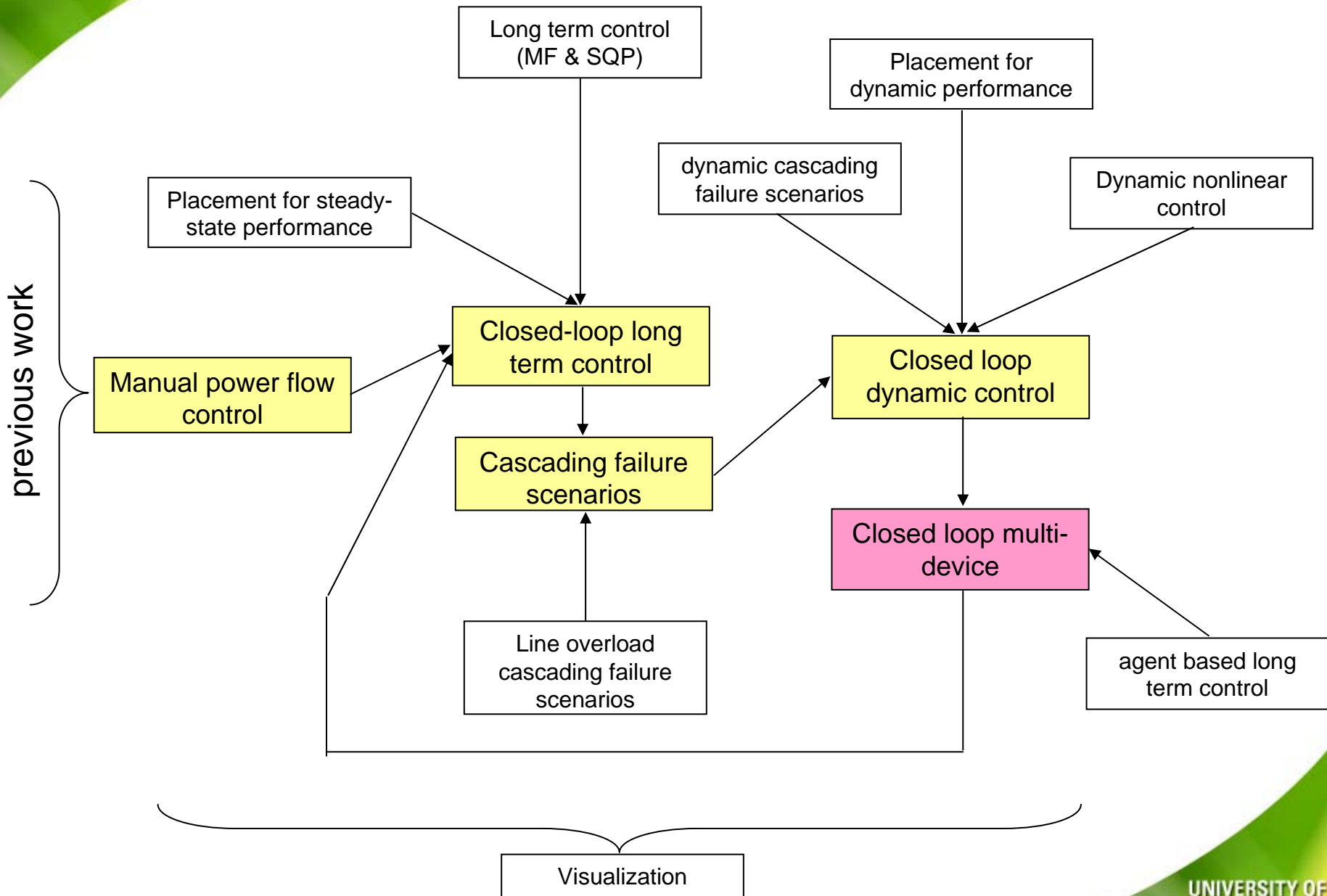


mode	$A(i)$	$B(i)$	$\omega(i)$		mode	$A(i)$	$B(i)$	$\omega(i)$
1	0.02	0	13.05		1	0.02	0	13.04
2	0.05	0	6.55		2	0.07	0	6.54
3	0.02	-0.14	6.08					
4	0.04	0	6.1					

$$x(t) = \sum A_i e^{B_i t} \cos(\omega_i t + \theta_i)$$

GUIs for HIL





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