

DOE Bioenergy Technologies Office (BETO) 2023 Project Peer Review

1.2.2.7801 Real time, Integrated Dynamic Control Optimization to Improve the Operation Reliability of a Biomass Dryer

04/05/2023

Feedstock Conversion Interface Consortium

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Battelle Energy Alliance manages INL for the
U.S. Department of Energy's Office of Nuclear Energy



Idaho National Laboratory

Project Overview

- **Objective:** Develop a real-time control-optimization solution that ensures a reliable and continuous feeding and conveying of biomass through a continuous dryer, while controlling the temperature to achieve the target moisture content of wood fiber.
- **Why:** Variations in feedstock characteristics (e.g., particle size distribution, moisture, ash, and heat content) negatively affect the integration of biomass feeding systems and result in low or unreliable on-stream time and long start-up times.
- **Project Goals:**
 - Integrate on-line instrumentation with adaptive control methods to produce a real-time optimal control model
 - Achieve 90% on-stream time and with 90% of the material meeting specified output moisture content of 12%-16% (wet basis)
- **Relevance to Industry:** This project addresses feedstock handling and preprocessing issues that have plagued the industry. If this project is successful, costs will decrease and system reliability will increase

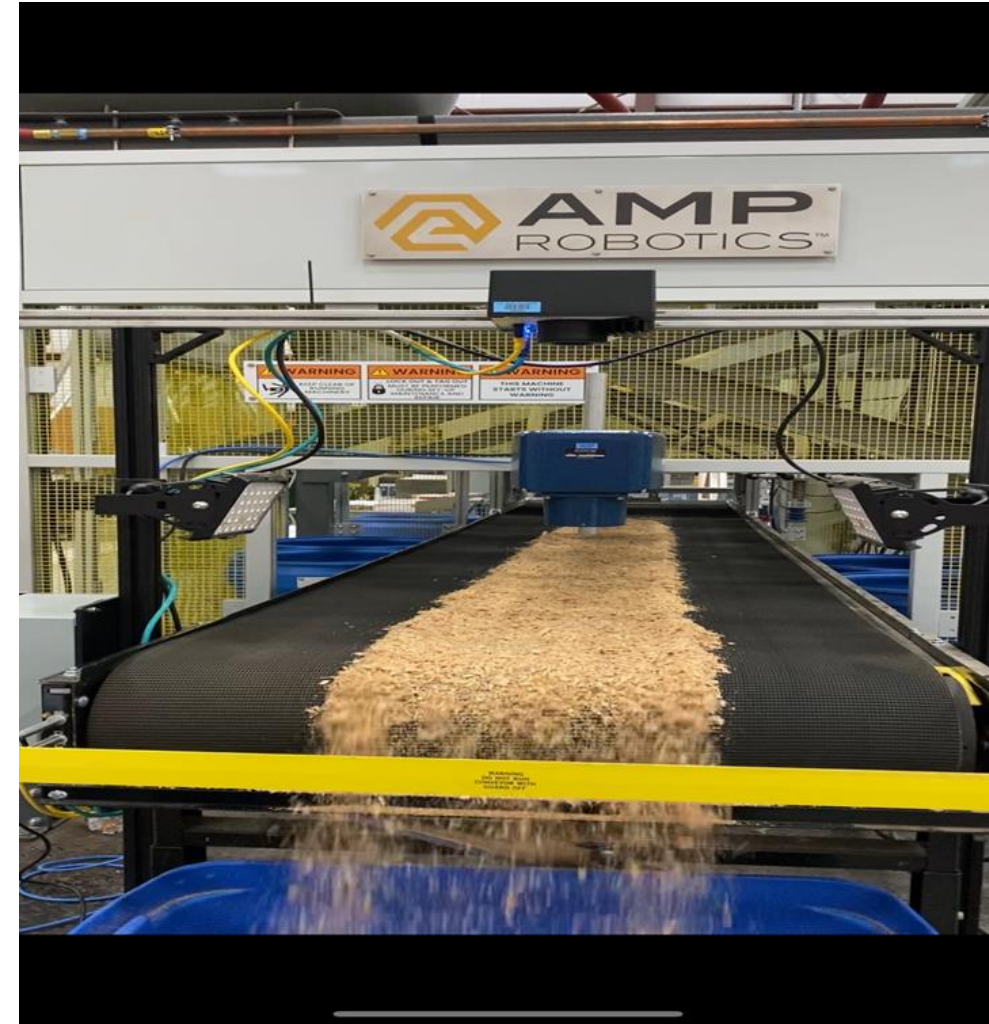
1 – Approach

Technical Approach

- Collect data for baseline run and identify root causes of feed system failure
- Collaborate with researchers and leverage existing knowledge to design in-line sensor arrays that can characterize feedstock moisture content, particle size and particle shape.
- Collect performance data for various conditions and system settings to serve as the base data set for model development
- Design and Implement optimal control algorithm

Technical Challenges

- Collecting data at relevant temporal scales
- Computational requirements of running models
- Safety and safe operations



1 – Approach

Go/No-Go Decision Point

- The Go/No-Go decision point was based on the ability of the proposed system to be able to acquire and process data quickly enough to improve on base line performance
- The Go decision point was met in Q2 of FY22
 - Showed a reduction in system latency from 5 min to 5 sec

Risks and Mitigation

- Safety of operating
 - Idaho Forest Group undertook additional safety requirements to become operational
 - No-cost extension to extend project

Performance Metrics

- Time on stream
- % of material in moisture content window

1 – Approach

Team

- Robert Kinoshita (INL) – Sensors/Data Interface
- Shaw Wen (INL) – Data Scientist
- Jason Mangano (IFG) – Project Coordinator
- Brian Riga (IFG) – Vice President of Technology

Communication/Collaboration

- Bi-weekly Team meetings to discuss progress
- Quarterly Check-ins with BETO
- Four Quarterly Milestones per Year

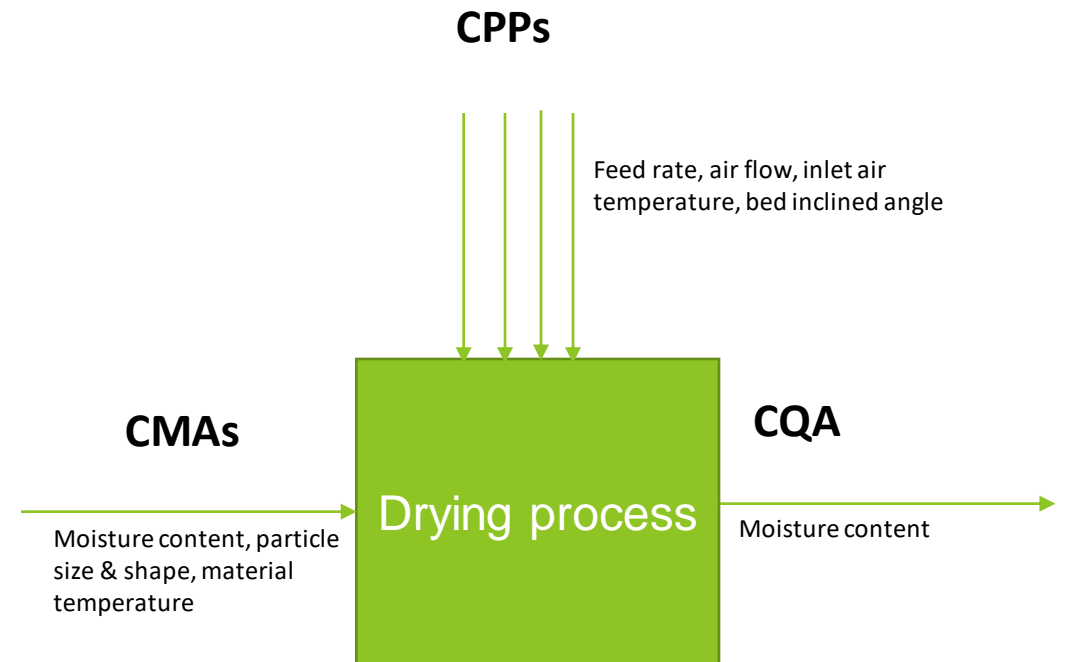
Diversity, Equity and Inclusion: While diversity, equity and inclusion is not a formal goal of this project, success in this project with help rural businesses and increase the wealth in rural communities



MoistTech: Non-contact moisture sensors appropriate for use in a continuous process

2 – Progress and Outcomes Proposed Process

- **Drying technology:**
 - Vibrating fluidized bed (1 ft wide x 7.5 ft long)
- **Capacity:**
 - Depending on moisture removal: 400 – 500 lb/hr (dry basis)
- **Current status:**
 - Designing the feed bin and feed conveyor to accommodate the particle image sensor
- **Critical Quality Attribute (CQA):**
 - Moisture content (10%)
- **Critical Material Attribute (CMA):**
 - Moisture content (~20%), particle size & shape, material temperature
- **Critical Process Parameter (CPP):**
 - Biomass feed rate, air flow, inlet air temperature, bed inclined angle



2 – Progress and Outcomes

Examining in-line sensor performance – Moisture Sensors

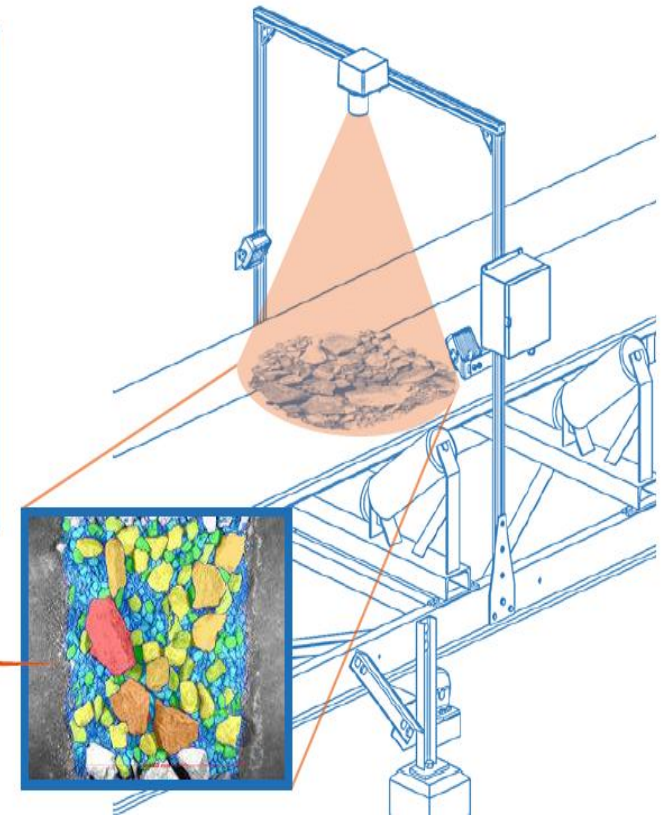
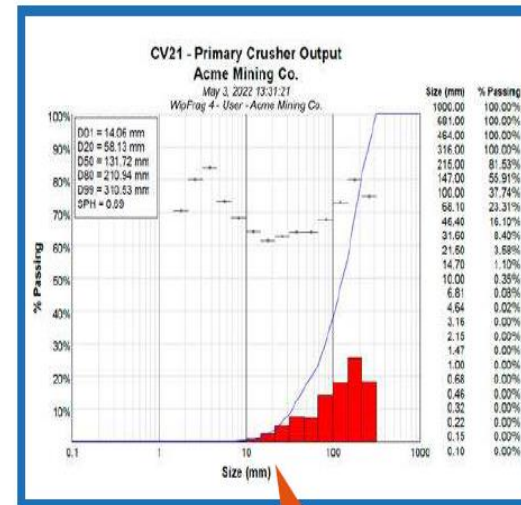
- Sensor Type: Near Infrared



2 – Progress and Outcomes

Examining in-line sensor performance – Particle Size

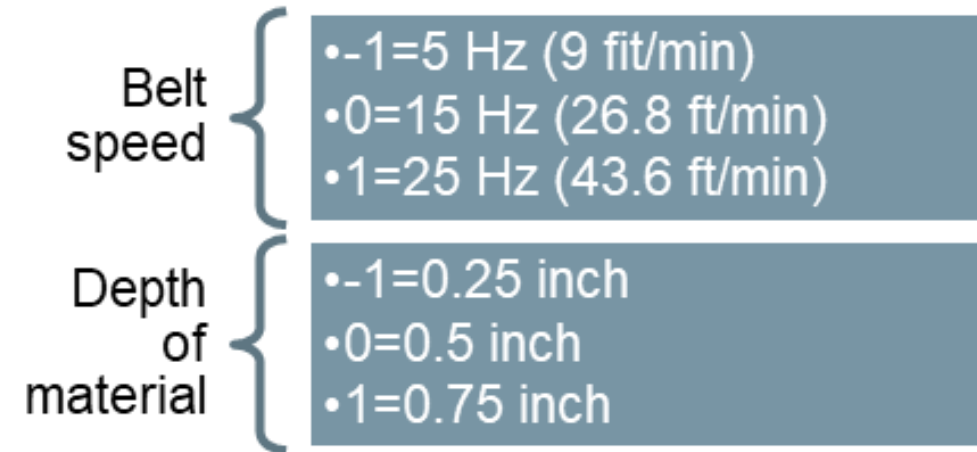
- Sensor Type: Image Processing



2 – Progress and Outcomes

Examining in-line sensor performance – Experimental Design

| Exp | Belt speed | Material Depth | Camera Settings |
|-----|------------|----------------|-----------------|
| 1 | -1 | -1 | 0 |
| 2 | -1 | 1 | 0 |
| 3 | 1 | -1 | 0 |
| 4 | 1 | 1 | 0 |
| 5 | -1 | 0 | -1 |
| 6 | -1 | 0 | 1 |
| 7 | 1 | 0 | -1 |
| 8 | 1 | 0 | 1 |
| 9 | 0 | -1 | -1 |
| 10 | 0 | -1 | 1 |
| 11 | 0 | 1 | -1 |
| 12 | 0 | 1 | 1 |
| 13 | 0 | 0 | 0 |



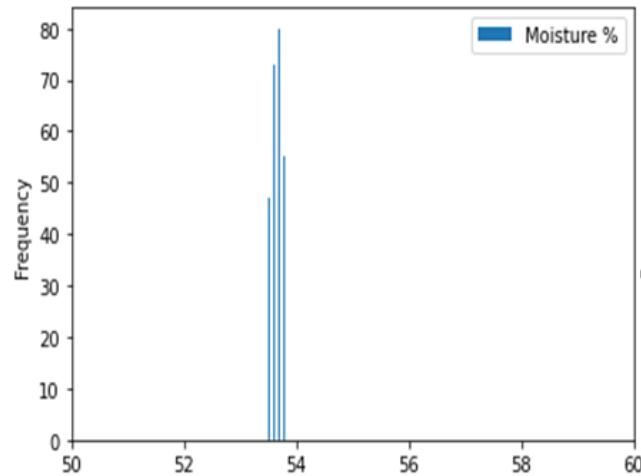
Camera Settings

| | Threshold | Valley Threshold | Blur | Search Dark | Search Radius | Window Size |
|----|-----------|------------------|------|-------------|---------------|-------------|
| -1 | -50 | -1.0 | 2.0 | 15 | 15 | 20 |
| 0 | -30 | -2.0 | 1.0 | 15 | 15 | 20 |
| 1 | -10 | -3.0 | 0.5 | 15 | 15 | 20 |

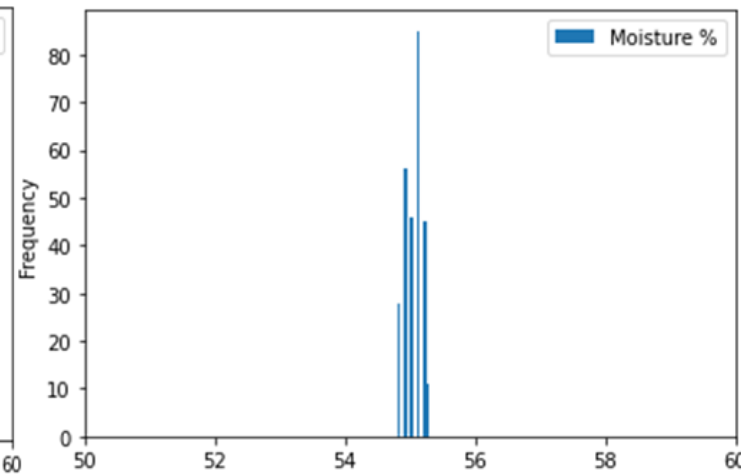
2 – Progress and Outcomes

Examining in-line sensor performance – Precision (Moisture)

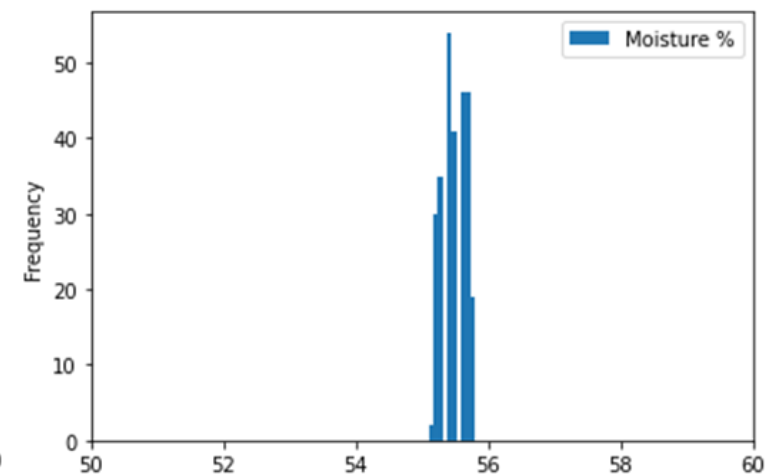
Depth=0.25 inch



Depth=0.5 inch



Depth=0.75 inch



| Depth | 0.25 inch | 0.5 inch | 0.75 inch |
|----------|--------------|--------------|--------------|
| Count | 255 | 271 | 273 |
| Mean (%) | 53.66 | 55.04 | 55.49 |
| Std. | 0.10 | 0.14 | 0.18 |
| CV | 0.33% | 0.25% | 0.33% |
| Min. (%) | 53.5 | 54.8 | 55.1 |
| Max (%) | 53.8 | 55.3 | 55.8 |

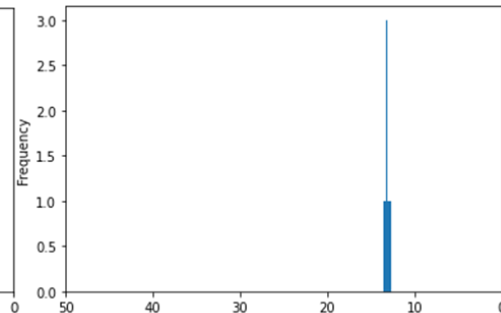
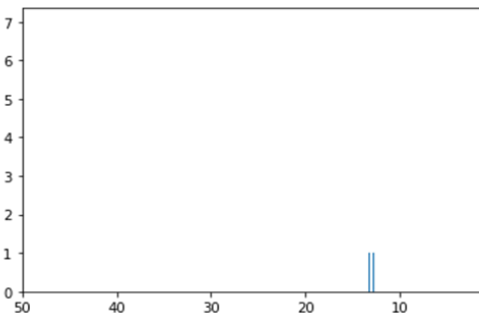
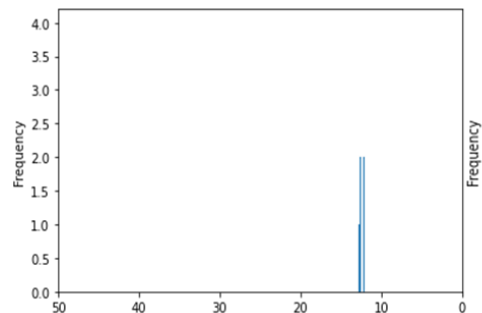
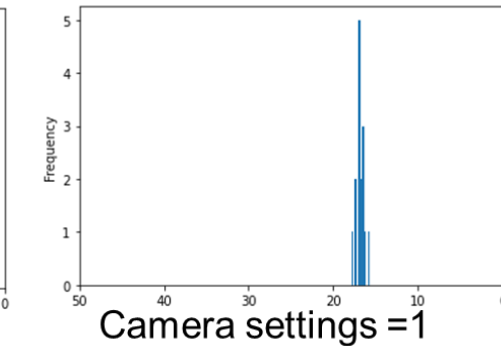
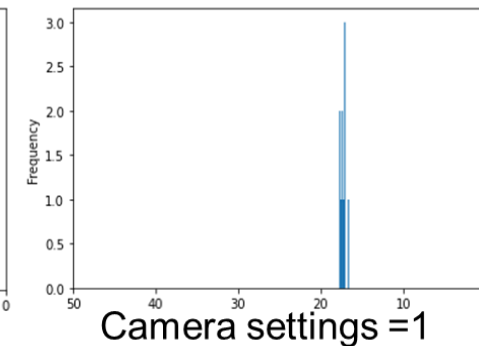
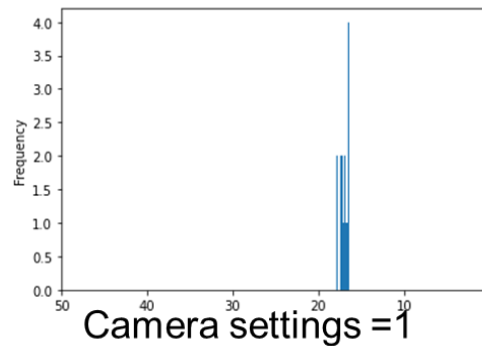
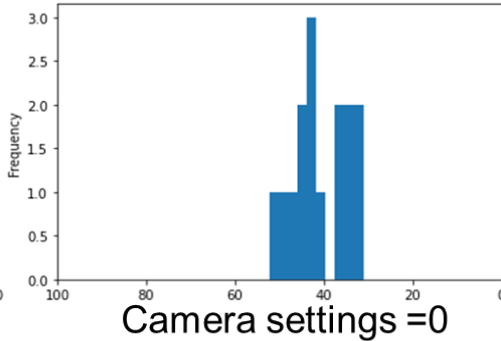
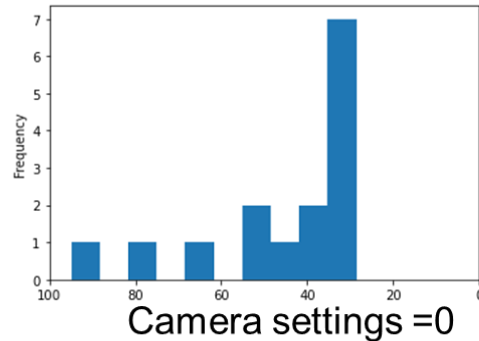
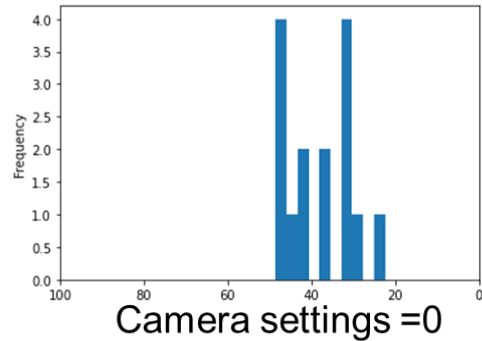
2 – Progress and Outcomes

Examining in-line sensor performance – Precision (PSD)

Depth=0.25 inch
Camera settings =-1

Depth=0.5 inch
Camera settings =-1

Depth=0.75 inch
Camera settings =-1



| Depth | 0.25 in | 0.5 in | 0.75 in |
|-----------|---------|--------|---------|
| Count | 15 | 15 | 15 |
| Mean (mm) | 37.93 | 45.13 | 40.78 |
| Std. | 8.27 | 19.42 | 6.28 |
| CV | 21.80% | 43.03% | 15.40% |

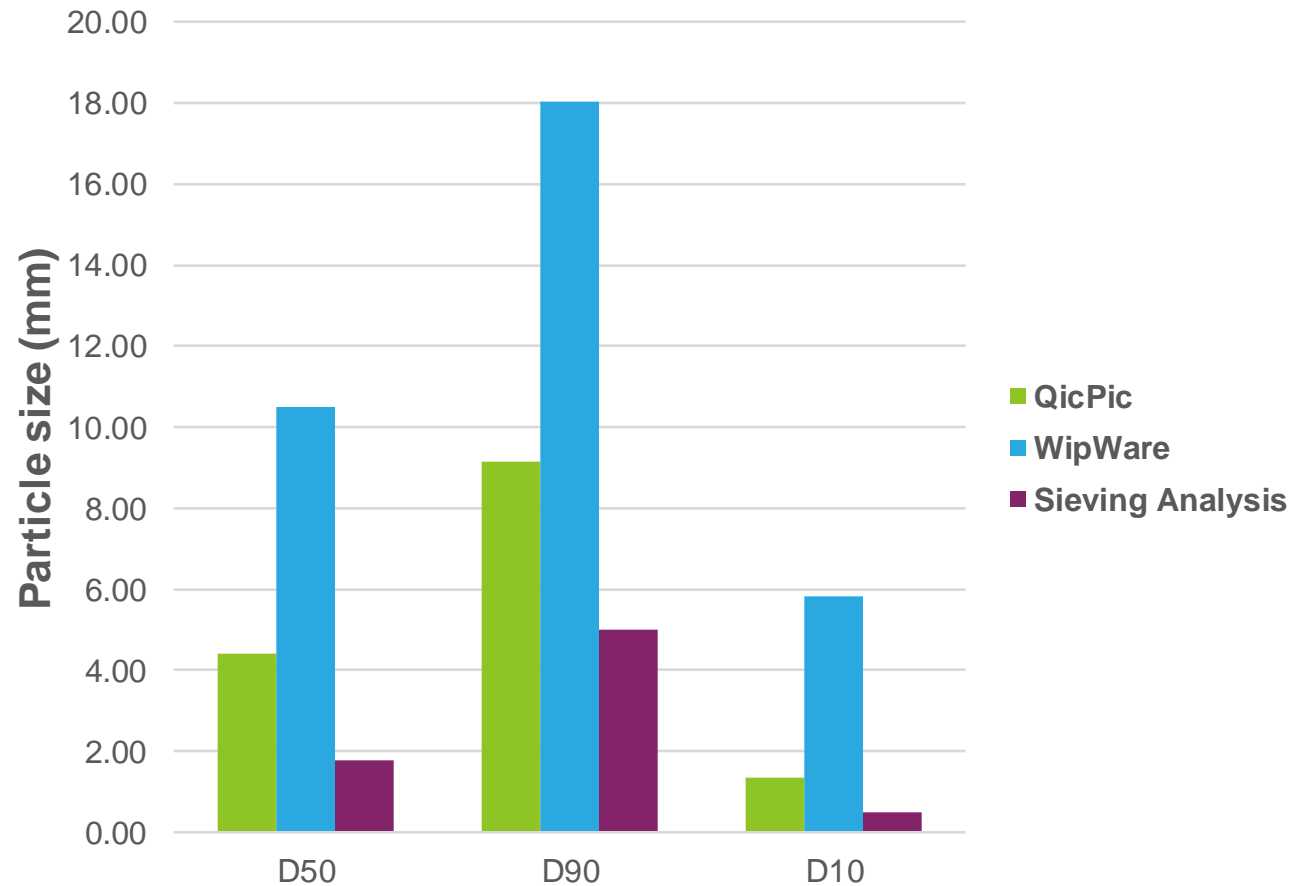
| Depth | 0.25 in | 0.5 in | 0.75 in |
|-----------|---------|--------|---------|
| Count | 15 | 15 | 15 |
| Mean (mm) | 16.99 | 17.2 | 16.78 |
| Std. | 0.48 | 0.3 | 0.53 |
| CV | 2.83% | 1.74% | 3.16% |

| Depth | 0.25 in | 0.5 in | 0.75 in |
|-----------|---------|--------|---------|
| Count | 15 | 15 | 15 |
| Mean (mm) | 12.52 | 12.98 | 13.16 |
| Std. | 0.23 | 0.12 | 0.27 |
| CV | 1.84% | 0.92% | 2.05% |

2 – Progress and Outcomes

Examining in-line sensor performance – Accuracy (PSD)

- Compared Sensor with two laboratory methods
- Sensor Overestimated Particle Size, but relative level of error appears to be consistent
- For use in the system, the true size of the particles is not necessary, but it is more important that a relative change in size can be detected.
- Optimizing camera settings and improvement in software may lead to higher accuracy



2 – Progress and Outcomes

Integrating Sensors and Reading Sensor Data

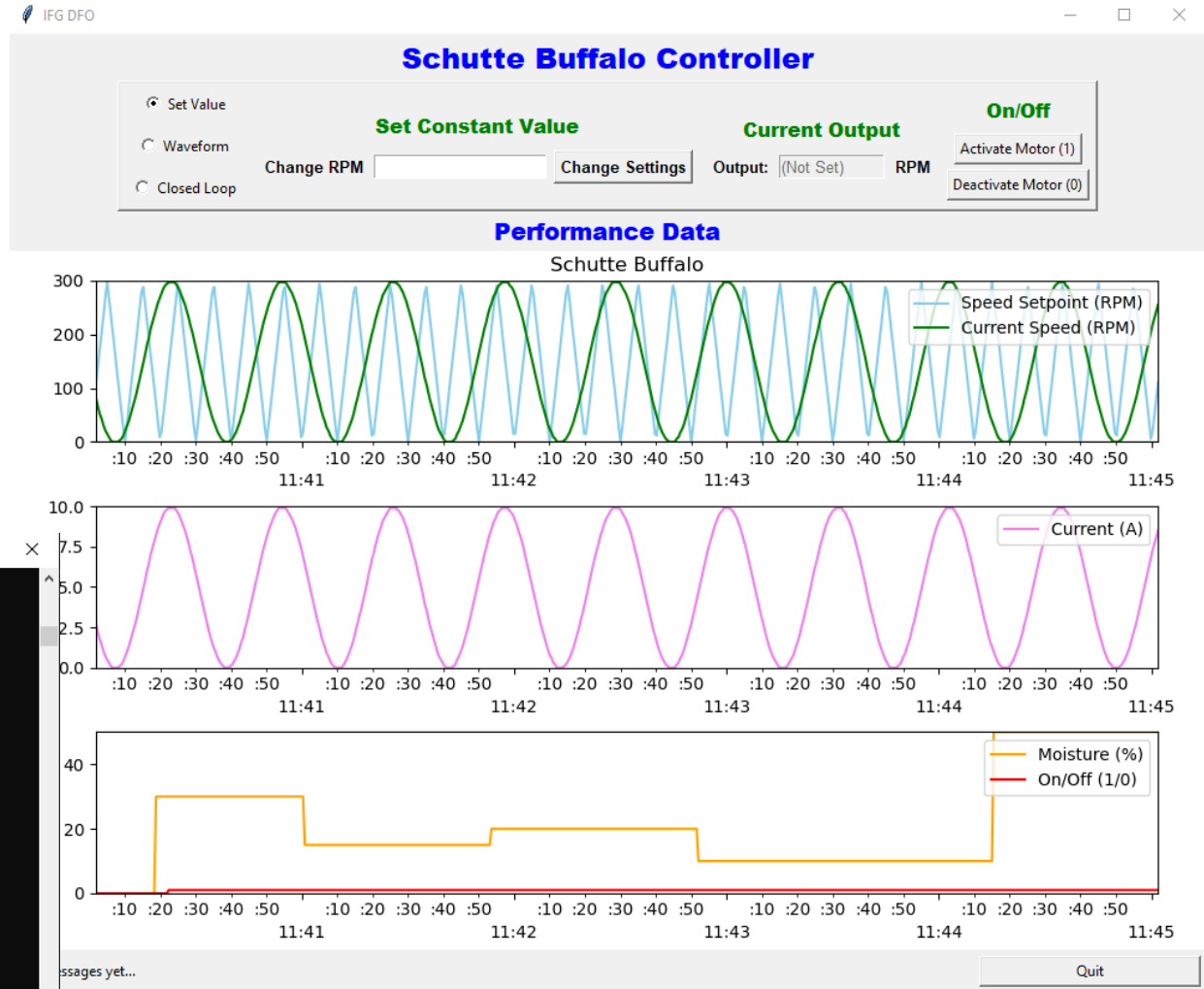


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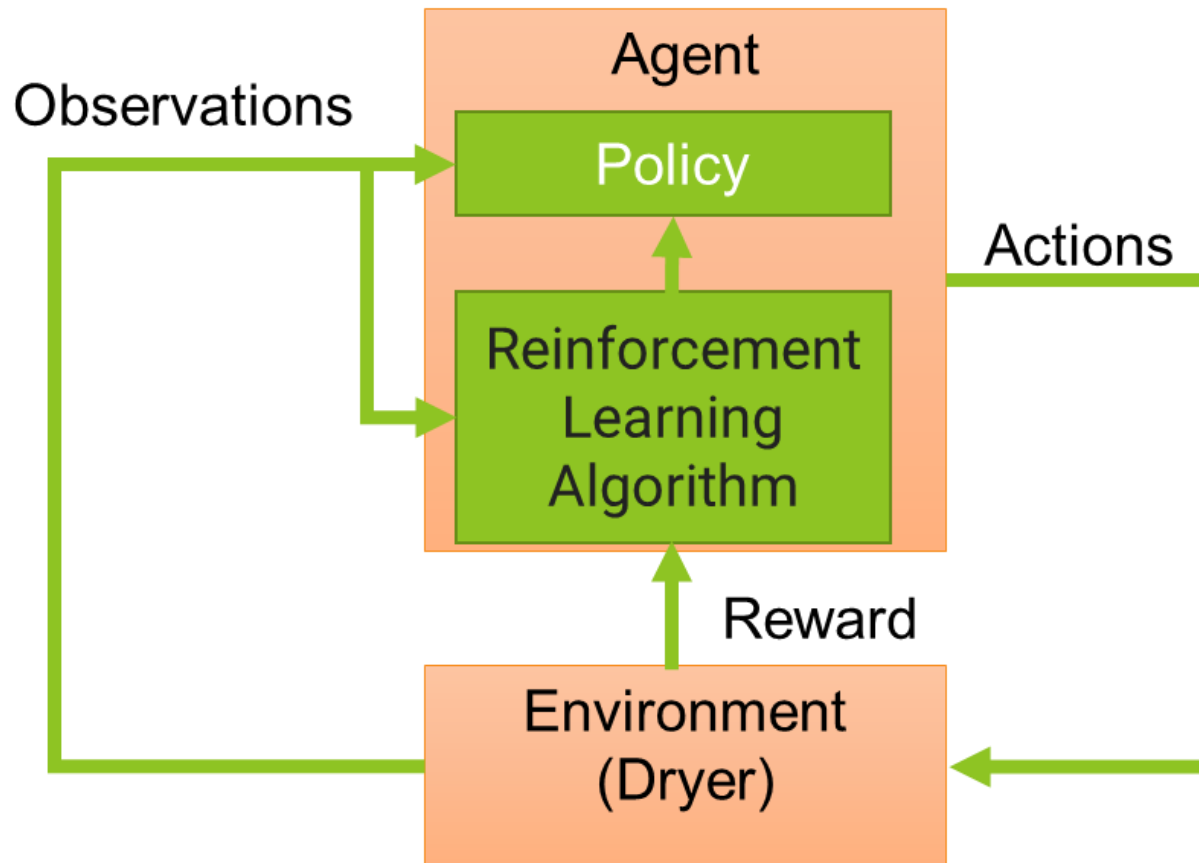
2022-04-15 09:22:39,491 MainThread INFO TestIR3000 :65 Block Text IR3000 Constituent 2 Name is: Constituent2
2022-04-15 09:22:39,537 MainThread INFO TestIR3000 :65 Block Text IR3000 Constituent 3 Name is: Constituent3
2022-04-15 09:22:39,600 MainThread WARNING TestIR3000 :57 Returned data length mismatch (16 requested, 1 returned)
2022-04-15 09:22:39,600 MainThread INFO TestIR3000 :65 Block Text IR3000 Temperature Name is:

(ifg_dfo_twisted) C:\Users\BOBK\Documents\Repos\IFG_DFO\Test Code\Moisttech IR3000>python TestIR3000.py
2022-04-15 09:23:19,627 MainThread INFO TestIR3000 :32 IR3000 Setup Bytes is: 0
2022-04-15 09:23:19,674 MainThread INFO TestIR3000 :32 IR3000 Reading 1 is: 81
2022-04-15 09:23:19,721 MainThread INFO TestIR3000 :32 IR3000 Reading 2 is: 0
2022-04-15 09:23:19,783 MainThread INFO TestIR3000 :32 IR3000 Reading 3 is: 0
2022-04-15 09:23:19,830 MainThread INFO TestIR3000 :32 IR3000 Pyrometer Reading is: 0
2022-04-15 09:23:19,877 MainThread INFO TestIR3000 :32 IR3000 Zero 1 is: 63802
2022-04-15 09:23:19,924 MainThread INFO TestIR3000 :32 IR3000 Zero 3 is: 0
2022-04-15 09:23:19,971 MainThread INFO TestIR3000 :32 IR3000 Zero 3 is: 0
2022-04-15 09:23:20,033 MainThread INFO TestIR3000 :32 IR3000 Span 1 is: 1874
2022-04-15 09:23:20,080 MainThread INFO TestIR3000 :32 IR3000 Span 2 is: 0
2022-04-15 09:23:20,127 MainThread INFO TestIR3000 :32 IR3000 Span 3 is: 0
2022-04-15 09:23:20,174 MainThread INFO TestIR3000 :32 IR3000 Wheel Frequency x 100 is: 3004
2022-04-15 09:23:20,221 MainThread INFO TestIR3000 :32 IR3000 Status Bits is: 97
2022-04-15 09:23:20,283 MainThread INFO TestIR3000 :32 IR3000 +5 Volt Rail is: 527
2022-04-15 09:23:20,330 MainThread INFO TestIR3000 :32 IR3000 -12 Volt Rail is: 604
2022-04-15 09:23:20,377 MainThread INFO TestIR3000 :32 IR3000 12 Volt Rail is: 609
2022-04-15 09:23:20,424 MainThread INFO TestIR3000 :65 Block Text IR3000 Current Product Name is: Dry Chips
2022-04-15 09:23:20,471 MainThread INFO TestIR3000 :65 Block Text IR3000 Constituent 1 Name is: Moisture
2022-04-15 09:23:20,533 MainThread INFO TestIR3000 :65 Block Text IR3000 Constituent 2 Name is: Constituent2
2022-04-15 09:23:20,580 MainThread INFO TestIR3000 :65 Block Text IR3000 Constituent 3 Name is: Constituent3
2022-04-15 09:23:20,627 MainThread WARNING TestIR3000 :57 Returned data length mismatch (16 requested, 1 returned)
2022-04-15 09:23:20,627 MainThread INFO TestIR3000 :65 Block Text IR3000 Temperature Name is:

(ifg_dfo_twisted) C:\Users\BOBK\Documents\Repos\IFG_DFO\Test Code\Moisttech IR3000>
    
```



2 – Progress and Outcomes Reinforcement Learning



Observations

- Input moisture
- Output moisture
- Feed rate
- Firing rate
- Particle Size

Actions

- Increase firing rate
- Slow down firing rate
- Increase feed rate
- Decrease feed rate

Reward

- Difference between target moisture and actual moisture

Summary

- **Challenge:** Variations in feedstock characteristics (e.g., particle size distribution, moisture, ash, and heat content) negatively affect the integration of biomass feeding systems and conversion processes and result in low or unreliable on-stream time and long start-up times
- **Goal:** Develop a dynamic, control system that produces 90% uptime and >90% of the material within 12% - 16% MC (wet basis) window.
- **Requirements:**
 - Use sensors to determine MC and Particle Size Distribution
 - Develop control algorithm that utilizes sensor output to control operation
 - Demonstrate control system on industrial scale equipment
- **Next Steps:**
 - Complete collection of process performance data
 - Parametric study of saw dust drying
 - Characterize amount and sources of variability of critical material attributes entering the dryer
 - Complete controller software
 - Train model based on operational data
 - Validate control of drying system

Quad Chart Overview

Timeline

- *Project Start: 10/1/2021*
- *Project end date: 9/30/2023*

| | FY22 Costed | Total Award |
|----------------------|-------------|-------------|
| DOE Funding | \$391,260 | \$528,000 |
| Project Cost Share * | | |

TRL at Project Start: 3
TRL at Project End: 5

Project Goal

Develop a new, real-time, integrated, dynamic, control-optimization solution that ensures a reliable, cost-effective, robust, and continuous feeding and conveying of biomass through a continuous dryer, with heated-air temperature and flow control to achieve the target moisture content of wood fiber.

End of Project Milestone

Demonstrate improved operational reliability to 90% and achieving moisture content of wood fiber in the 12-16% range by integrating FCIC and other collaborator capabilities (e.g., sensors, in-line instrumentation, intelligent adaptive control, predictive model for mechanical behavior of biomass

Funding Mechanism

FCIC Direct Funding Opportunity

Project Partners*

- Idaho Forest Group

*Only fill out if applicable.



Idaho National Laboratory

Battelle Energy Alliance manages INL for the U.S. Department of Energy's Office of Nuclear Energy. INL is the nation's center for nuclear energy research and development, and also performs research in each of DOE's strategic goal areas: energy, national security, science and the environment.



Additional Slides

Responses to Previous Reviewers' Comments

- This project has not been reviewed previously

Publications, Patents, Presentations, Awards, and Commercialization

Due to the business sensitive nature of the project, no publications or presentations have been made