



**SOLAR ENERGY
TECHNOLOGIES OFFICE**
U.S. Department Of Energy

SAPPHIRE: Stability-Augmented Optimal Control of Hybrid PV Plants with Very High Penetration of Inverter-based Resources

Principal Investigator:

Jin Tan (PI); Andy Hoke (Co-PI)

National Renewable Energy Laboratory

11/17/2021



Team

National Lab



Research Institute



University



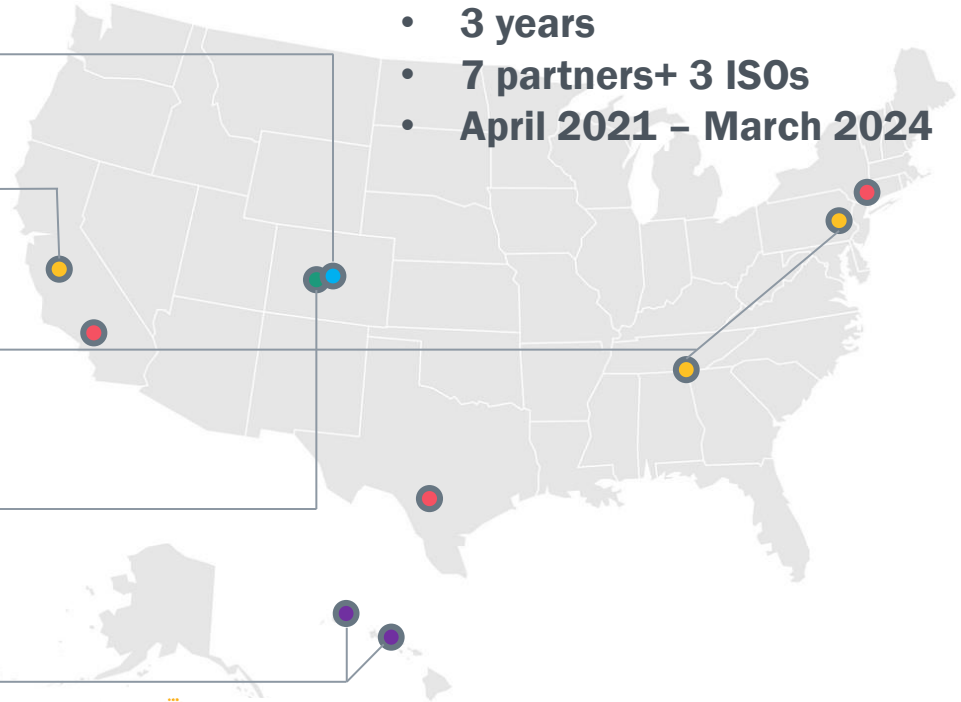
Vendor



ISO and Utility



- DOE SETO funded
- 3 years
- 7 partners+ 3 ISOs
- April 2021 - March 2024



Team



- Jin Tan
- Andy Hoke
- Przemyslaw Koralewicz
- Xin Fang
- Xinyang Zhou
- Andrey Bernstein
- Vahan Gevorgian
- Shannon Calkum **(Project controller)**



- Sam Ley
- Kevin V. Galloway
- Christopher C. Boyer,
- Shazreen M. Danial
- Kelsey Horowitz **(Project manager)**



- Marc Asano **(Lead)**



- Yilu Liu**(Lead)**
- Shutang You
- Henry Yin
- Hongyu Li



- Brad W. Rockwell **(Lead)**
- Cameron Kruse

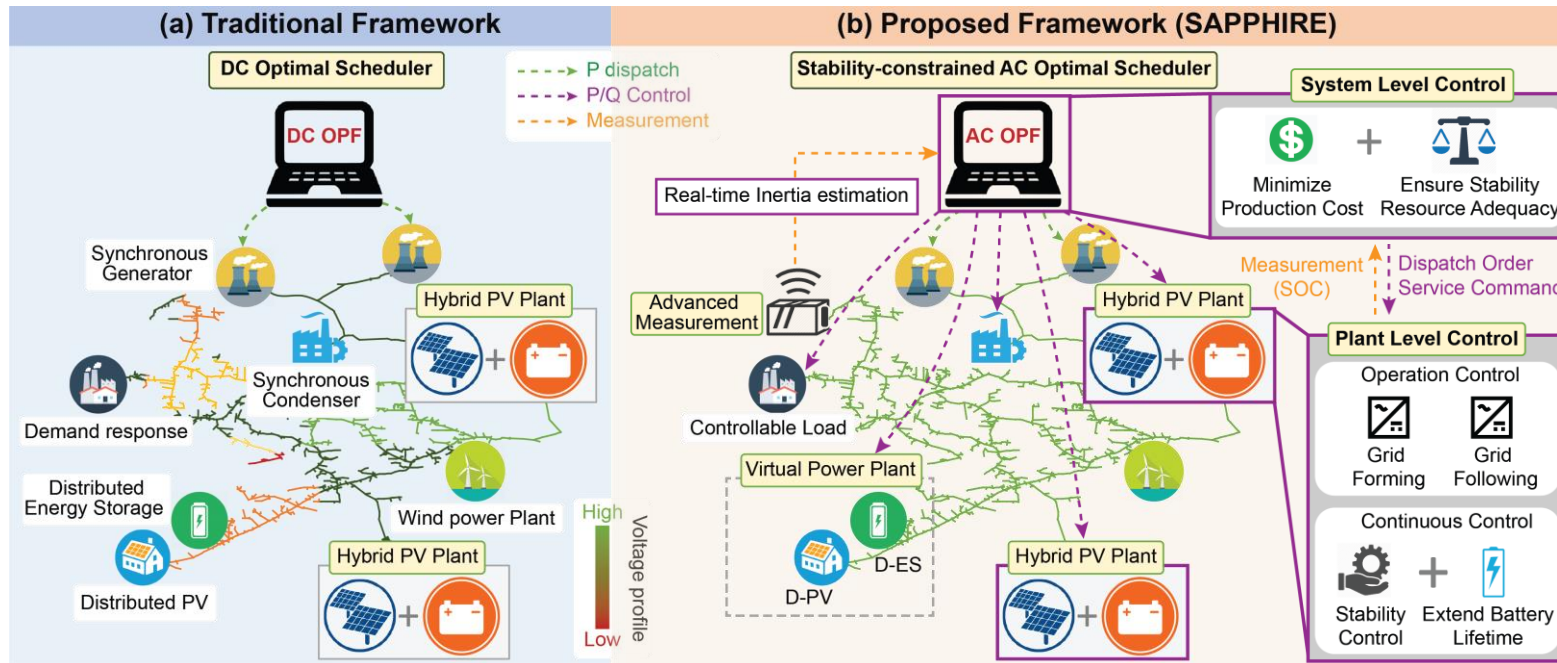


- Xiaonan Lu**(Lead)**
- Yuhua Du
- Lizhi Ding



- Robert Entriken **(Lead)**
- Erik Ela
- Nikita Singhal

Project Introduction



The proposed solution can simultaneously ensure **system stability** at the transmission system level, **optimize the provision of multiple services**, and **realize GFM operation of individual HPPs in coordination with PVs and BESS at the plant level**.

Project Approach



Task 1

System-level
scheduling & modeling

- HPP Modeling
- FFR quantification from IBRs
- Stability-constrained scheduling
- AC-OPF formulation



Task 2&4

Real-time monitoring

- Real-time inertia estimation
- Frequency measurement
- HPP operational data analysis



Task 3

Plant/device level
Stability analysis & control

- Stability issues related to Grid-forming control
- Advanced control of HPP
- Optimal control of PV and battery



Task 5

PHIL validation

- Grid services provision
- GFM operation
- inertia estimation using HPP

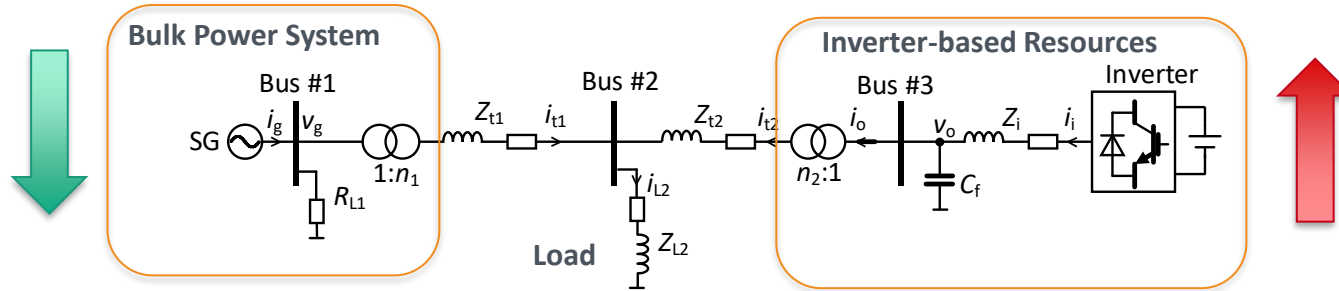


Task 6

Field demonstration

- Grid services
- Probing-based inertia estimation using HPP
- 100% Renewable operation with HPP

Fundamental Questions

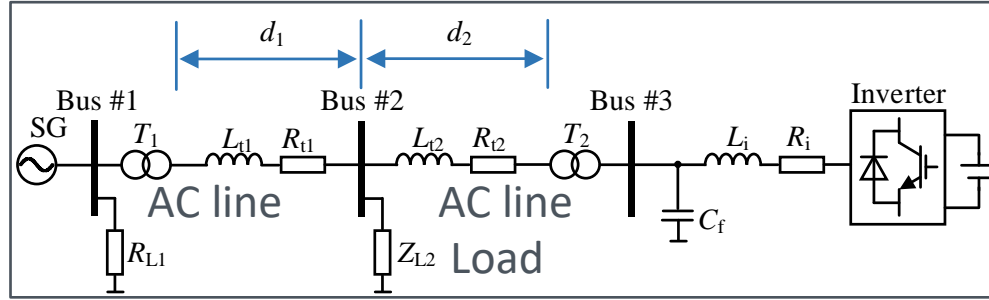


- What are the fundamental dynamic stability impact and characteristics when the IBR penetration level increases in a large-scale bulk grid?
 - Will IBRs introduce any new system-level stability issue?
 - How do they interact with the rest of SGs?
 - What are the critical/key parameters for the new stability issues, if there is any?
 - How do we determine the generation mix of GFL and GFM to mitigate stability issues for a given grid?

Lack of the theoretical analysis to understand the reason behind it!

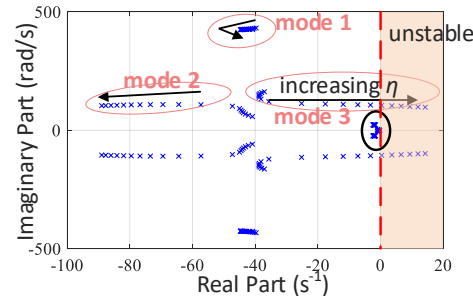
Approach for Small Signal Stability

Transmission System Representation



- State-space model
- Eigenvalue analysis

$$\begin{bmatrix} \Delta \dot{X}_{\text{Gen}} \\ \Delta \dot{X}_{\text{Inv}} \\ \Delta \dot{X}_{\text{Load}} \\ \Delta \dot{X}_{\text{Net}} \end{bmatrix} = A_{\text{sys}} \begin{bmatrix} \Delta X_{\text{Gen}} \\ \Delta X_{\text{Inv}} \\ \Delta X_{\text{Load}} \\ \Delta X_{\text{Net}} \end{bmatrix}$$



Case1.1 Eigenvalue trajectory plots when IBR penetration level changes ($d_1 = 400$ km)

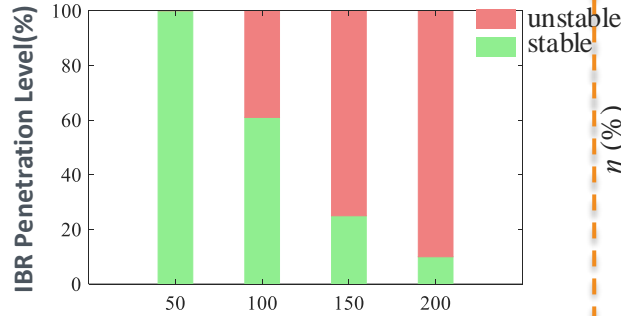
- Four dimensions
 - Control technology
 - Grid topology
 - Grid strength
 - Renewable penetration level

Scenario		GFL Inverter w/o Droop	GFL Inverter w/ Droop	GFM Inverter
Scenario 1 $d_1 = 50$ km, $d_2 = 1$ km	IBRS are located in the load center	Case 1.1	Case 1.2	Case 1.3
Scenario 2 $d_1 = 1$ km, $d_2 = 50$ km	IBRS are far away the load center	Case 2.1	Case 2.2	Case 2.3

Control Technology Comparison

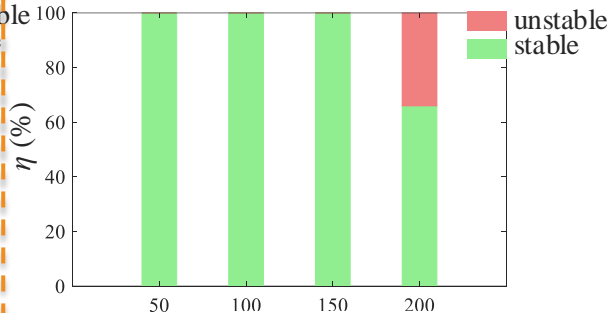
GFL Inverter w/o Droop

Case 2.1



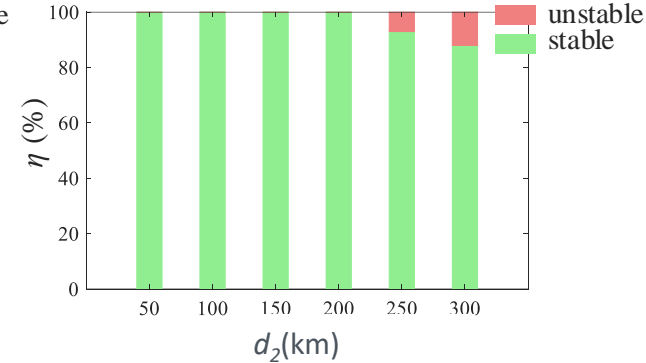
GFL Inverter with Droop

Case 2.2



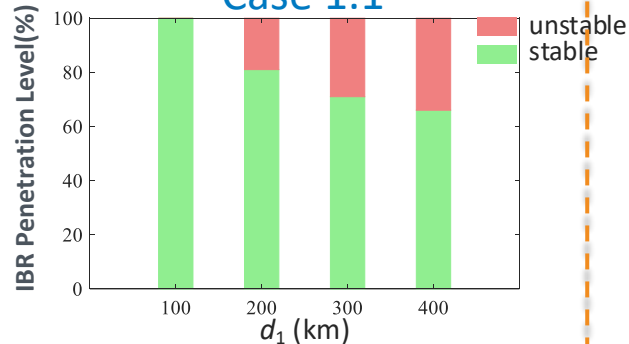
GFM Inverter

Case 2.3

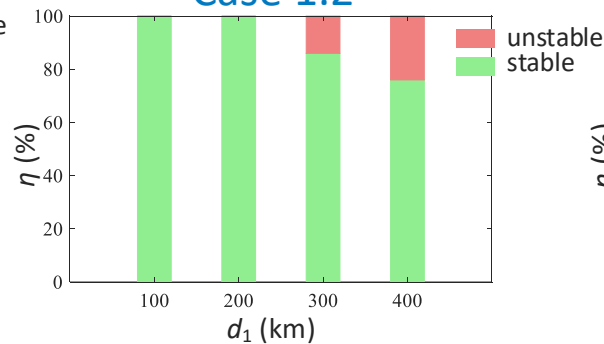


d_2 (km) → weaker grid

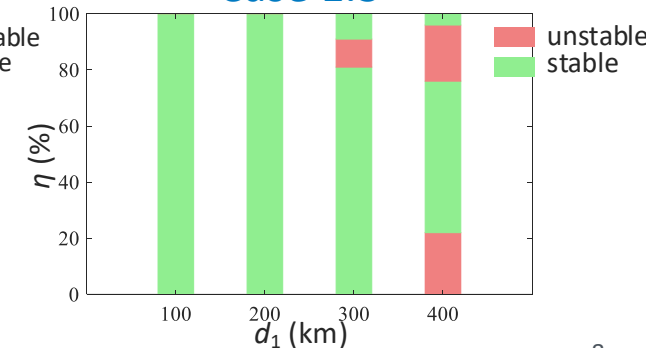
Case 1.1



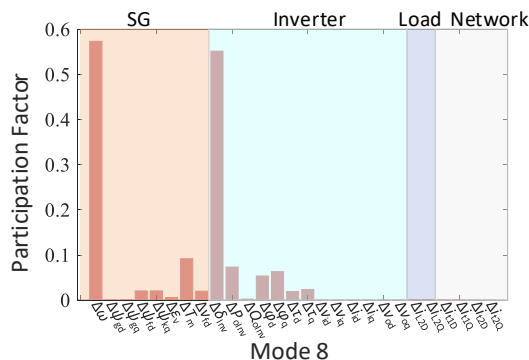
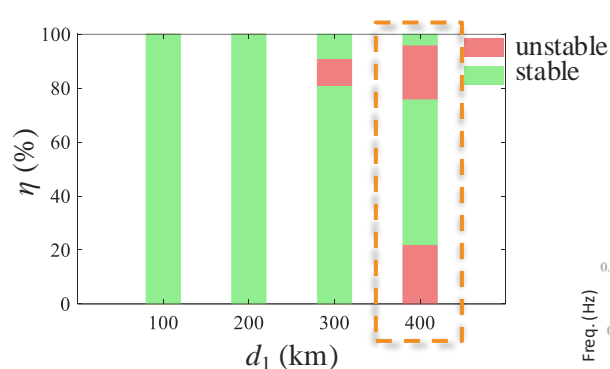
Case 1.2



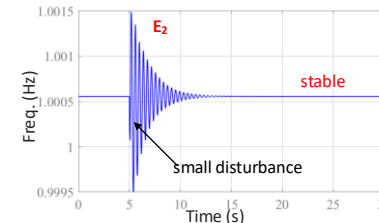
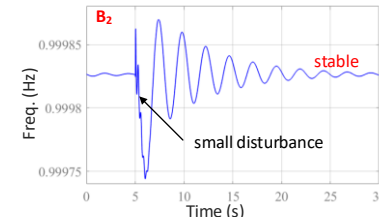
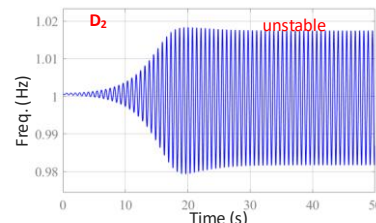
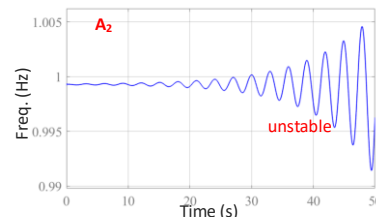
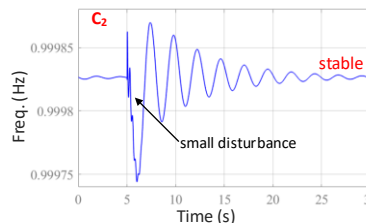
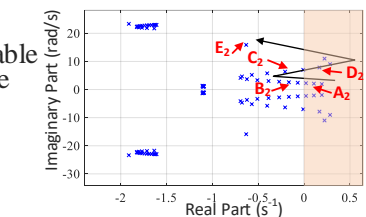
Case 1.3



Case 1.3

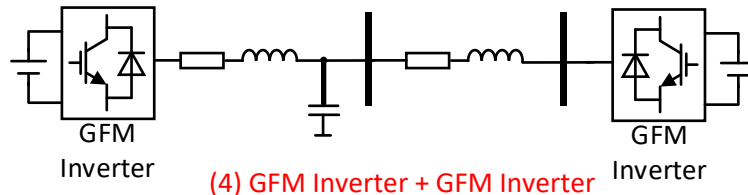
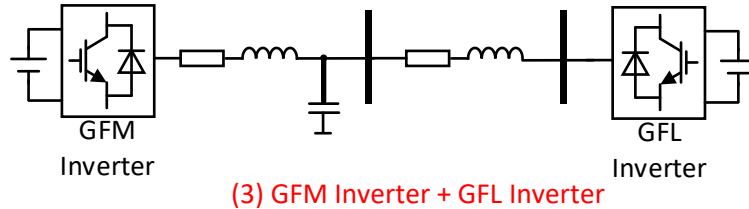
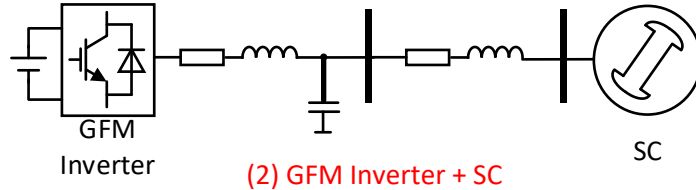
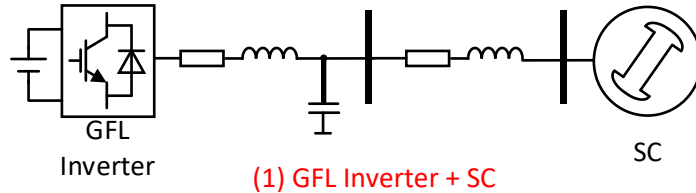


0.93 Hz coupling mode
(IBR Penetration=75%)



The new coupling oscillation mode between SG and GFM (Mode 8) has the dominant impact on stability when penetration level changes

Towards 100% Penetration of IBRs



100% GFL is different from 100% GFM

- Transient stability

Preliminary data shows

- with the same small signal stability margin, the transient stability margins for different inverters are different.
- GFM may improve transient stability margin, comparing to GFL.

...many questions remain

- All the control technologies are sensitive to grid strength. Compared to GFL with or w/o droop, GFM has the largest stability margin, but it still can have small-signal instability when we further push the envelop of the grid strength.
- Both GFL and GFM can achieve 100% renewable under some specific hypothesis in terms of small signal stability.
- Modal analysis reveals that unlike the **GFL** that a **PLL-related medium-frequency oscillation mode** could become the troublemaker for grid stability, the **GFM can introduce a low-frequency oscillation mode** that shows a strong interaction between the SGs, network and inverter controls.
- Compared to **GFL** with and w/o droop, **GFM** has the largest small signal stability margin, **but it still can have small-signal instability when we further reduce the grid strength.**
- When **GFM** is located at/near load center and SG is far away, it is easier to achieve 100% renewable than relatively high renewable. The instability is mainly caused by the new coupling oscillation modes that are introduced by GFM.



Thank you

Contact:

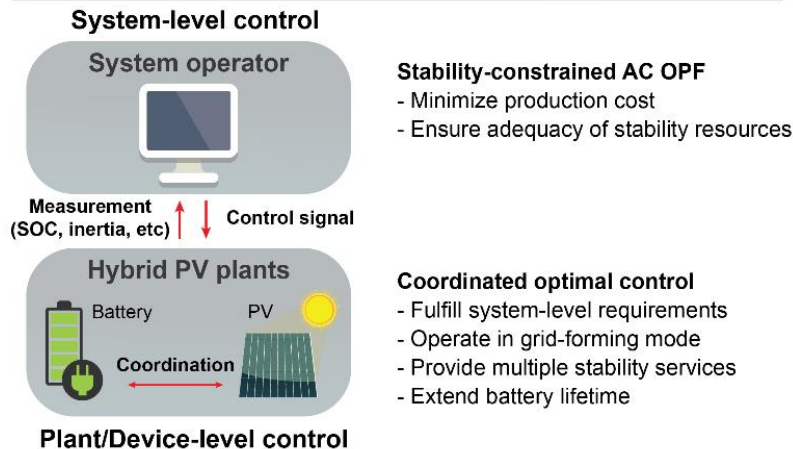
Jin Tan

jin.tan@nrel.gov

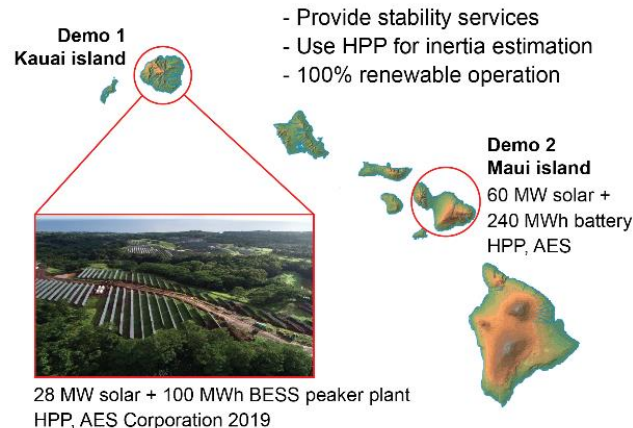
Andy Hoke

andy.hoke@nrel.gov

Hierarchical Control Framework: SAPPHIRE



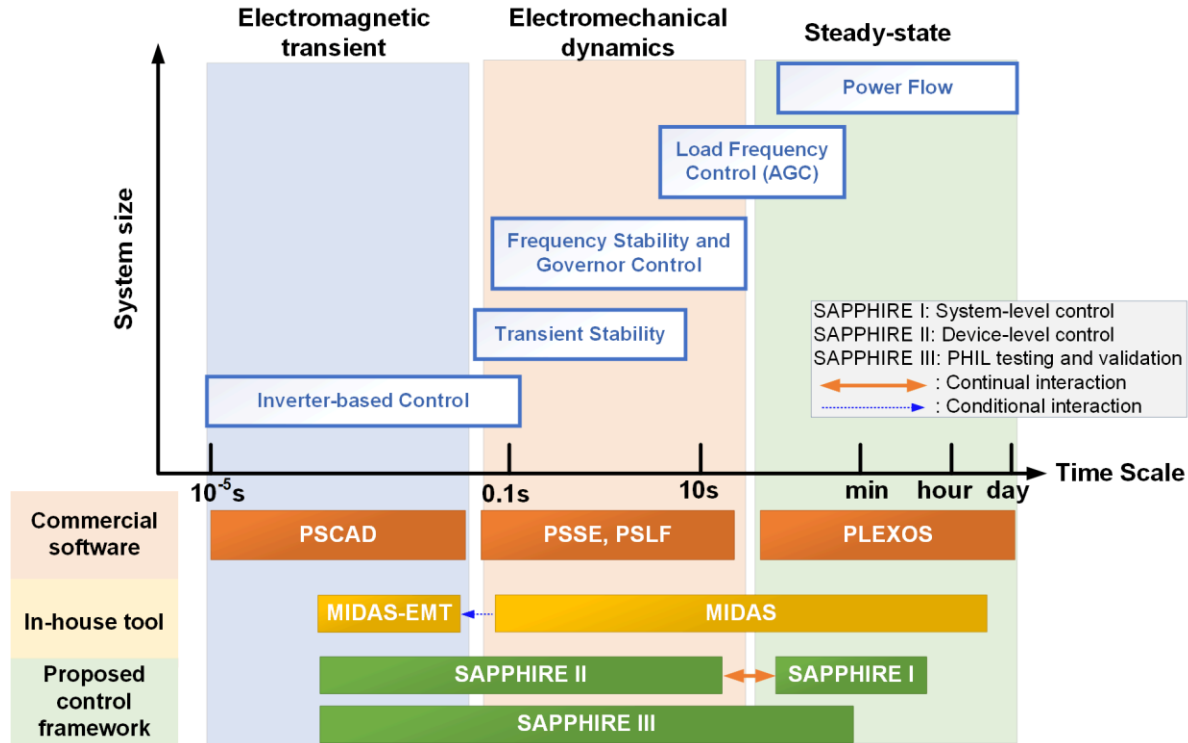
Field Demonstration in Hawaii Grids



To improve the performance of HPPs in supporting the stability of grid operations:

- Unlock the capability of **HPPs to provide essential stability services**
- Bridge the gaps between system-level and plant-/device-level control of HPPs
- **Help the power industry achieve high renewable grids** by demonstrating the use of HPPs as the backbone of extremely high inverter-based resource (IBR) grids

Timescales of SAPPHIRE



Challenges

System level

- Lack of a unified framework and systematic method to consider the fast response capability of HPPs for **grid stabilization**



Plant level

- GFM control of HPP is not mature
- Sub-optimal coordination of PV and BESS



Move forward to practice

- Lack of actual field demonstration of advanced stability-related HPP controls



Solutions

Hierarchical HPP control framework

- Develop **stability-constrained AC-power-flow-based optimal control**
- Develop **measurement-based real-time inertia estimation**



Plant-level stabilization

- Develop **versatile GFM controls**
- Develop **optimal coordinated control of PV and battery**



First-of-its-kind field test in Hawaii

- Develop a “**no-harm to grid**” field test plan to demonstrate 100% renewable operation for hours

