

# T17 – Energy Research and Forecast modeling (ERF)

Tech R&D – Atmosphere to electrons

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LLNL

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```
function main(argc, argv) {
  // ...
  // ...
  // ...
  // ...
  // ...
}
```

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# FY21 Peer Review – ERF Project Overview

## Project Summary:

- The ERF project will facilitate multiscale atmospheric-wind plant simulation within a wide range of wind energy applications by developing a modern atmospheric downscaling code to accurately and efficiently exchange flow information across scales between weather (energy) and the wind plant on next-generation high-performance computing architectures.
- Collaboration between LLNL, ANL, NREL, PNNL and NCAR

## Project Objective(s): 2019-2020

- Rescope a tractable project plan based on results of project workshop, in light of changes to emerging computational architectures
- Develop detailed Applications, Requirements and Design documents to guide code development toward the highest wind energy impacts
- Leverage the AMReX mesh refinement framework to maximize efficient use of multiple computational architectures
- Set up open Github for code development tracking, documentation, and sharing of the code with the community
- Develop appropriate verification and validation tests, and automate

## Overall Project Objectives (life of project):

- A modern code base to seamlessly couple mesoscale energy flows with microscale wind plant simulation to advance wind energy deployment.

Project Start Year: [FY19 (Q4)]  
Expected Completion Year: [FY 24]  
Total expected duration: [5] years

FY19 - FY20 Budget: 1.35M

Key Project Personnel: Jeff Mirocha (LLNL),  
Rao Kotamarthi (ANL), Eliot Quon (NREL), Bill  
Gustafson (PNNL), Branko Kosovic (NCAR)

Key DOE Personnel: Shannon Davis

# ERF Project Impact

- Multiscale environmental interactions influence the entire life cycle of wind power generation, resource characterization → design → operation → integration.
- Broader incorporation of multiscale atmosphere/wind plant simulation into wind energy workflows has potential for far reaching, industrywide impacts.
- ERF enables efficient multiscale atmospheric simulation on multiple emerging HPC architectures (via the AMReX adaptive mesh framework).
  - Emerging high-performance computing (HPC) hardware is shifting to graphics processing units (GPUs).
  - Models in use or under development either are not multiscale, or not GPU – compatible.
- ERF will seamlessly couple with the AMRWind microscale wind plant code (also built upon AMReX) to enable high-fidelity wind plant simulations in diverse atmospheric flow regimes.
- ERF will assimilate procedures from related WETO projects (e.g. Mesoscale-Microscale Coupling, Offshore Wind Resource Science, ...).
- Open-source code with extensive documentation and test cases to facilitate widespread adoption.
- ERF has the potential to serve as a foundational code across a broad swath of WETO projects, as well as multiple research and operational centers.
- Potential for wide applicability across weather-dependent renewable energy sectors (grid integration, energy storage, hybrid plant operation, other services).

# Program Performance – Scope, Schedule, Execution

## Obstacle

- Original Plan (2018): Refactor WRF for more efficient multiscale computation targeting Intel's Many Integrated Core architecture
- (2018-2019) HPC landscape rapidly shifted toward GPUs
- Project kickoff workshop (FY20 Q1): Consensus –WRF's software is not compatible with GPU architectures

## Opportunity

- Design ERF from ground up (but not starting from scratch)
  - Develop a modern, efficient and flexible software (in C++)
  - Target wind energy research needs directly

## Challenge

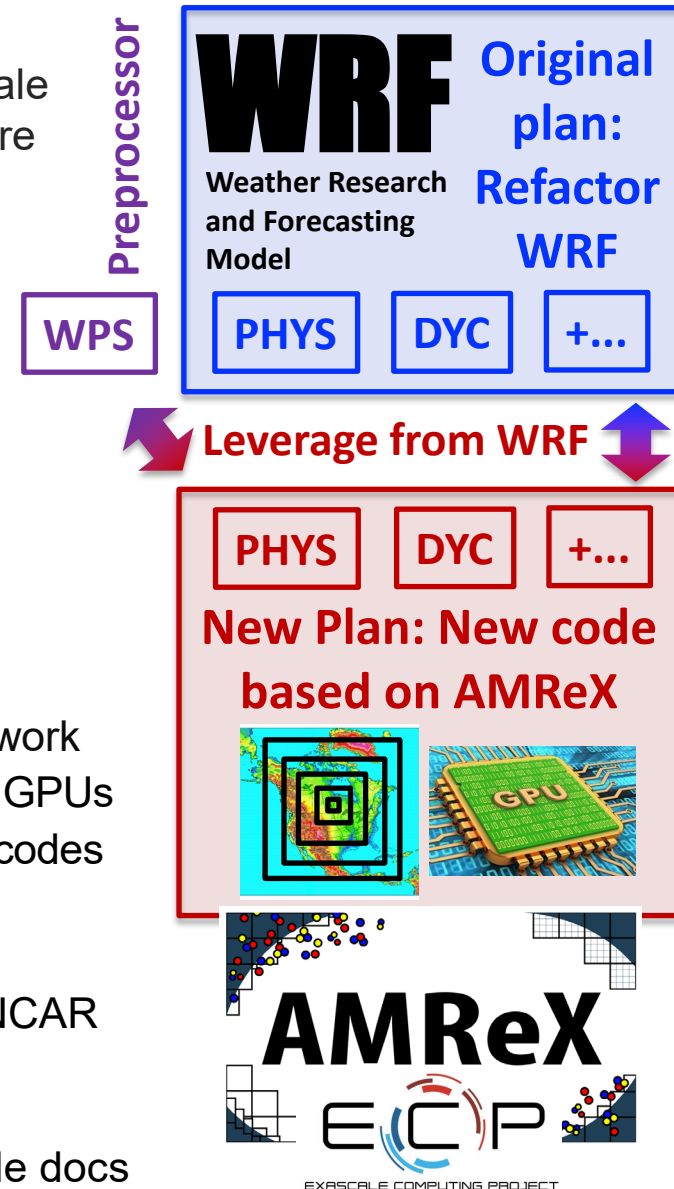
- Re-envision/rescope project within budget constraints (FY20)

## Solution

- Build ERF upon the AMReX sdaptive mesh refinement framework
  - Built-in abstractions for multiple HPC architectures, including GPUs
  - C++ and Fortran → rapid buildout using modules from other codes
  - Exascale Computing Project support ensures maintainability

## Project Execution

- Multi-lab coordination among LLNL, ANL, PNNL, NREL and NCAR
  - Weekly team technical meetings
  - Monthly team meetings with management
  - Code and documentation shared through Github and Google docs



# Project Performance – FY21 Activities: ERF Github, documentation

## ERF development: <https://github.com/erf-model>

- ERF model source code
- Verification and validation test cases
- Extensive documentation (readthedocs)

## Compressible Euler Equations

ERF advances the following set of equations:

$$\begin{aligned} \frac{\partial \rho}{\partial t} &= -\nabla \cdot (\rho \mathbf{u}), \\ \frac{\partial(\rho \mathbf{u})}{\partial t} &= -\nabla \cdot (\rho \mathbf{u} \mathbf{u} + p \mathbf{I}) + \rho \mathbf{g}, \\ \frac{\partial(\rho \theta)}{\partial t} &= -\nabla \cdot (\rho \mathbf{u} \theta), \\ \frac{\partial(\rho A)}{\partial t} &= -\nabla \cdot (\rho \mathbf{u} A), \end{aligned}$$

The relationship between potential temperature and temperature is given by

$$\theta = T \left( \frac{p^0}{p} \right)^{R_d/c_p}$$

and we use the following equation of state:

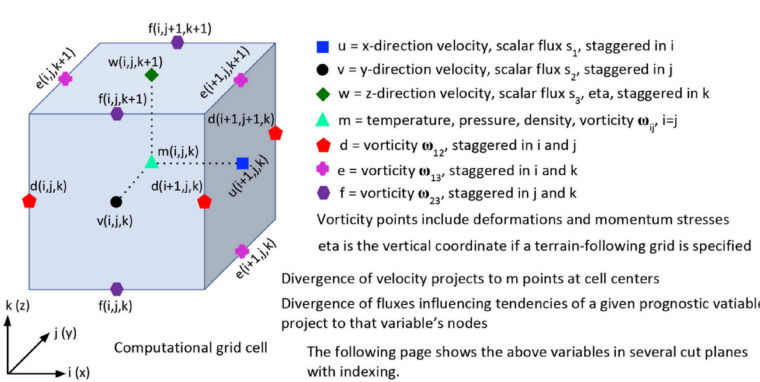
$$p = \rho R_d T;$$

which can also be written in terms of  $\theta$  as

$$p = (\rho R_d \theta / p_0^{R_d/c_p})^{\gamma}$$

Here  $\rho$ ,  $T$ ,  $\theta$ , and  $p$  are the density, temperature, potential temperature and pressure, respectively; these variables are all defined at cell centers.  $A$  is an advected quantity, i.e., a tracer, also defined at cell centers  $\mathbf{u}$  and  $(\rho \mathbf{u})$  are the velocity and momentum, respectively, and are defined on faces. The gravitational vector is denoted by  $\mathbf{g}$ .

Arakawa "C" grid prognostic and diagnostic variable distribution



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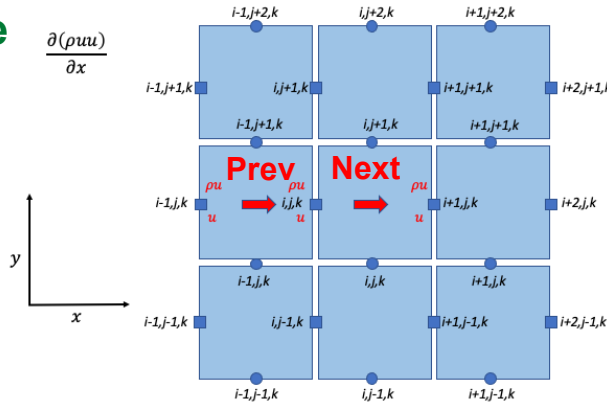
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# Project Performance – FY21 Activities: ERF code development

## Correspondence between equations, notation, and source code

- Governing equation (u-momentum):  $\frac{\partial(\rho u)}{\partial t} = -\nabla \cdot (\rho \mathbf{u} \mathbf{u} + pI) + \rho \mathbf{g}$ ,
- Discretized equation:

$$\begin{aligned}
 (\rho u)_{i,j,k}^{n+1} = & (\rho u)_{i,j,k}^n - \Delta t \left\{ \frac{1}{2\Delta x} \left[ ((\rho u)_{i+1,j,k}^n + (\rho u)_{i,j,k}^n) u_{i+\frac{1}{2},j,k}^n - ((\rho u)_{i,j,k}^n + (\rho u)_{i-1,j,k}^n) u_{i-\frac{1}{2},j,k}^n \right] \right. \\
 & + \frac{1}{2\Delta y} \left[ ((\rho v)_{i,j+1,k}^n + (\rho v)_{i,j,k}^n) u_{i,j+\frac{1}{2},k}^n - ((\rho v)_{i,j,k}^n + (\rho v)_{i,j-1,k}^n) u_{i,j-\frac{1}{2},k}^n \right] \\
 & \left. + \frac{1}{2\Delta z} \left[ ((\rho w)_{i,j,k+1}^n + (\rho w)_{i,j,k}^n) u_{i,j,k+\frac{1}{2}}^n - ((\rho w)_{i,j,k}^n + (\rho w)_{i,j,k-1}^n) u_{i,j,k-\frac{1}{2}}^n \right] \right\} \\
 & - \frac{\Delta t}{\Delta x} [p_{i,j,k}^n - p_{i-1,j,k}^n]
 \end{aligned}$$



### Discretization graphics:

// Add advective terms

```

Real centFluxXXNext, centFluxXXPrev, edgeFluxXYNext, edgeFluxXYPrev, edgeFluxXZNext, edgeFluxXZPrev;
centFluxXXNext = ComputeAdvectedQuantityForMom(i, j, k, rho_u, rho_v, rho_w, u, v, w, nextOrPrev: NextOrPrev::next,
    advectedQuantity: AdvectedQuantity::u, advectingQuantity: AdvectingQuantity::rho_u, solverChoice.spatial_order);
centFluxXXPrev = ComputeAdvectedQuantityForMom(i, j, k, rho_u, rho_v, rho_w, u, v, w, nextOrPrev: NextOrPrev::prev,
    advectedQuantity: AdvectedQuantity::u, advectingQuantity: AdvectingQuantity::rho_u, solverChoice.spatial_order);
edgeFluxXYNext = ComputeAdvectedQuantityForMom(i, j, k, rho_u, rho_v, rho_w, u, v, w, nextOrPrev: NextOrPrev::next,
    advectedQuantity: AdvectedQuantity::u, advectingQuantity: AdvectingQuantity::rho_v, solverChoice.spatial_order);
edgeFluxXYPrev = ComputeAdvectedQuantityForMom(i, j, k, rho_u, rho_v, rho_w, u, v, w, nextOrPrev: NextOrPrev::prev,
    advectedQuantity: AdvectedQuantity::u, advectingQuantity: AdvectingQuantity::rho_v, solverChoice.spatial_order);
edgeFluxXZNext = ComputeAdvectedQuantityForMom(i, j, k, rho_u, rho_v, rho_w, u, v, w, nextOrPrev: NextOrPrev::next,
    advectedQuantity: AdvectedQuantity::u, advectingQuantity: AdvectingQuantity::rho_w, solverChoice.spatial_order);
edgeFluxXZPrev = ComputeAdvectedQuantityForMom(i, j, k, rho_u, rho_v, rho_w, u, v, w, nextOrPrev: NextOrPrev::prev,
    advectedQuantity: AdvectedQuantity::u, advectingQuantity: AdvectingQuantity::rho_w, solverChoice.spatial_order);

rho_u_upd(i, j, k) += (-dt) * (
    (centFluxXXNext - centFluxXXPrev) / dx[0] // Contribution to x-mom eqn from flux in x-dir
    +(edgeFluxXYNext - edgeFluxXYPrev) / dx[1] // Contribution to x-mom eqn from flux in y-dir
    +(edgeFluxXZNext - edgeFluxXZPrev) / dx[2] // Contribution to x-mom eqn from flux in z-dir
    )
    
```

### - Time advance:

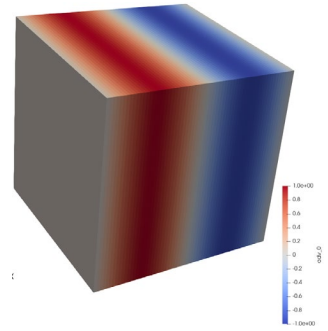
# Project Performance – FY21 Activities: ERF testing

Verification and validation of ERF compressible atmospheric solver code is underway

## 1. Spatial discretization:

Scalar Advection and Diffusion

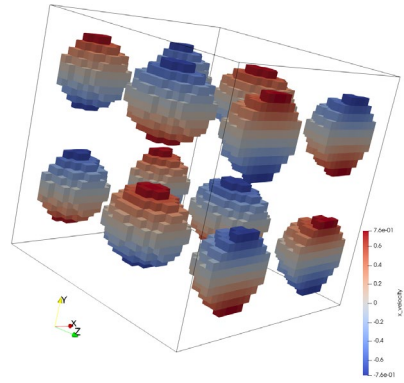
- $\frac{\partial f}{\partial t} + a \frac{\partial f}{\partial x} = D \frac{\partial^2 f}{\partial x^2}$
- $f(x, t) = e^{-Dt} \sin(x - at)$



## 2. Time integration:

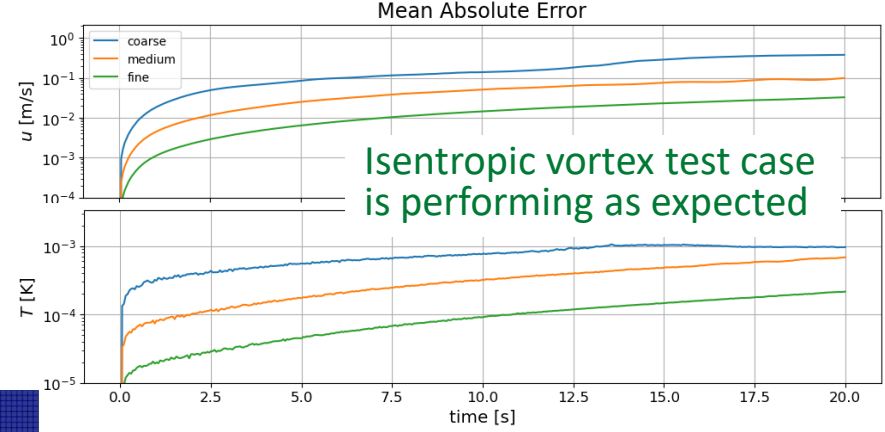
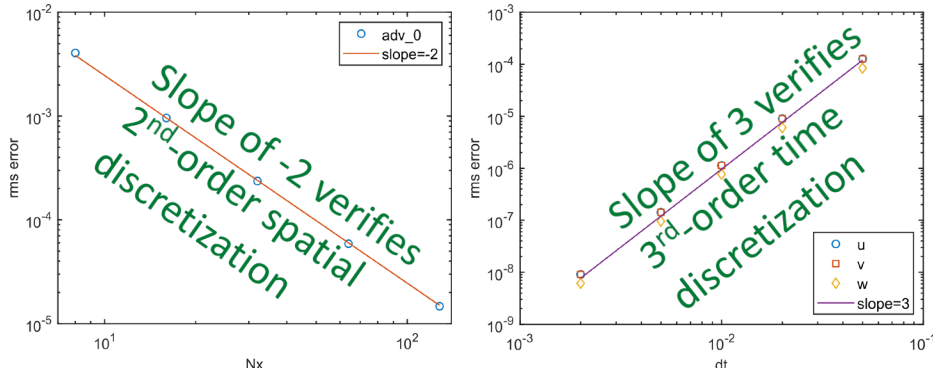
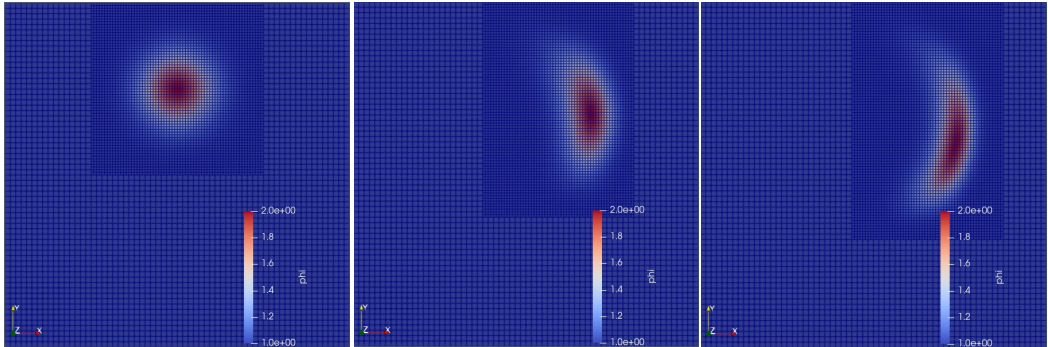
Taylor-Green Vortex

- $u = A \cos ax \sin by \sin cz,$
- $v = B \sin ax \cos by \sin cz,$
- $w = C \sin ax \sin by \cos cz.$



## 3. Adaptive mesh refinement.

Scalar Advection and Diffusion



- ERF code is passing all verification tests
- New tests being developed for each new functionality added
- Test suite is being archived
- Automated testing is being established

# Project Performance – Remaining Activities through FY24:

## FY21:

**Go/No-Go Criterion:** Demonstrate ERF in an atmospheric boundary layer (ABL) simulation, either coupled with AMRWind, or with a concrete near-term plan to complete the coupling, **by 7/31/21**.

- (Q3) Add Log-Law boundary condition for the surface.
- (Q3) Add pressure gradient/geostrophic forcing for ABL simulation.
- (Q3) Finish addition of Smagorisky subgrid model for large-eddy simulation.
- (Q3) Couple ERF outflow with AMRWind and test initial coupling of the two codes.
- (Q4) Test ERF ABL simulations against expected behaviour, simulation results from WRF.
- (Q4) Assess computational performance improvements using ERF versus WRF.

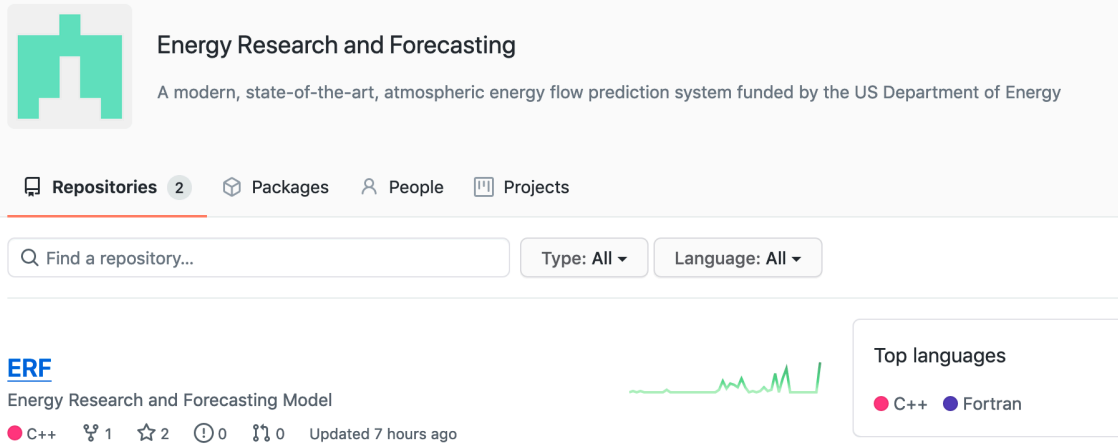
## FY22-24:

- (FY22) Incorporate mesoscale physics modules to capture mesoscale energy features.
- (FY22) Incorporate interface to WRF preprocessor to ingest large-scale forcing data.
- (FY23) Add terrain-following coordinates and/or immersed boundaries to represent surfaces.
- (FY23) Incorporate appropriate wave-atmosphere interaction models for offshore settings.
- (FY23-24) Assess performance of ERF versus WRF in multiscale, whole model setups.
- (FY23-24) Assess performance of coupled ERF AMRWind simulations.
- (FY24) A validated source code with extensive documentation, user/developer resources, and relevant test cases to demonstrate capability and facilitate adoption, community development.



# Stakeholder Engagement & Information Sharing

## ERF code & documentation are live and accessible



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A modern, state-of-the-art, atmospheric energy flow prediction system funded by the US Department of Energy

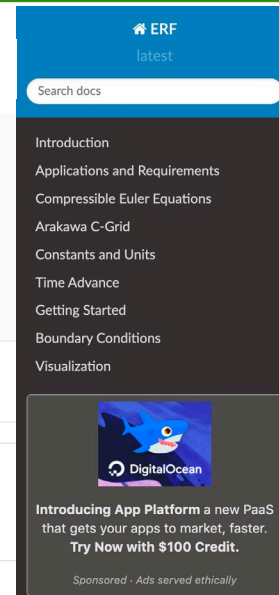
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- Project not widely advertised during FY20 due to rescope; advertizing has resumed during FY21.
- One large company has expressed interest in becoming an early adopter.
- Team plans to advertise code at upcoming workshops and conferences.
- ERF team will conduct workshops and webinars with industry and academic partners.
- ERF will assemble an advisory panel to keep the team aware of emerging industry and research priorities, as well as leveragable activities and capabilities under development elsewhere.
- Coupling with AMRWind will encourage adoption by users of ExaWind codes.
- Demonstrations of computational and physical code performance will be published in appropriate widely read journals and disseminated at popular scientific and industry conferences.

# Key Takeaways and Closing Remarks

## Project Impact:

- Enabling multiscale atmosphere/wind plant simulations in a wide range of wind energy workflows is essential to ensure the reliability of an electrical grid dependent upon large inputs of wind energy.
- Extensibility of simulation code to new operating environments (complex terrain, offshore) is critical for timely responses to new challenges.

## Project Performance:

- Team demonstrated resilience and adaptability, rescoping project, progressing on code development.
- Rigorous testing of code components
- Extensive, comprehensible documentation.

## Stakeholder Engagement:

- Public Github with documentation, test problems.
- Beginning advertising and interacting with stakeholders following successful construction of the code base.