



**Project ID: elt258**



# Grid-Enhanced, Mobility-Integrated Network Infrastructures for Extreme Fast Charging (GEMINI-XFC)

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DOE Vehicle Technologies Office (VTO) Annual Merit Review

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# Overview

## TIMELINE

- Project start date: December 2019
- Project end date: September 2022
- Percent complete: 50%

## BUDGET

- Total project funding: \$3.0M
  - DOE share: \$3.0M
  - Contractor share: \$0
- Funding for FY 2020: \$1M
- Funding for FY 2021: \$1M

## PARTNERS



- National Renewable Energy Laboratory (NREL)



- Lawrence Berkeley National Laboratory (LBNL)

## BARRIERS ADDRESSED

- Develop technologies that minimize the impacts of electric vehicle (EV) charging on the nation's electric grid and support vehicle electrification
- Develop controls and integration to enable extreme fast charging (XFC) to support EVs at scale

# Relevance

Increasing **vehicle electrification will require extensive use of extreme fast charging (XFC)**, especially for larger vehicles. Uncoordinated XFC can create grid challenges, particularly at the distribution level. Two strategies can support widespread XFC:

- × Extensive grid upgrades (i.e., upgrade all systems to enable worst-case, fully coincident loads) or
- ✓ Integrated planning to co-design a smart system based on advanced controls that leverage load flexibility and distributed energy resources.

With the right design and control, XFC can simultaneously **support both mobility and grid operations.**

Fully realizing the potential of XFC will require **unprecedented coordination among the charging infrastructure, grid, and vehicles.**

## Objectives:

- Identify how XFC will support transportation with evolving mobility patterns and very high EV adoption levels
- Assess the impact of widespread uncoordinated XFC of passenger vehicles on distribution networks
- Design effective control strategies to integrated XFC in distribution systems

# Milestones

	Milestone Name/Description	End Date	Type
✓	Document progress towards definition of future mobility/power scenarios requirements and format	12/30/2019	Quarterly Progress
✓	Document progress on forecasts XFC electricity demand	6/30/2020	Quarterly Progress
✓	Document progress on coordination scheme and analysis	9/30/2020	Annual Milestone
✓ 1.	Full scenario definition	12/30/2020	Quarterly Progress
✓ 2.	Proof-of-concept integrated simulation with GEMINI framework	3/30/2021	Go / No-Go
3.	Document progress on finalizing coordination scheme and analysis	6/30/2021	Quarterly Progress
4.	Assess impact of widespread uncoordinated XFC on distribution networks (first key question)	9/30/2021	Go / No-Go Annual Milestone
	Assess strategies to mitigate the negative impact on distribution networks from widespread XFC of light-duty and commercial vehicles (second key question)	3/30/2022	Quarterly Progress
	Assess communication requirements to enable coordinated XFC of light-duty and commercial vehicles (third key question)	6/30/2022	Quarterly Progress
	Project completion. Model and result/insights documentation	9/30/2022	Annual Milestone

## Year 2 Activities

1. TEMPO scenario development for EV and technology adoption
2. Develop a grid and transportation systems co-simulation using the HELICS framework
3. Refinement of control and coordination strategies
4. Evaluation of uncoordinated XFC impacts on the grid

XFC – Extreme Fast Charging

HPC – High Performance Computing

TEMPO – Transportation Energy & Mobility Pathway Options

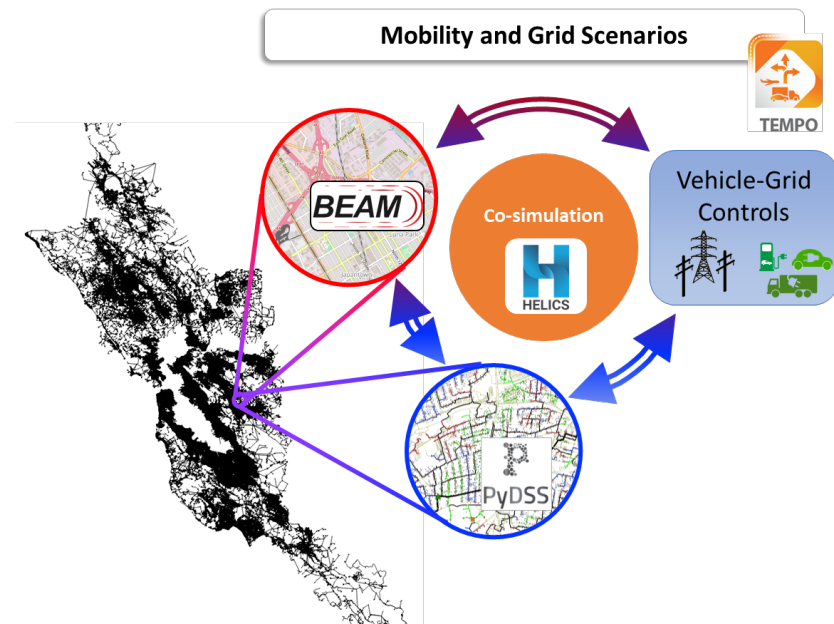
HELICS – Hierarchical Engine for Large-scale Infrastructure Co-Simulation

# Approach

GEMINI-XFC will use **first-of-a-kind integrated high-fidelity grid and transport modeling to identify effective pathways for widespread electrification**, to design and evaluate integrated vehicle-grid control schemes, and to optimize electric vehicle integration at a **full regional scale with individual customer resolution**.

Control variables will include:

- **Charging station design** and planning (where and what kind of charging stations)
- **EV route scheduling** considering grid "status"
- **Dispatch of behind-the-meter energy storage** and legacy voltage control actuators (on-load tap changes, voltage regulators, capacitors).



Focus on **XFC** (single plug at 250 kW or multiple plugs for a total of 1+ MW)

# Approach (Scope)

GEMINI-XFC will focus on **on-road passenger mobility in the entire San Francisco Bay Area** looking at transportation options and grid systems in a **long-term future (~2040)** characterized by significant changes compared to today's systems.

Leverage existing capabilities through co-simulation and workflow automation:

- **Customer-resolved** mobility meso-modeling, charging requirements, and power flow
- Mapping **EV charging and synthetic grid data** for rapid and open analysis.

## Geographic extent:

Large metro regions (e.g., San Francisco, Denver, etc)



## Disruptive technologies:

Consideration of impact of wide-spread electrification, connectivity, automation, new business models



## Electrical grid:

Full electric grid from customer connections, through feeders, and up to bulk system



## Temporal resolution:

Minutes for driving dynamics, traffic, charging profiles, grid services, tariffs, solar/wind/load dynamics, grid dispatch and control equipment



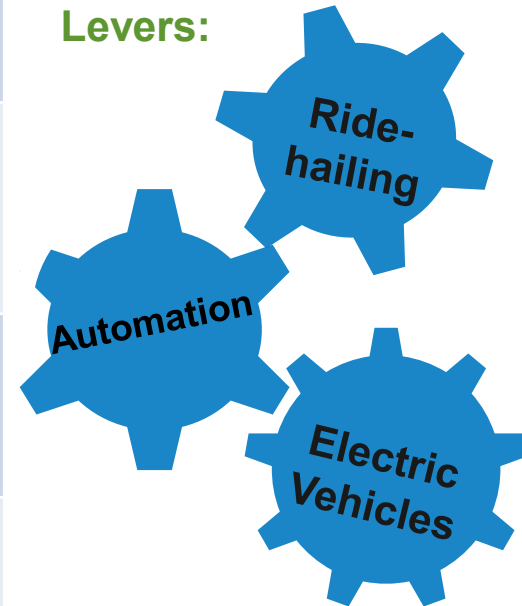
# Technical Accomplishments and Progress: Transportation Scenarios Approach



Scenarios designed to capture **range of possible futures** and impact on XFC operation

Scenario	Questions to Answer	Description
<b>Base</b>	What is the baseline state for comparison?	Business as usual (aligned with EIA AEO Reference), with proposed CA policy
<b>Mid-Term High EV Adoption</b>	Impacts of XFC under high electrification? Can smart controls mitigate these impacts?	High EV adoption (driven by advanced technology and CA policy), business-as-usual mobility options, and consumer behavior (limited ride-hailing, sharing, automation)
<b>Mid-Term Advanced Mobility</b>	What are the impacts of disruptive mobility changes? Are different controls needed?	High EV adoption with disruptive mobility changes: widespread ride-hailing, reduced vehicle ownership, automation
<b>Long-Term Advanced Mobility</b>	What are the incremental impacts of XFC and how do capabilities of control change under extreme levels of electrification?	Almost full EV adoption with disruptive mobility changes

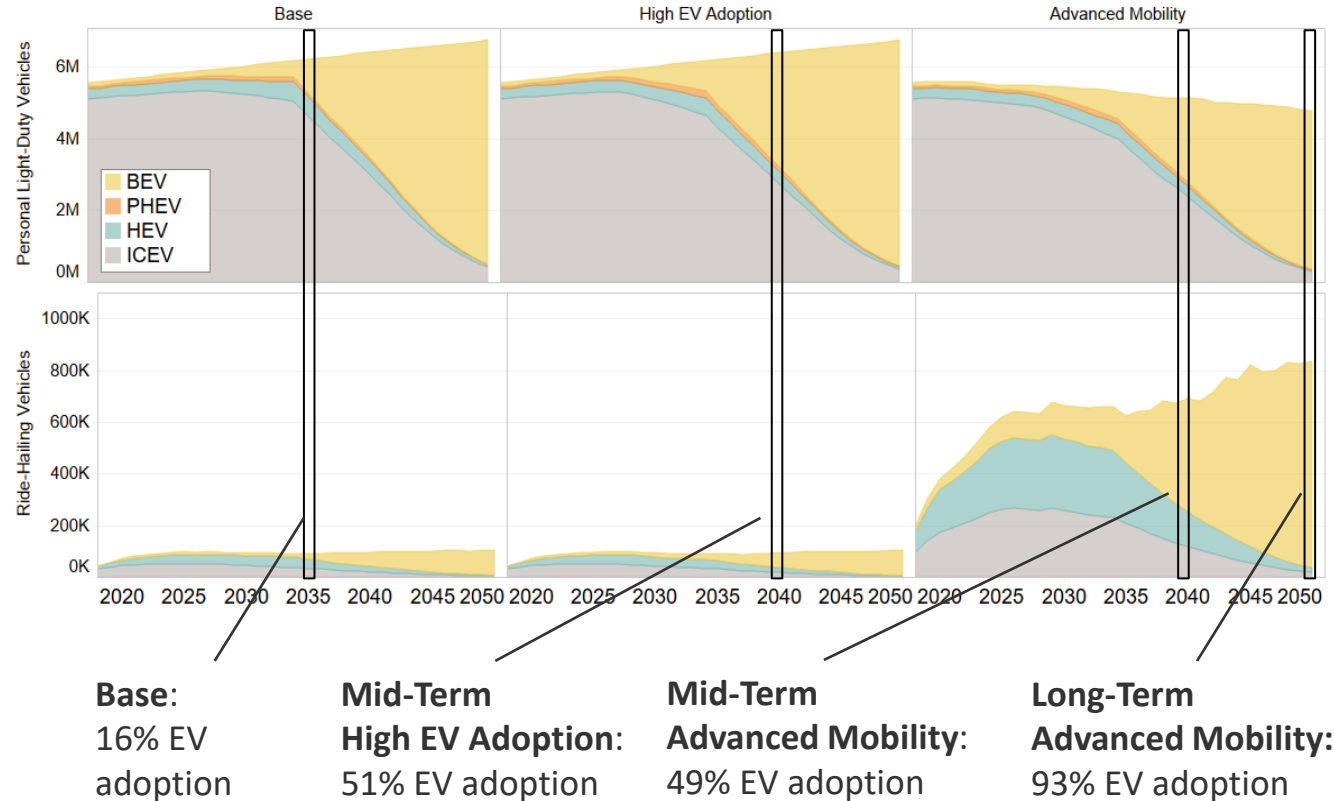
**Key Scenario Levers:**



# Technical Accomplishments and Progress: Transportation Scenario Inputs

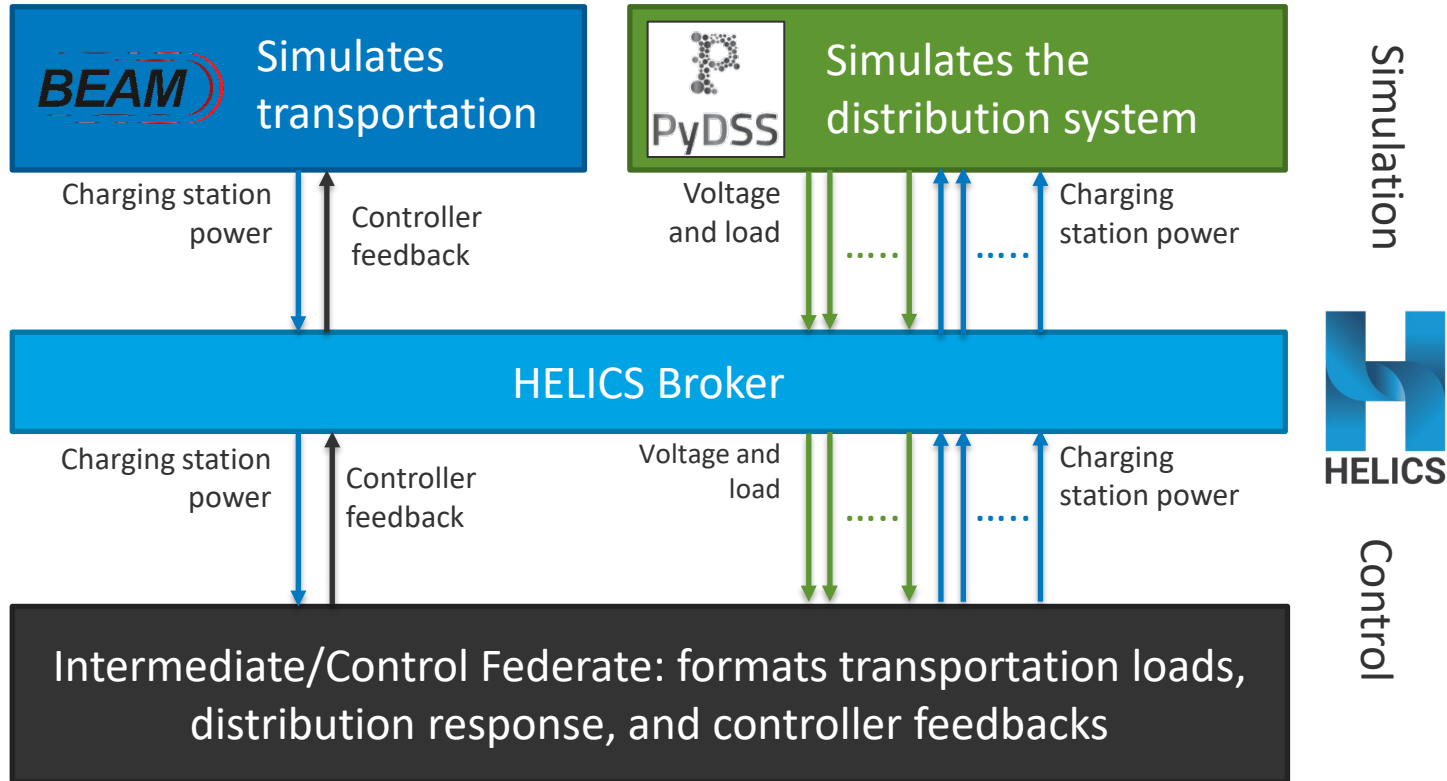


- Vehicle stock for personal and ride-hailing light-duty vehicles estimated using TEMPO model (results shown for San Francisco Bay Area)
- TEMPO stock results will be used as input for the vehicle stock in BEAM



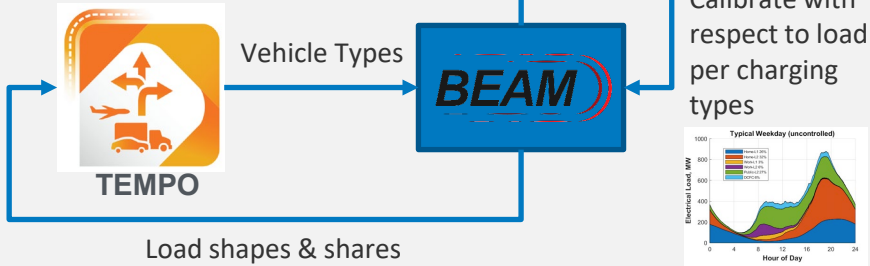


# Technical Accomplishments and Progress: Co-Simulation Setup



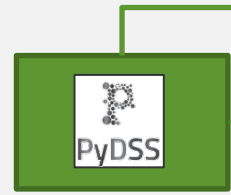
# Technical Accomplishments and Progress: Uncontrolled Co-Simulation Pipeline

## Calibration of Mobility



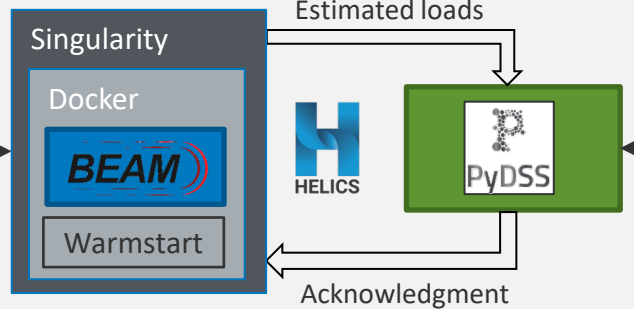
Add charging stations and respective infrastructure and pubs/subs

Initialize converged circuit states and export files

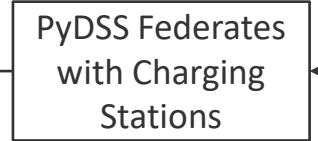


## Distribution System Configuration

## Co-simulation on NREL's Eagle HPC

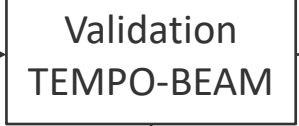


Distribute federates across many compute nodes to assure sufficient memory and storage

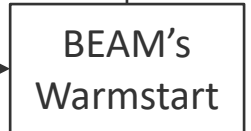


HPC – High Performance Computing

Run BEAM for multiple iterations to pseudo-equilibrium, then validate the overall loads and charging behavior.



Snapshot the population plans, skims and link stats



Use the Snapshot to run BEAM inside a portable docker on a single large memory node for only one iteration along HELICS CoSim

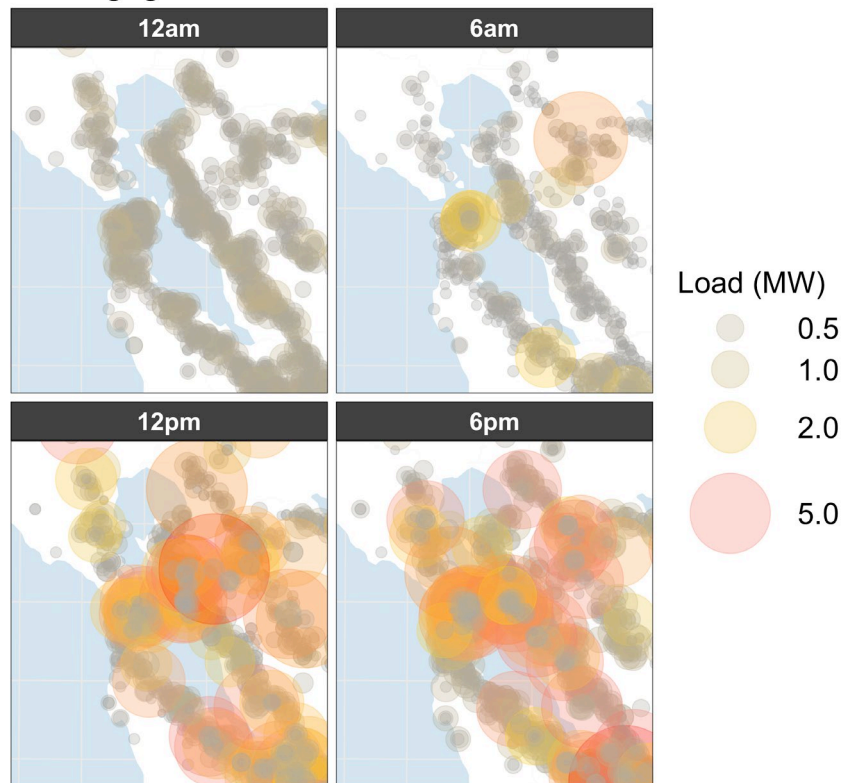
# Technical Accomplishments and Progress: XFC Requirements



The results show for the Base Scenario, with uncontrolled charging, illustrates the **spatiotemporal representation of XFC events** (>1 MW, or single plug >250 kW) possible using BEAM.

- Charging for electrification of **1M vehicles** (16 % of the fleet)
- Limited transition from privately owned vehicles to ride-hailing (6% of EVs are for commercial ride-hailing use)
- 29% of the total charging power demand is served by XFC (7% of charging energy goes to commercial ride-hailing use).

EV Charging Loads



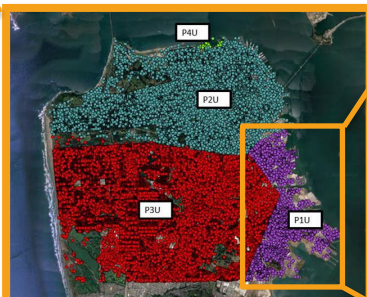
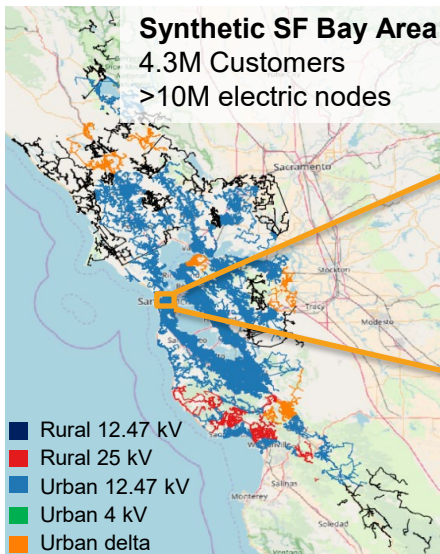
# Technical Accomplishments and Progress: Grid Scenarios

## Identified full customer-resolution distribution data (realistic but not real)

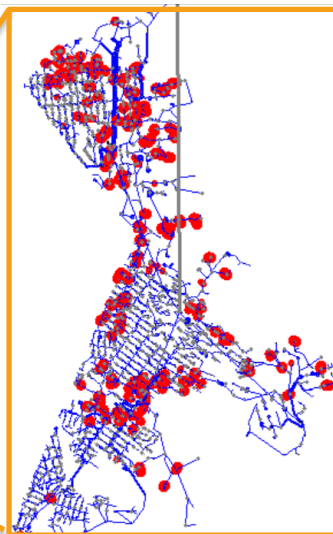
- Smart-DS ([ARPA-E] grid data): geographically accurate, but openly sharable distribution system
- Scenario data: load profiles, distributed PV profiles, PV and distributed storage installations
- Entire Bay Area at customer level
- Verification (statistics for line length, substation locations load profiles, etc.) included collaboration with 5 utilities

Base DER Scenario: 14%  
gen from distributed solar  
(Aligned with Baseline  
Standard Scenario)

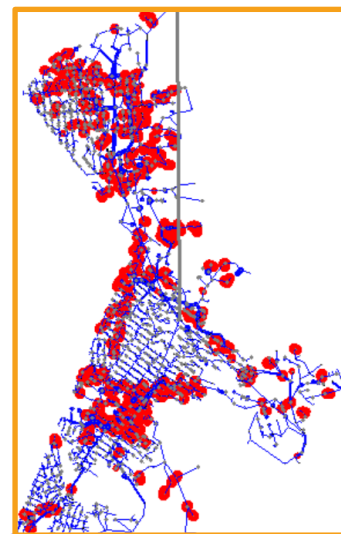
High DER Scenario: 58%  
gen from distributed solar  
and storage  
(Aligned with NRPS80)



*B. Palmintier and B.-M. Hodge, "Smart-DS: Synthetic Models for Advanced, Realistic Testing: Distribution systems and Scenarios," presented at the ARPA-E Energy Innovation Summit, National Harbor, MD, March 14, 2018.*



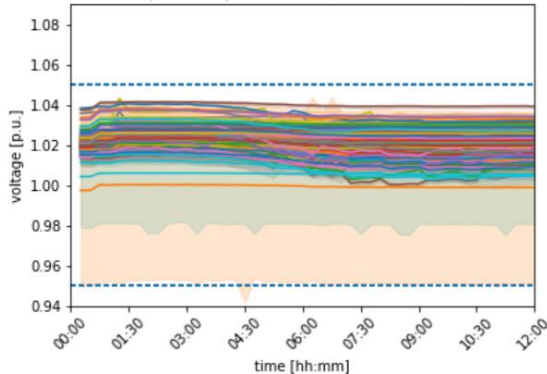
● solar installation



# Technical Accomplishments and Progress: Grid Modeling

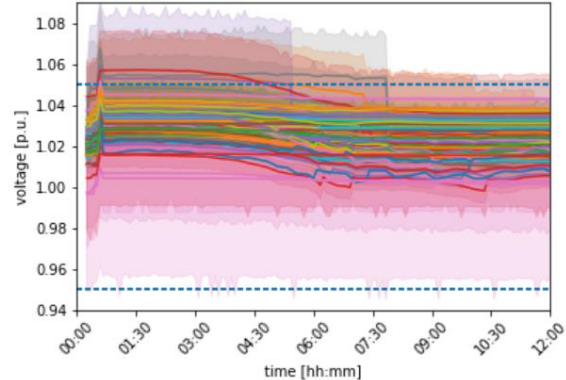
- Full San Francisco Bay Area model with no solar or storage modeled and running
  - Voltage excursions in some regions with charging
- Co-simulation runs of base case with 370k EVs and charging stations in preliminary stages
  - 40 distribution regions, 667 feeder models each spanning medium voltage to customer level (69kV down)
  - These initial results show expected feedback of the co-simulation though detailed analysis on EV impacts are pending further EVSE infrastructure placement

Distribution feeder nodal voltage mean and 95% range for all nodes, plotted by substation interconnection



Distribution System Voltage without charging

Distribution feeder nodal voltage mean and 95% range for all nodes, plotted by substation interconnection

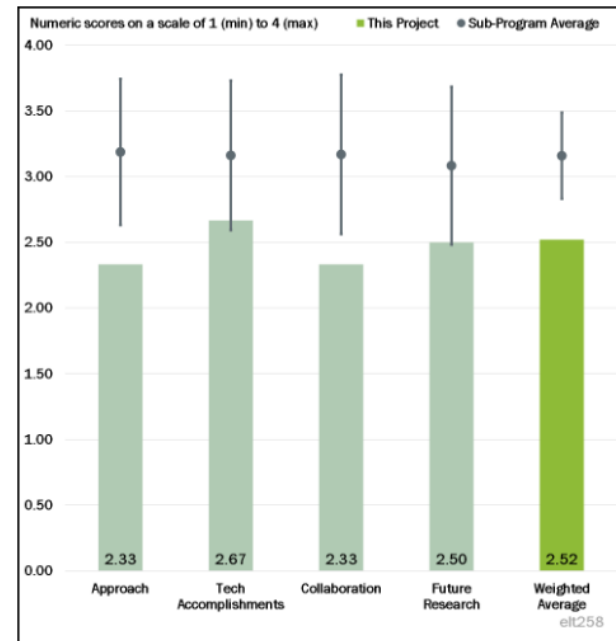


Distribution System Voltage with charging

# Responses to Previous Year Reviewers' Comments

## Concerns raised at the last AMR:

- ... [this is] a control technique that hinders EV drivers with a high level of inconvenience, how would driver behavior be accounted for?
  - Response: The control provides price incentives to personal vehicles that choose the charging station with cheapest solution. Additional flexibility is provided through the ride-hail fleet.
- ... engagement with utilities that serve the area being simulated [are not included]. Will grid scenarios be reviewed by utilities?
  - Response: The team is leveraging the Smart-DS project for the synthetic grid which engaged several utilities and industry representatives to define a representative network. The project has engaged the US Drive Grid Integration Tech Team with several utility participants
- ... What is so important about developing this model—will not having it make any significant difference to society, energy security, fossil fuel consumption, climate change?
  - Response: This project aims to show how targeted infrastructure deployment and control coordination across the grid and transportation system could leverage flexibility of EVs to support a more renewable grid and reduce the cost of charging. Which supports DOE's goal to reduce barriers to EV adoption.



# Collaboration and Coordination

The project is being developed in close collaboration between two National Laboratories leveraging key capabilities and models at each lab:

- NREL: Project coordination, transportation and grid scenarios, co-simulation and HELICS, grid modeling (Smart-DS and OpenDSS), TEMPO, control scheme
- LBNL: Transportation and grid scenarios, mobility agent-based modeling (BEAM), control scheme.

Coordination with other DOE-funded projects:

- VTO SMART (Systems and Modeling for Accelerated Research in Transportation) Mobility and VTO Analysis: mobility options and vehicle adoption/characteristics
- VTO Smart Charge Management Projects (RECHARGE, DirectXFC): consistent tech attributes and energy storage characteristics
- SA: Transportation and Grid Annual Technology Baseline and Standard Scenarios
- GMLC HELICS+: jointly developing shared transportation model interface standard
- ARPA-E Smart-DS: Building on existing rich data set.

# Remaining Challenges and Barriers

GEMINI-XFC is progressing as planned and there are **no major barriers**

Research challenges currently being tackled:

- XFC Infrastructure requirements: BEAM modeling has demonstrated ability to project XFC load for a selected scenario, but refinements are needed to cover all the dimensions considered in GEMINI-XFC.
- Assess the impact on distribution networks: Now that co-simulation setup is complete, a distribution upgrade analysis is needed for higher adoption scenarios that adequately identify potential modifications.
- Co-simulation and design control strategies: envisioned but needs to be fully conceived and implemented in HELICS.



# Proposed Future Research

Milestone Name/Description	End Date	Type
Assess impact of widespread uncoordinated XFC on distribution networks (first key question)	9/30/2021	Go / No-Go Annual Milestone
Assess strategies to mitigate the negative impact on distribution networks from widespread XFC of light-duty and commercial vehicles (second key question)	3/30/2022	Quarterly Progress
Assess communication requirements to enable coordinated XFC of light-duty and commercial vehicles (third key question)	6/30/2022	Quarterly Progress
Project completion. Model and result/insights documentation	9/30/2022	Annual Milestone

## Research for the remainder of FY 2021:

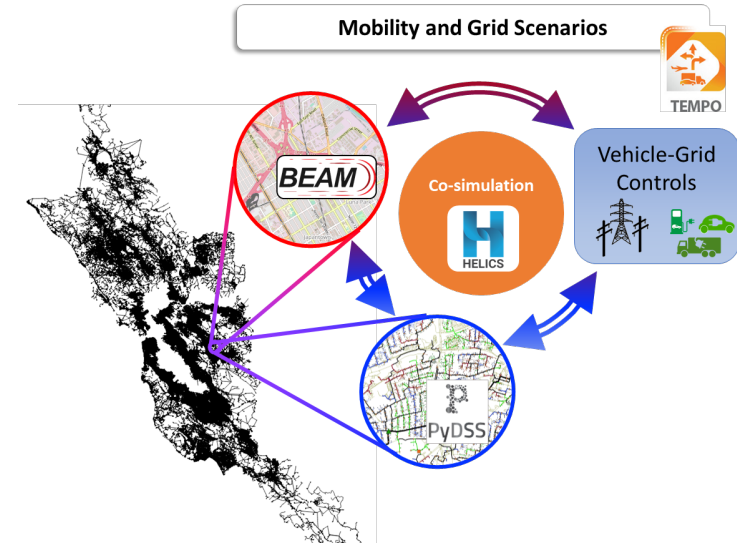
- Continue refinement on charging infrastructure disaggregation and resulting spatially resolved L1/L2 and XFC electricity demand for baseline scenario
- Expand current prototype PyDSS/BEAM HELICS co-simulation to full San Francisco Bay Area
- Define an approach to identify reasonable infrastructure upgrades for future scenarios that meets the intent of the GEMINI-XFC control approach but considers balanced improvements
- Conceive, design, and start development of the coordination and control scheme through HELICS co-simulation that minimizes grid impacts of XFC for personal and commercial light-duty vehicles.

Any proposed future work is subject to change based on funding levels.

# Summary

As electrification of transportation progresses, new **synergies and interconnections with the electricity systems** will arise. Fully realizing the potential of these integrated systems while meeting mobility needs requires **unprecedented coordination among the charging infrastructure, grid, and vehicles.**

GEMINI-XFC combines **high-fidelity grid and transport modeling at an unprecedented level of resolution** and codesigns a smart system based on advanced controls that leverage load flexibility and distributed energy resources to optimize the integration of extreme fast charging (XFC) across a full regional scale.



# Thank you!

*The GEMINI Team at NREL and LBNL*

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**[www.nrel.gov](http://www.nrel.gov)**

NREL/PR-5400-79963



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# Technical Back-Up Slides

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# Transportation Energy & Mobility Pathway Options (TEMPO) Model

TEMPO was conceived at NREL by a Laboratory Directed Research and Development (LDRD) project (FY 2019–2020) aimed at developing the **core foundation of an integrated transportation demand model** to better understand future transportation systems.

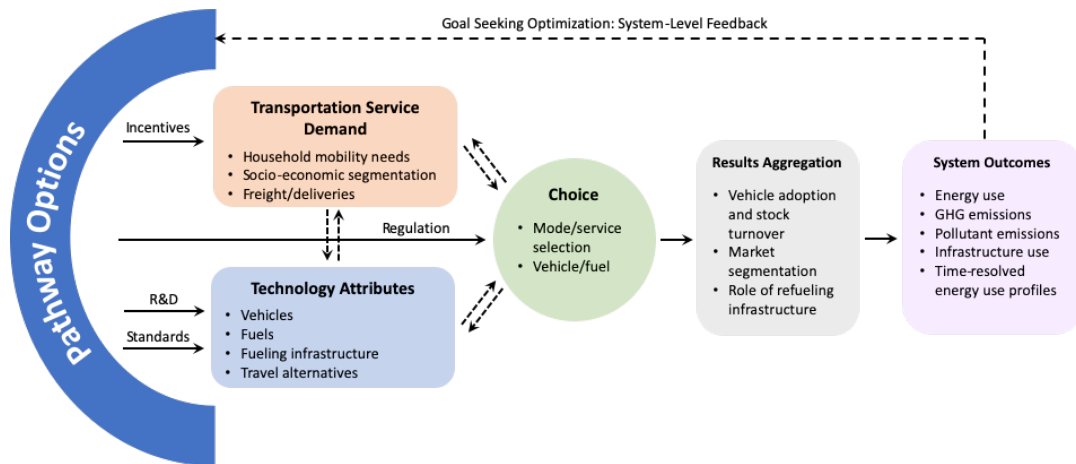
## CHALLENGE

- What is the potential for **radical transformations** of transportation supply and demand?
- How might **interconnections** with other sectors and infrastructure evolve?
- Which fuels/technologies will be adopted and in which **market segments**?

## PLAN

- Model **household-level** mobility demand and travel choice
- Perform endogenous **out-of-sample forecasting** to explore radical transformation
- Model **time-resolved energy use** for grid model linkages.

<https://www.nrel.gov/transportation/tempo-model.html>



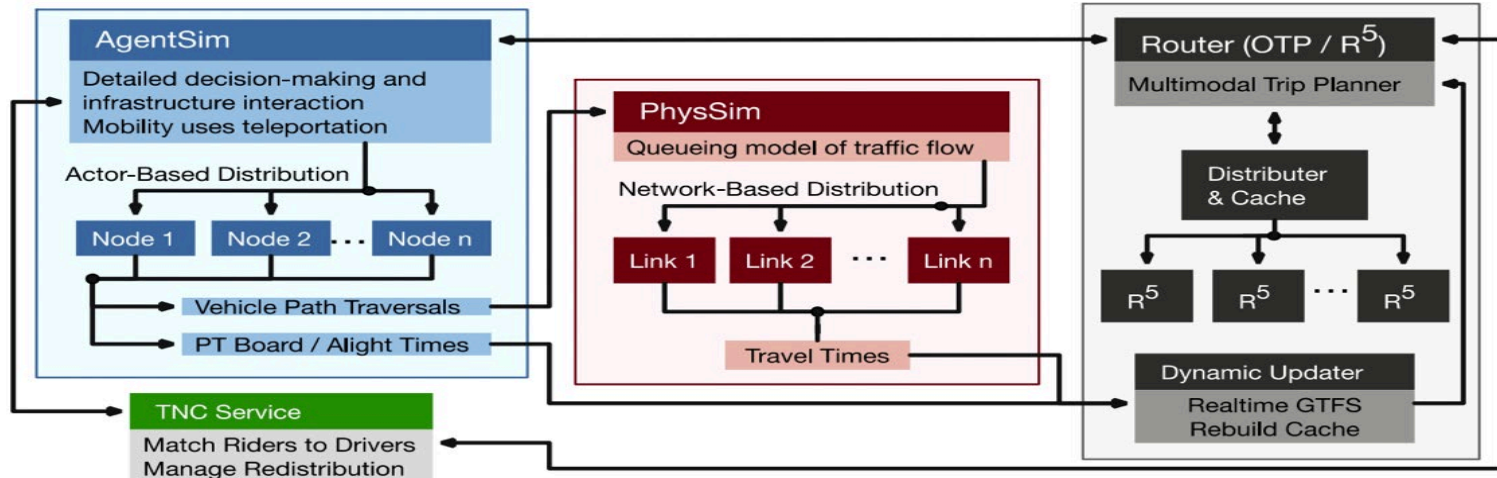
## Significance & Impact

- Fills a research gap on sector-wide transportation modeling for long-term multi-sectoral scenarios
- Enables multi-sectoral coupling while providing a proper representation of mobility requirements and constraints

# BEHAVIOR, ENERGY, AUTONOMY, AND MOBILITY (BEAM) MODEL

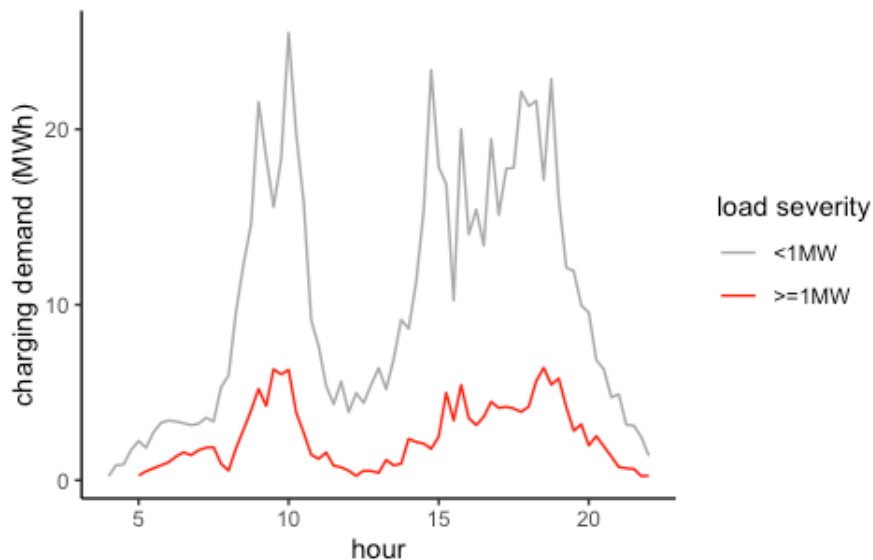
The Behavior, Energy, Autonomy, and Mobility (BEAM) Modeling Framework is an open-source tool that was developed by LBNL to model resource markets in the transportation sector (see <http://beam.lbl.gov/>). BEAM is an integrated, agent-based travel demand simulation framework. BEAM models the road network, parking and charging infrastructure, transit system, on-demand mobility from ride-hail and vehicle sharing, and a synthetic population with plans and preferences.

## BEAM ARCHITECTURE [BEAM VIDEO](#)

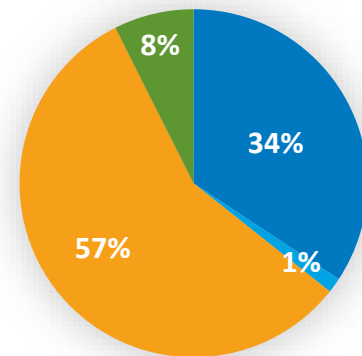


# Technical Accomplishments and Progress: XFC Requirements

- In this San Francisco Bay Area scenario, we assume that technology has disrupted mobility: high retirement of privately owned vehicles and significant penetration of EVs. 46.4% of the total number of vehicles are EVs, and 34% are fully automated driverless vehicle ride-hailing.



Electrical Vehicles



■ BEV-RH-CAV ■ BEV-RH ■ BEV-CAR ■ PHEV-CAR

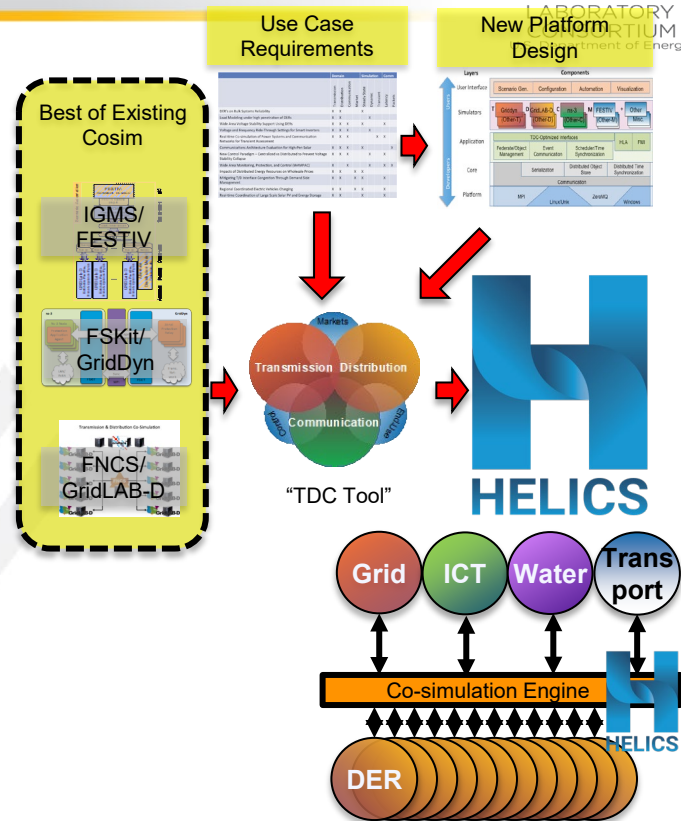
- 19% of the total charging demand is served by automated vehicles (CAV) ride-hail (RH) depots with a load above 1 MW, which is considered as XFC.

**High-performance co-simulation to combine best-in-class tools for breakthrough integrated energy analysis**

## Capabilities:

- **Scalable:** 2–100,000+ Federates
- **Cross-platform:** HPC (Linux), Cloud, Workstations, Laptops (Windows/OSX)
- **Modular:** mix-and-match tools
- **Minimally invasive:** easy to use lab/commercial/open tools
- **APIs:** C++, C, Python, MATLAB, Java, Julia, HMI, FMI, etc.
- **Open Source:** BSD 3-clause
- **Many Simulation Types:**
  - Discrete Event
  - QSTS
  - Dynamics
- **Co-iteration enabled:** “tight coupling”

v2.4.2 available now at  
<https://www.github.com/GMLC-TDC/HELICS>





# Smart-DS: Synthetic Models for Advanced, Realistic Testing: Distribution Systems and Scenarios

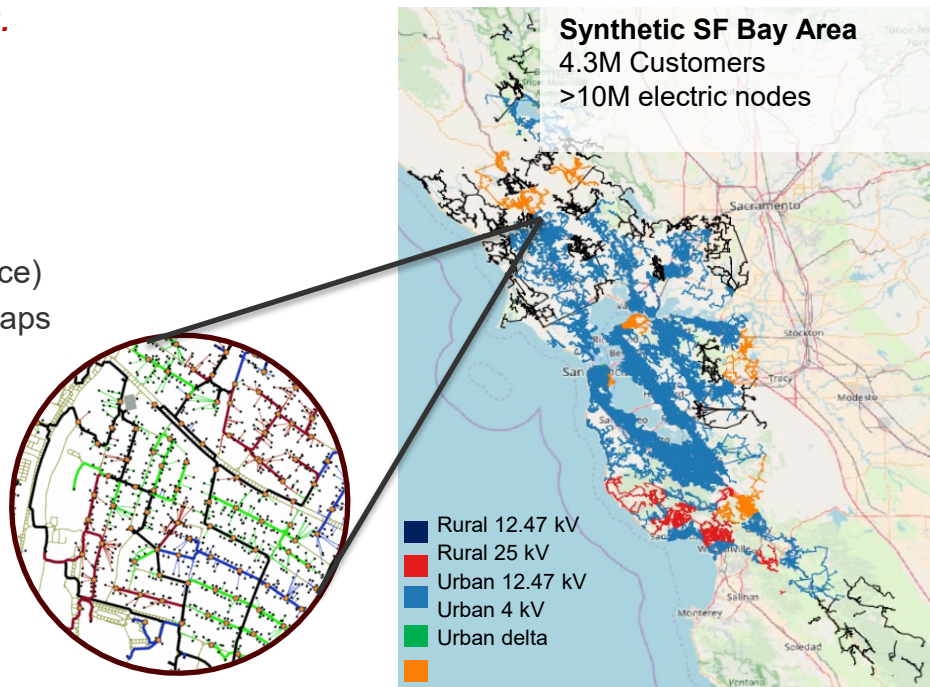
**Full-scale “Realistic but not real” power grid test systems for testing new algorithms, analysis techniques, etc.**

## Features

- Actual building geo-location/types from Parcel Data
- Fully synthetic grid built using [RNM-US](#)
- Full electrical details: from every house to transmission
  - Lines: HV, MV, LV (Transmission, Distribution, Service)
  - Substations, Transformers, Switches, Regulators, Caps
- Detailed Mix-and-Match Scenarios: PV, Storage, etc.
  - Bottom-up building-level loads (P&Q) from ResStock/ComStock
  - 1 year at 15-min timeseries load, solar, etc.
- Extensive validation: Statistical, Powerflow, Expert

## Key features for GEMINI-XFC

- Based around actual street map (Open Street Map)
- Synthetic data allows easy sharing/publication of results
- Diversity of common U.S. distribution network designs



# TEMPO Primary Scenario Assumptions

- **Base**
  - Vehicle cost and performance consistent with AEO 2018
  - Non-ZEV ban starting in 2035 (consistent with [CA phase out](#))
  - Technology penetration consistent with 2035 fleet (less turnover of vehicle stock)
- **High EV Adoption**
  - Vehicle cost and performance improvements for PEVs based on [NREL Annual Technology Baseline \(ATB\) 2020](#) Advanced scenarios
  - Non-ZEV ban starting in 2035
  - Technology penetration consistent with 2040 fleet (higher turnover of vehicle stock)
- **Advanced Mobility**
  - High EV Adoption
  - + Advanced ride-hailing (50% reduction in cost and time)
  - + Option for households to drop personally owned vehicles
  - + Automation assumed for ride-hailing fleets (reduced cost)
- **Max EV Adoption**
  - Advanced Mobility
  - + Technology penetration consistent with 2050 fleet (almost full turnover of vehicles after non-ZEV ban)

Scenarios intended to capture range of possible futures and impact on XFC operation