

High Power and Dynamic Wireless Charging of Electric Vehicles (EVs)

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Oak Ridge National Laboratory (ORNL)

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Overview

Timeline

- Start Date: Oct 2019
- End Date: March 2022
- 78% Complete

Budget

DOE Total Share: \$11,275K

FY \$K	ORNL	INL	NREL
FY19	\$3,075	\$675	\$250
FY20	\$2,900	\$875	\$250
FY21	\$2,900	\$825	\$250
Total	\$8,875	\$2,325	\$750

Barriers

- **Power Density:** Developing a compact vehicle coil and power electronics assembly which can receive 200 kW power dynamically
- **Efficiency:** Achieving 90 % efficiency in a vehicle integrated dynamic wireless charging system
- **Controllability:** Identifying and implementing a control and communication system which can perform wide range power regulation without compromising efficiency or power density

Partners

National Laboratories



Veda Galigekere, Lincoln Xue, Rong Zeng, Gui-Jia Su, Omer Onar, Emre Gurpinar, Shajjad Chowdhury, Randy Wiles, Jon Wilkins, Larry Seiber, Cliff White, and Burak Ozpineci



Richard Carlson and Bo Zhang



Ahmed Mohamed, Andrew Meintz, and Cory Sigler

External Partners



Hyundai Kia American Technical Center



American Center for Mobility



Virginia Tech Transportation Institute

Project Objectives and Relevance

Relevance: Dynamic EV charging can significantly alleviate range anxiety and concurrently reduce the on-board battery requirement (weight and cost reduction)

Overall Objective: Design, develop, build, and validate vehicle integrated 200 kW dynamic wireless electric vehicle (EV) charging

- Conduct a high-level cost study → Feasibility targets for light duty (LD) vehicles
- Perform gap analysis of SOA systems → R & D required to realize a viable dynamic wireless power transfer (DWPT) solution
- Develop 200 kW DWPT and validate in a real-world application scenario:
 - Vehicle integrated validation at 55 mph
 - Mitigation of vehicle body impact on power transfer and achieving minimal power oscillation
 - Development of roadway embeddable coil structure

FY 2021 Objectives:

- Complete laboratory validation of 200 kW dynamic charging system
- Conduct EM-field safety analysis and validation, and develop data acquisition system for high power DWPT system and support on-track evaluation of 200 kW dynamic charging system
- Explore the impact of DWPT infrastructure on primary roadways that was optimized for LD vehicles on the driving performance of HD (Class 8) EV travel

FY21 Milestones

Milestones

Lab	Date	Milestones	Status
ORNL	12/31/2020	Validate 200 kW power transfer capability of primary side power electronics, WPT coil, and resonant network.	Completed
ORNL	9/30/2021	Validate functionality of stationary high-power wireless charging with coil embedded on the vehicle.	In progress
INL	3/31/2021	Complete data acquisition system required for dWPT testing and evaluation	Completed
INL	9/31/2021	Assist with the evaluation and demonstration of ORNL DWPT system during dynamic operation	In progress
NREL	3/31/2021	Complete development of HD vehicle travel data	Completed
NREL	9/30/2021	Complete test cases for HD vehicles with different designs, allocations and EV models	In progress

Go/No-Go Decision Point

Lab	Date	Go/No-Go Decision	Status
ORNL	06/30/2020	If standalone test of 200 kW power electronics is successful, proceed with integration of PE and WPT coils	Go

Any proposed future work is subject to change based on funding levels

FY22 Milestones and Go/No-Go Decision

Milestones

Lab	Date	Milestones	Status
ORNL	12/31/2021	Validate functionality of the high-power dynamic wireless charging system.	Planned
ORNL	3/31/2022	Evaluate performance of dynamic wireless EV charging system based on performance.	Planned

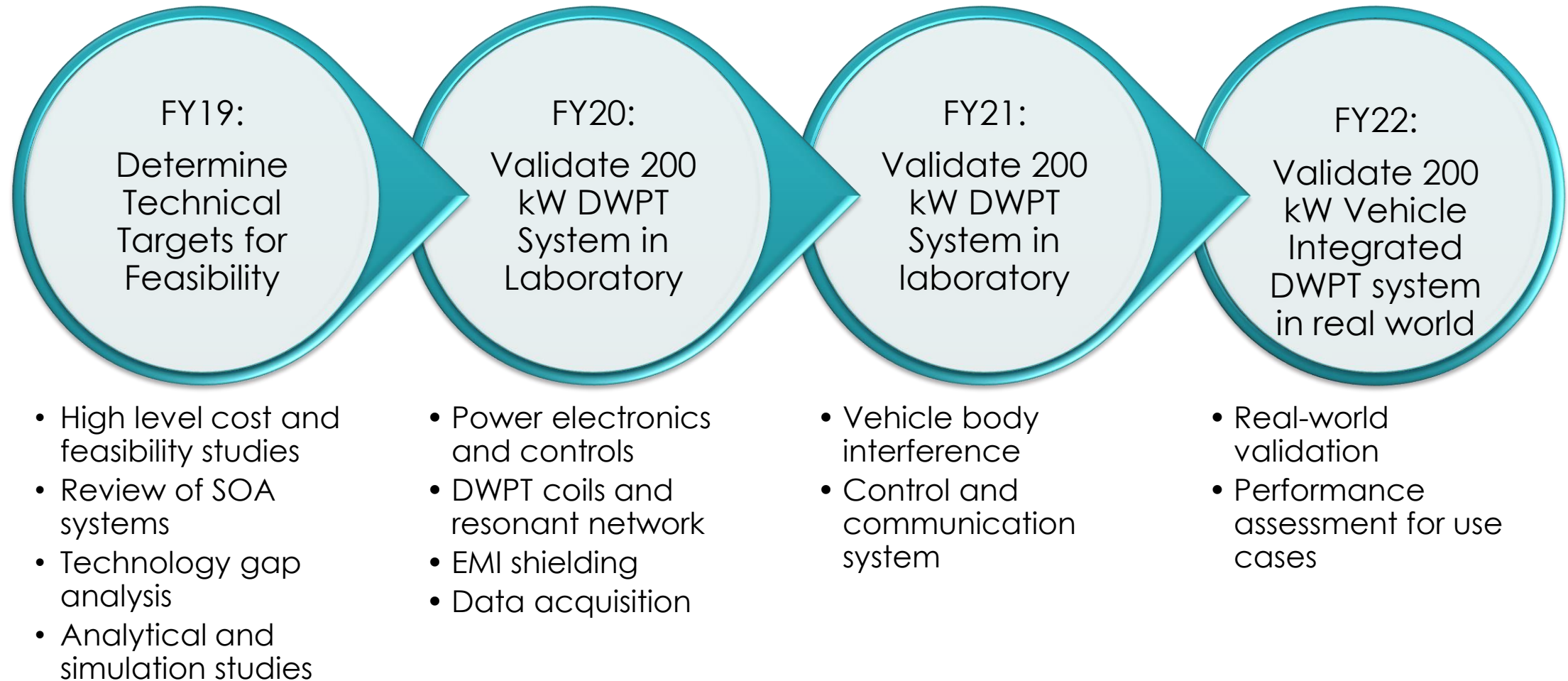
Go/No-Go Decision Point

Lab	Date	Go/No-Go Decision	Status
ORNL	12/30/2021	If basic functionality of robust dynamic wireless EV charging is proven at low-speed tests, proceed with performance evaluation.	Planned

Any proposed future work is subject to change based on funding levels

Overall Approach

Goal: Validate a vehicle integrated dynamic wireless EV charging system with parameters which enable it to be economically viable in real world conditions



Approach: Proof of Concept Validation

FY 19:

Analytical and
simulation
studies



FY 20:

Hardware design
and
development



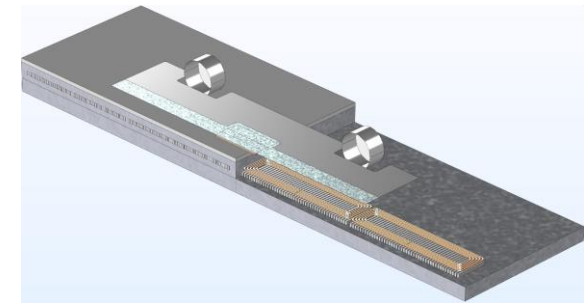
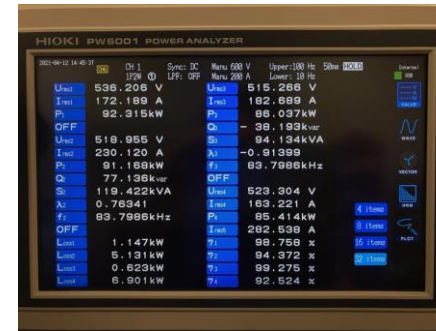
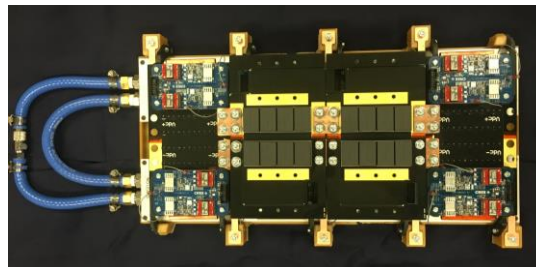
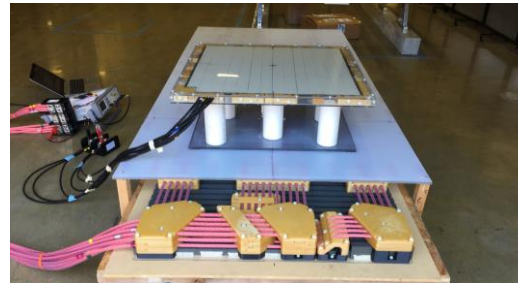
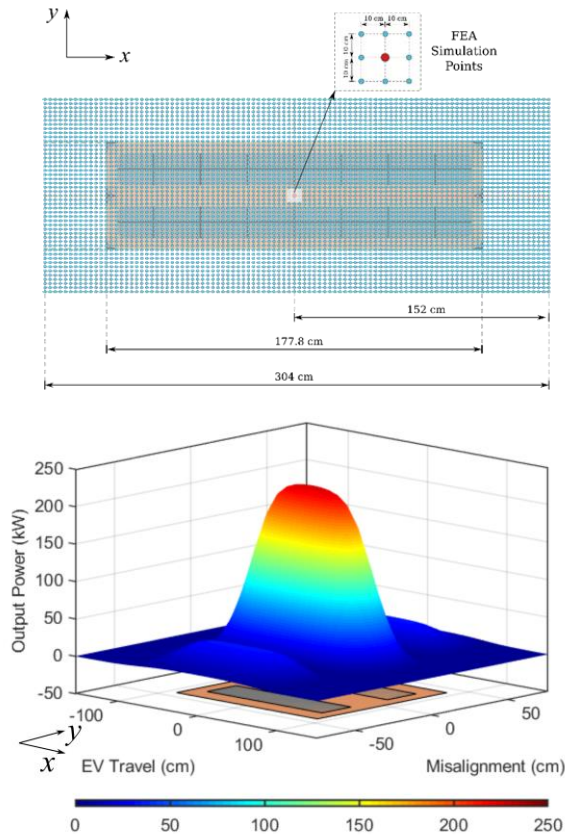
FY21:

Laboratory
validation of 200
kW DWPT



FY: 22

Real world
validation of 200
kW DWPT



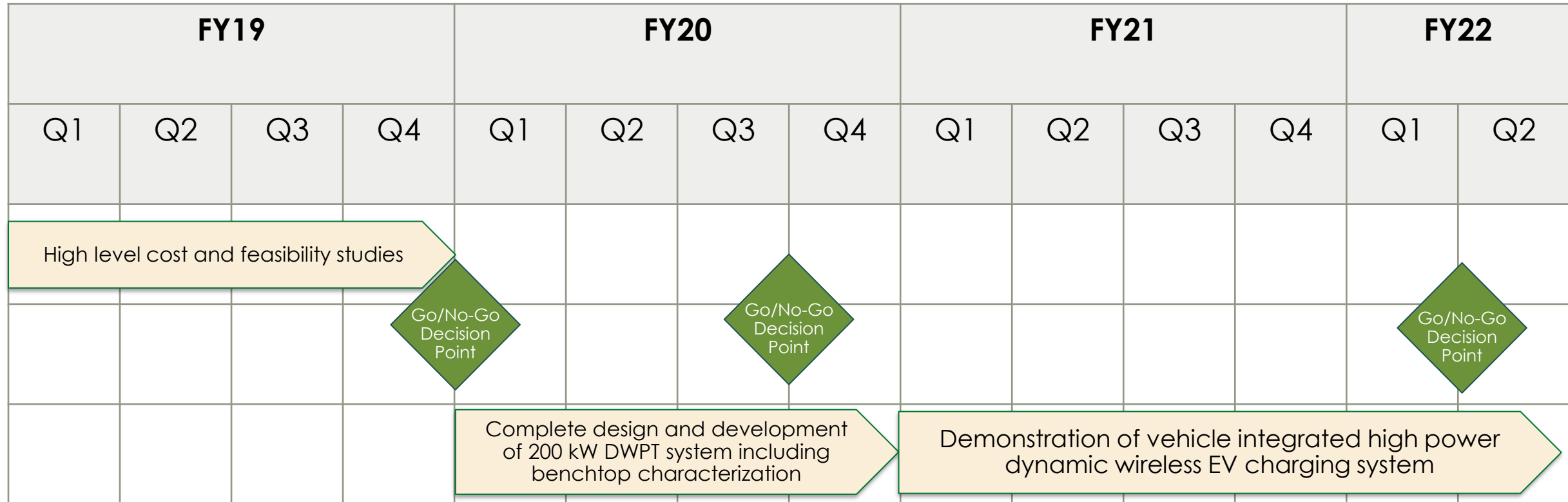
Detailed simulation and analytical design-oriented study

Hardware development and benchtop validation

Laboratory Validation of 200 kW DWPT using dynamic inductive charging emulator

Planned 200 kW 55 mph DWPT validation at ACM

Overall Project Timeline



FY20 Go/No-Go Decision Point: If standalone test of 200 kW power electronics is successful, proceed with integration of PE and WPT coils

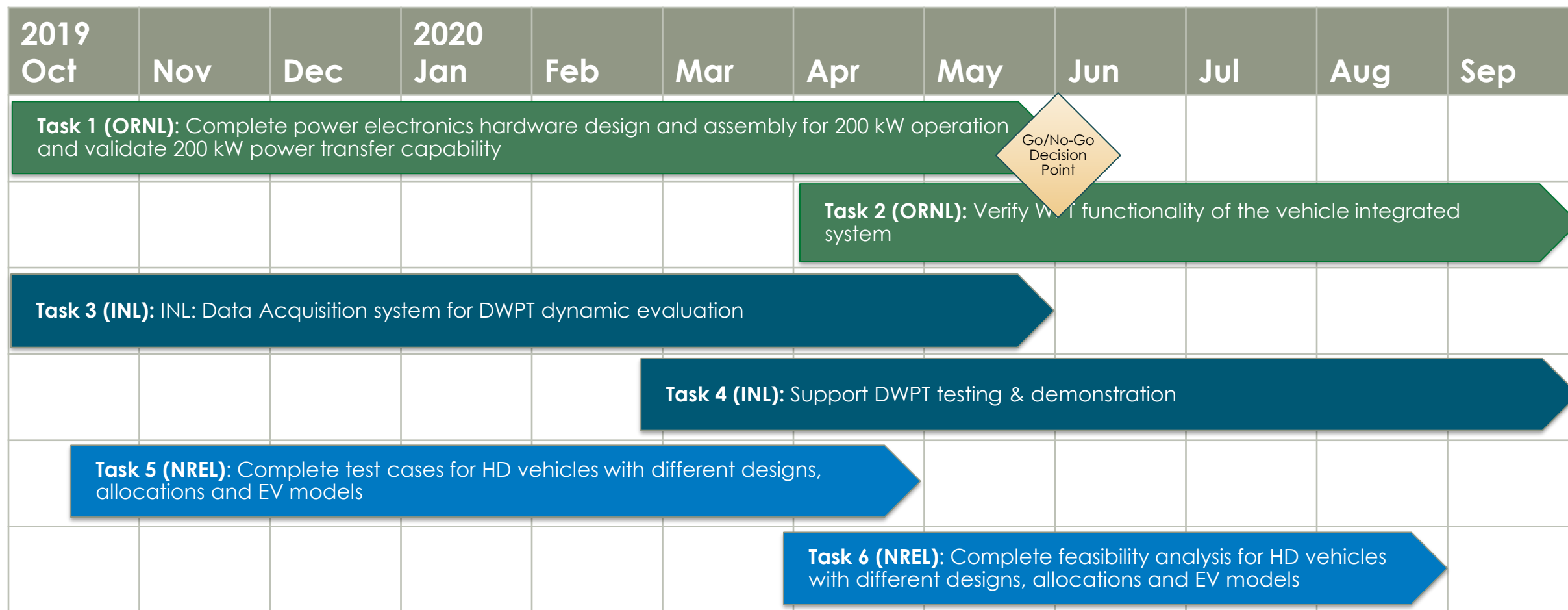
Outcome: Proceed with integration of PE and WPT coils

FY22 Go/No-Go Decision Point: If basic functionality of robust dynamic wireless EV charging is proven at low-speed tests, proceed with performance evaluation.

Outcome: In progress

Any proposed future work is subject to change based on funding levels

FY21 Timeline



FY20 Go/No-Go Decision Point: If standalone test of 200 kW power electronics is successful, proceed with integration of PE and WPT coils

Outcome: Proceed with integration of PE and WPT coils

Any proposed future work is subject to change based on funding levels

Technical Accomplishments FY20: Completed Benchtop Characterization of 200 kW DWPT Couplers

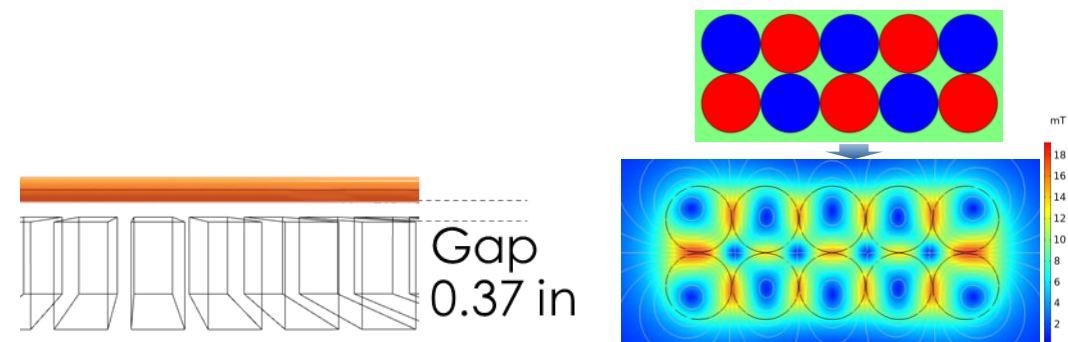
Goal: To design DWPT couplers to achieve the mutual inductance target for 200 kW power transfer

Challenge: High current density exasperates thermal challenges, and the required long lead length translates to significant additional inductance

- Verified 200 kW power transfer capability
- Minimized lead-inductance by introducing wire-interleaving
- Optimized core-geometry to remove potential thermal hotspot
- Optimized ferrite and winding spacing which led to further increase in mutual inductance

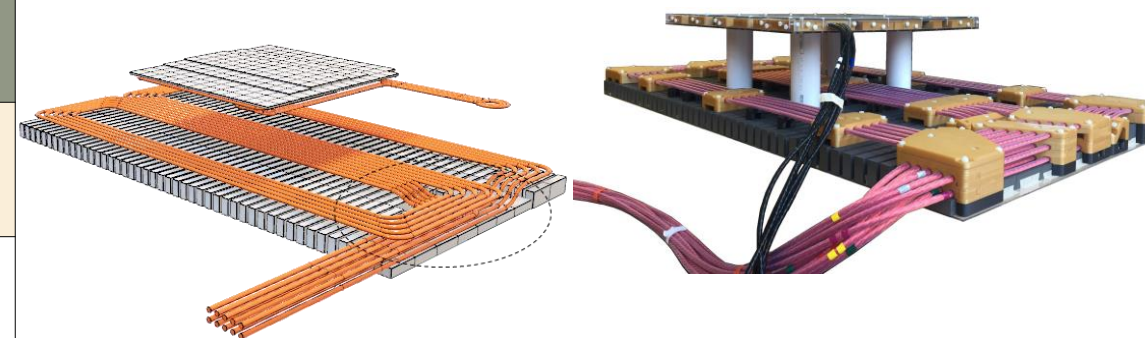
Mutual inductance target for 200 kW DWPT at 9.3" gap – 1.7 μ H

	Tx self inductance (μ H)	Tx self inductance with interleaving (μ H)	Rx self inductance (μ H)	Mutual inductance (μ H)
Preliminary benchtop measurement	8.2	7.1	22.79	1.67
FEA results based on proposed modifications	NA	7.6		1.96



Optimized coil and ferrite spacing

Interleaving minimizes lead-inductance



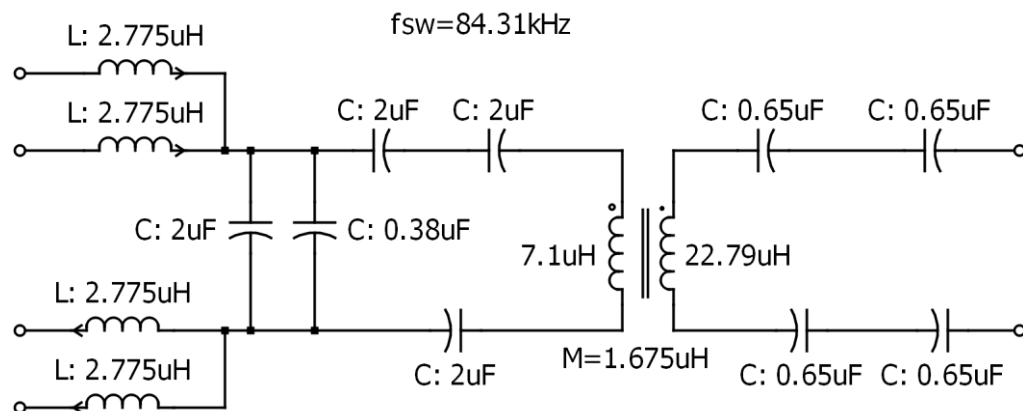
FEA coil and core model and prototype

Technical Accomplishments FY20: Completed Resonant Network Analysis for 200 kW DWPT Operation

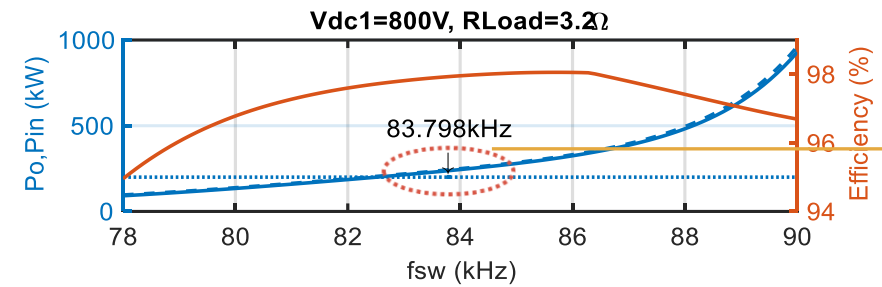
Goal: Design resonant network to enable efficient and controllable 200 kW DWPT

Challenge: Dynamic charging offers wide range of coupling variation and achieving soft-switching (for efficiency and safety) is critical

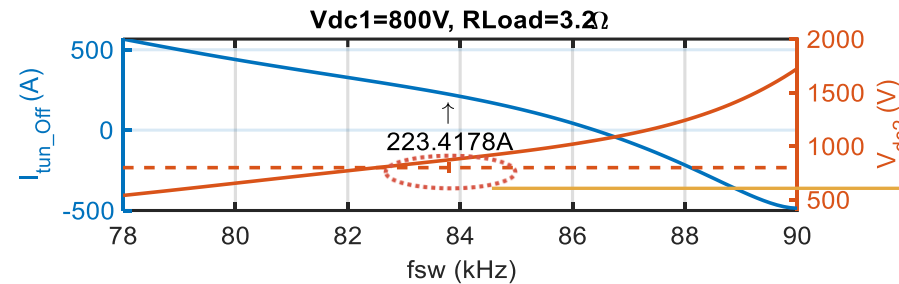
- Completed analysis and design of primary side LCC and secondary side series tuned 200 kW DWPT
- Design targets
 - 200 kW power transfer capability at 800 V
 - Reduced switching and conduction losses
 - Component values that can be practically realized



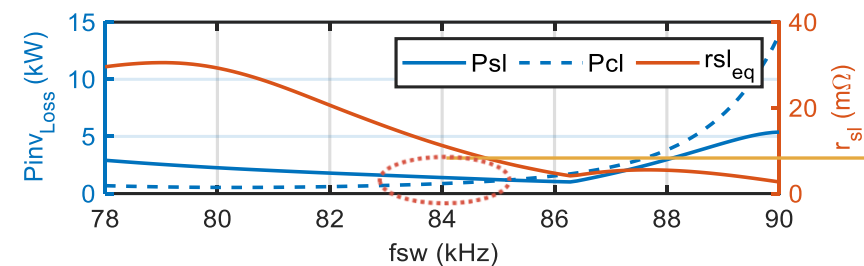
Primary side LCC and secondary side series resonant network for 200 kW DWPT



Operating frequency required for 200 kW+ operation at 98 % primary inverter efficiency



Estimation of turn-off current required to estimate switching losses



Less than 5 kW of total PE inverter losses

Analytical calculation of output power and losses for the designed resonant network configuration

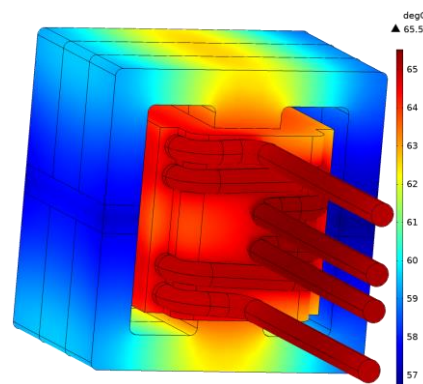
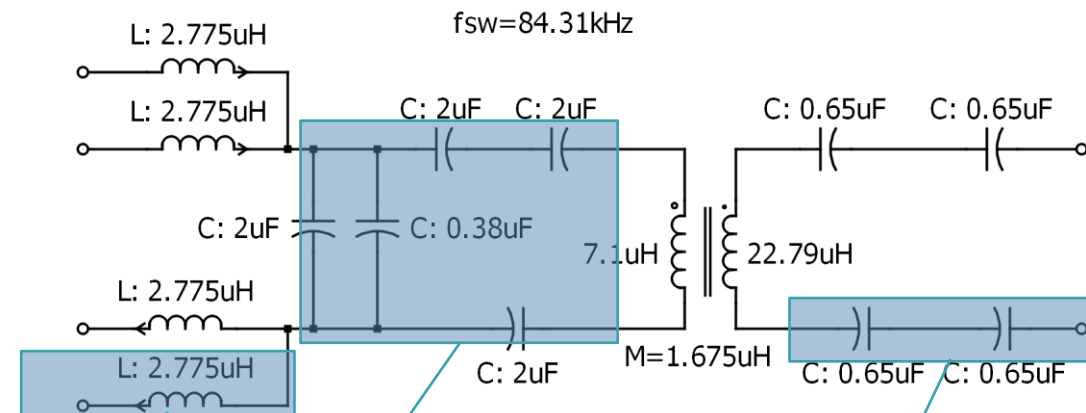
Technical Accomplishments FY21: Designed and Built Optimized Resonant Network for 200 kW DWPT

Goal: To design compact capacitor bank that meets current, voltage, and thermal requirements of 200 kW power transfer

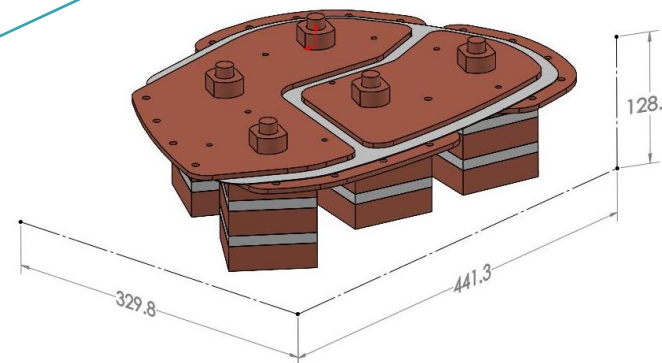
Challenge: High voltage (~4kV), high current (~750A), and high frequency (~85 kHz) operation leads to power density and efficiency challenges

Identified optimized capacitance, busbar design, and cooling method for the high-power high-frequency capacitor bank

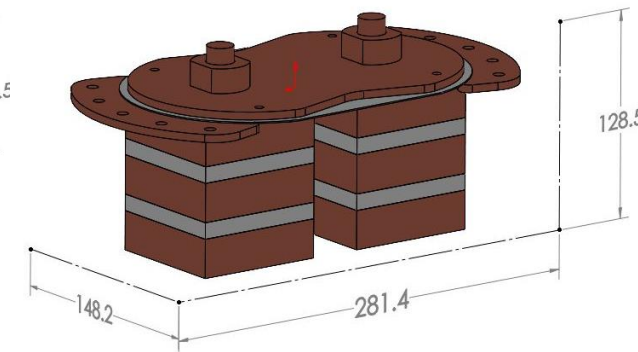
- Modified capacitances to compensate additional lead-inductance
- Optimized coolant and cooling channel to efficiently meet the thermal limit of capacitor
- Identified potential compact capacitor bank design that will reduce the size by ~40%
- Designed and built optimized resonant inductor with less than 25 Dec C.



Primary-side
resonant inductor



Primary-side
capacitor bank



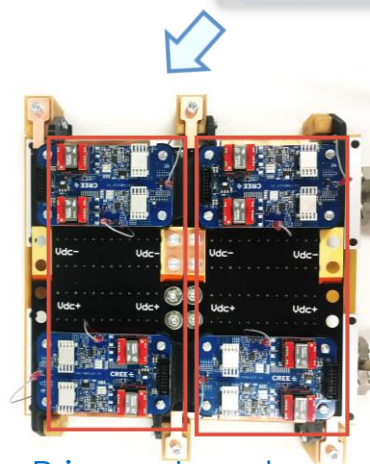
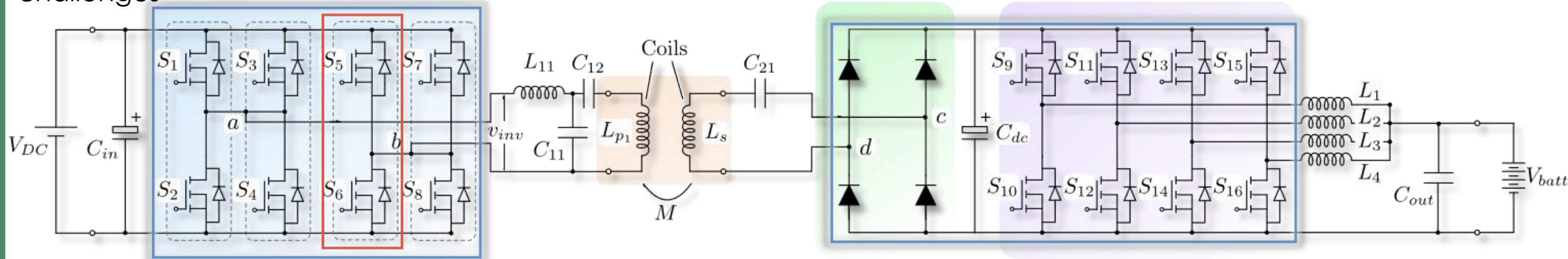
Secondary-side (half)
capacitor bank

Technical Accomplishments FY21: Completed

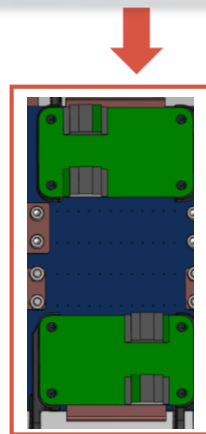
Development of Primary and Secondary Power Electronics

Goal: To develop efficient, compact, and reliable power electronics for high power operation

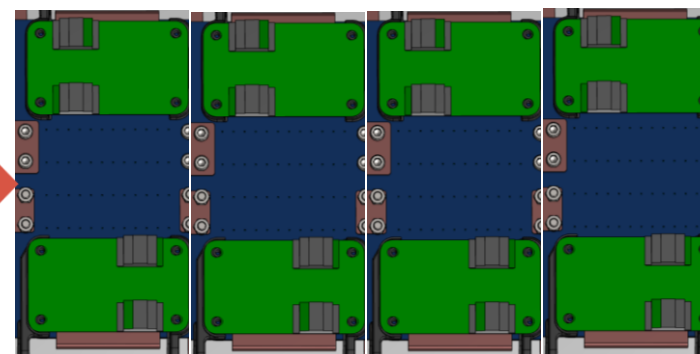
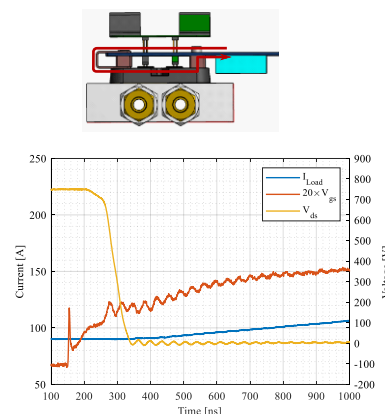
Challenge: Each power electronic stage has high frequency, high-voltage, and high current related design challenges



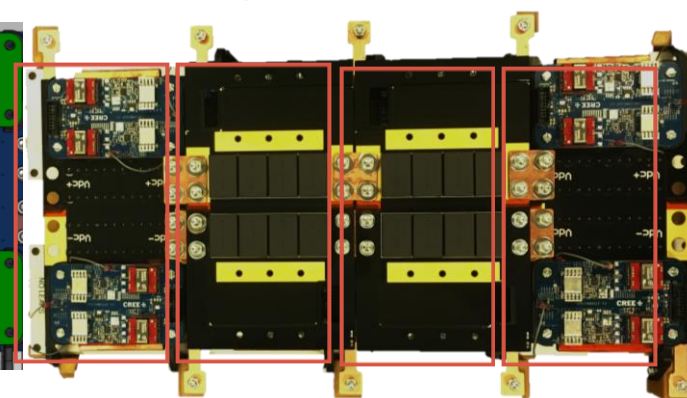
Primary Inverter:
2x building blocks



Compact, low noise building block with
reliable and efficient switching



Modular up-scaling by
horizontal cascading

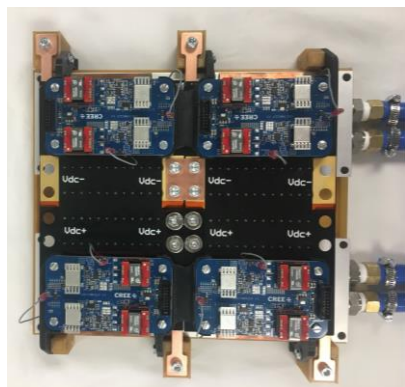
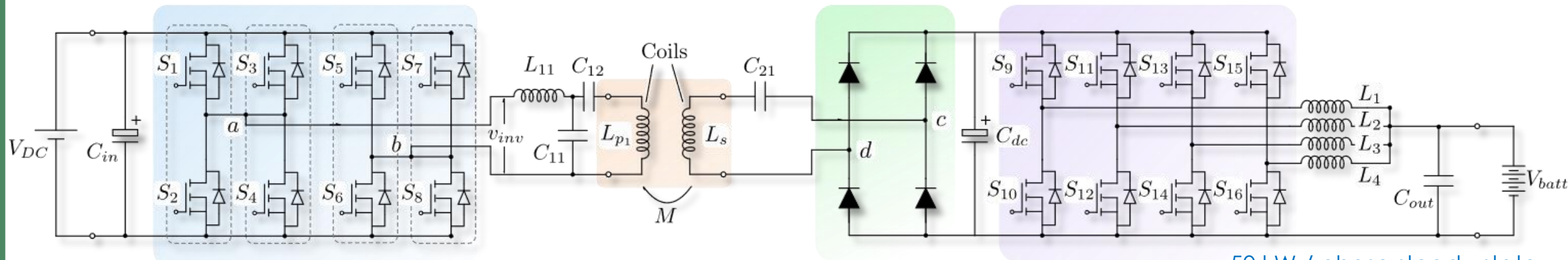


Secondary Rectifier
and DC/DC:
4x building blocks

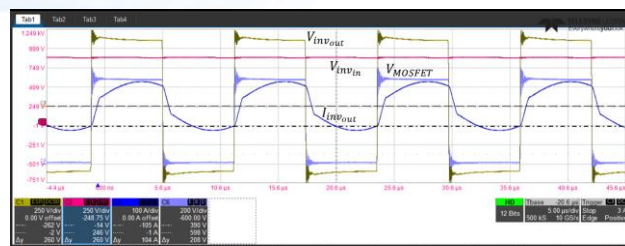
Modular approach enables high performance, fast prototyping, and reliable operation

Technical Accomplishments FY21: Completed Validation of Primary and Secondary Power Electronics

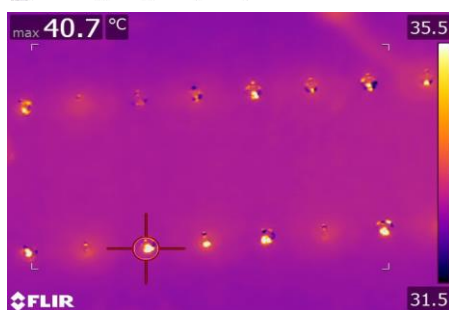
Goal: Validate the operation of the power electronics in WPT setup



Primary Inverter

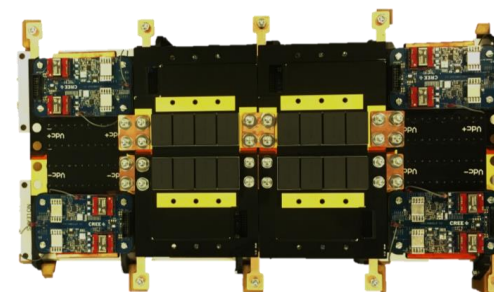


85 kW test waveforms



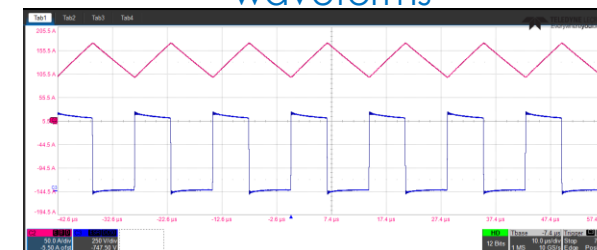
Thermal image of the PCB bus bar

- Tested inverter @ 85 kW, 800 V, 85 kHz, achieved 98.6% efficiency
- Low 41 °C high-current PCB temperature after 30 minutes continuous operation

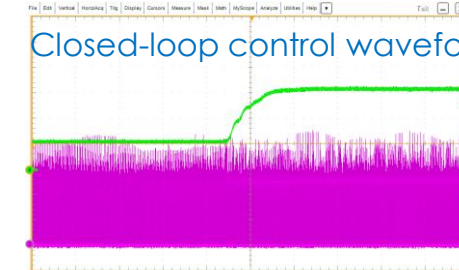


Secondary Rectifier and DC-DC converter

50 kW / phase steady-state waveforms

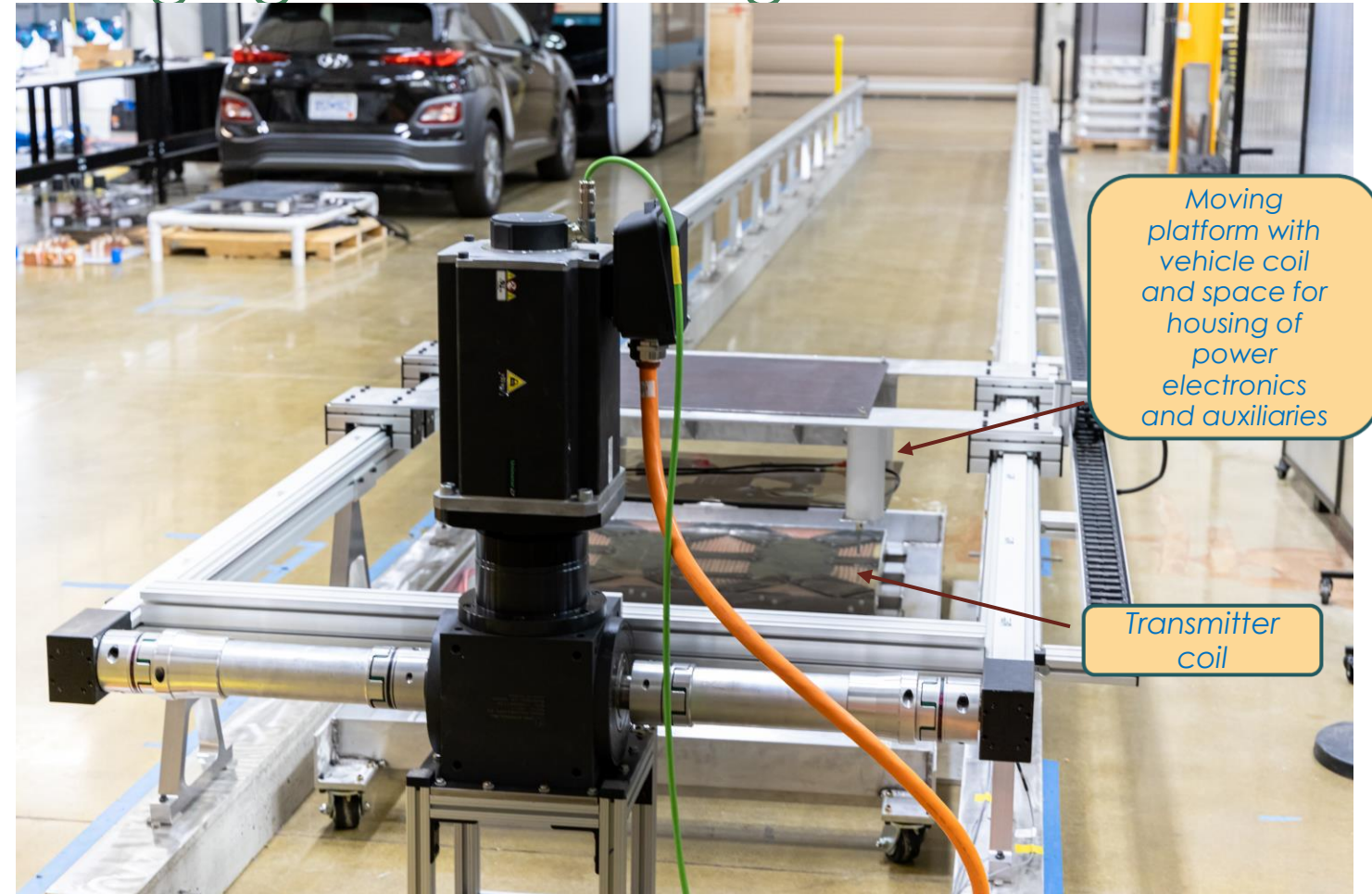


Closed-loop control waveforms



- Tested power stage @ 50kW/phase, 800 V, 70 kHz, achieved 98.3% efficiency
- Developed fast hardware protection with 4μs response time
- Verified closed-loop regulation at reduced power

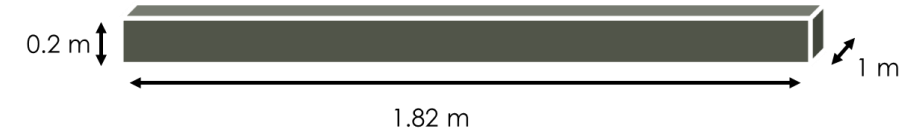
Technical Accomplishments FY21: Installed and Verified Functionality of Dynamic Charging Evaluation Rig



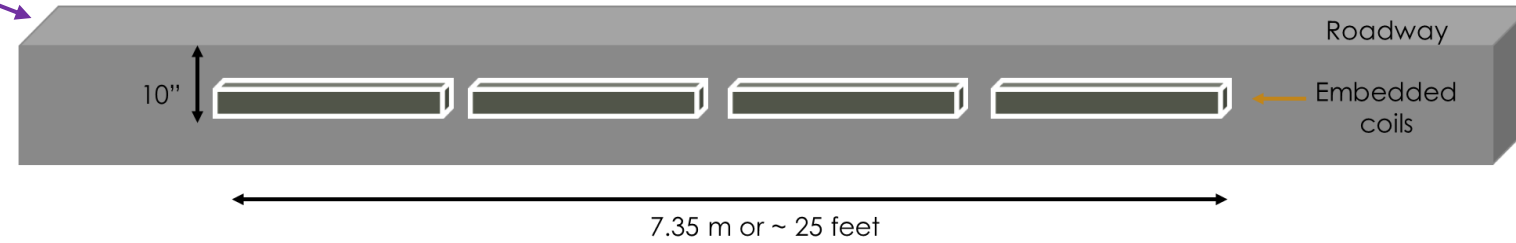
Dynamic inductive charging validation rig

- Track length - 18 m
- Payload capability – 100 Kg
- Speed ~ 9 m/s (20 mph)
- x, y, and z coil misalignment capability
- Automated and programmable operation modes
- Capability to incorporate with HIL software

Technical Accomplishments FY21: Identified 200 kW Dynamic Charging Location



Individual precast ground coil block



Electrified Segment: Four precast ground coil blocks embedded in the roadway

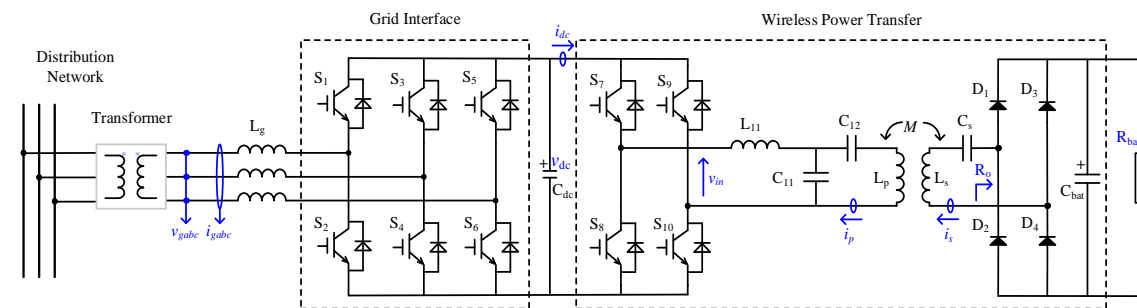
Demonstration site - ACM

- Four precast coil blocks to be embedded in roadway at ACM in location 4
- 13 KV electrical supply line to provide power for 200 kW DWPT evaluation
- Roadway with ample distance to get up to speed over the installed couplers.

Technical Accomplishments FY20: Completed Preliminary DWPT Grid Integration & Impact Analysis

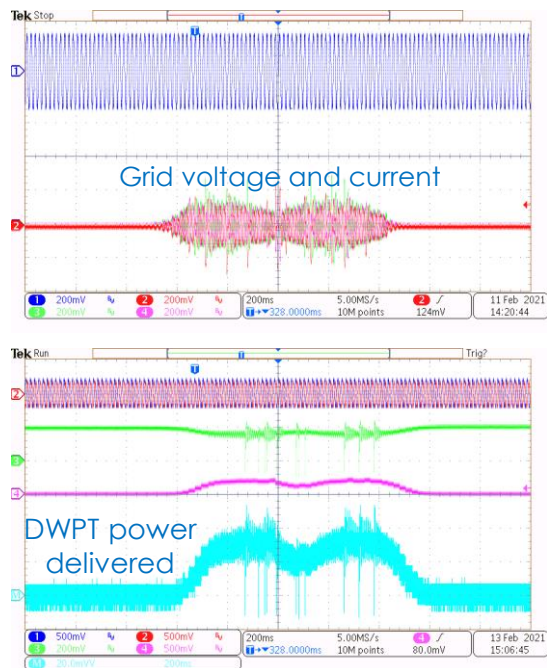
Accomplishment:

- Proposed and verified grid interface control strategy by detailed real-time emulation
 - Enhanced load transient response capability to address power pulsation from DWPT
 - Considered Imbalanced distribution network

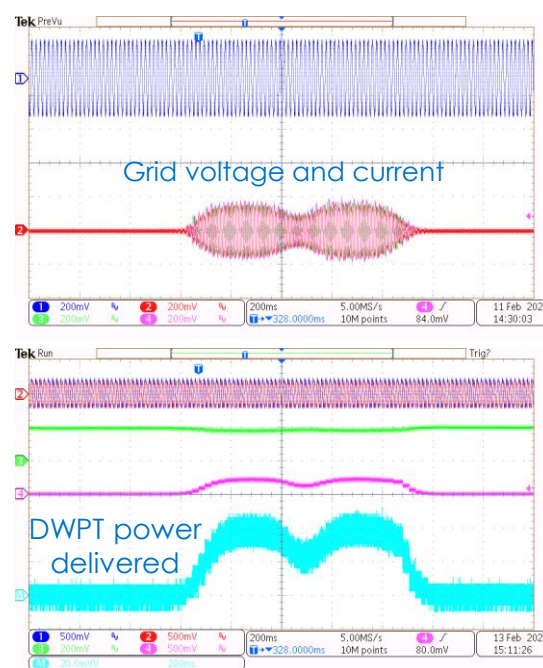


Architecture of Grid integrated 200 kW DWPT system

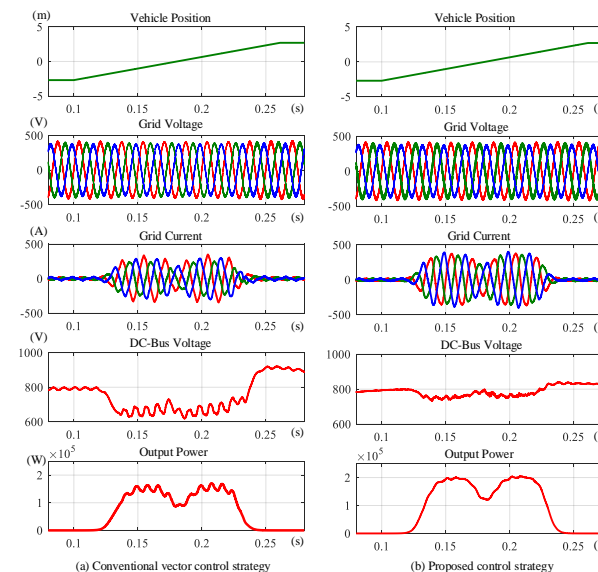
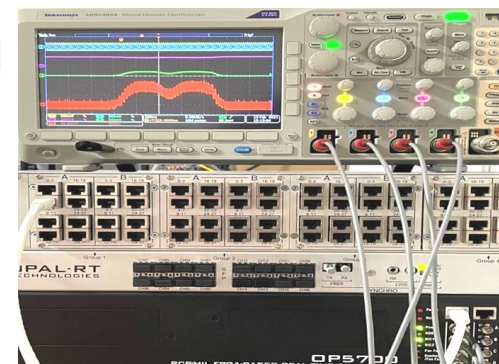
Conventional Grid-interface Control Scheme



Proposed Grid-interface Control Scheme



Proposed Grid-interface Control Scheme implemented in OPAL-RT



Comparisons of the conventional control strategy and the proposed control strategy for the grid interface converter

Technical Accomplishments FY21: EM-field Shielding

Design for the 200kW DWPT

Goal: To ensure safety of 200kW DWPT system with respect to electro-magnetic safety

Issue: DWPT leads to more complicated charging scenarios. All typical wireless charging scenarios should be investigated to ensure EM safety.

- **Scenarios**

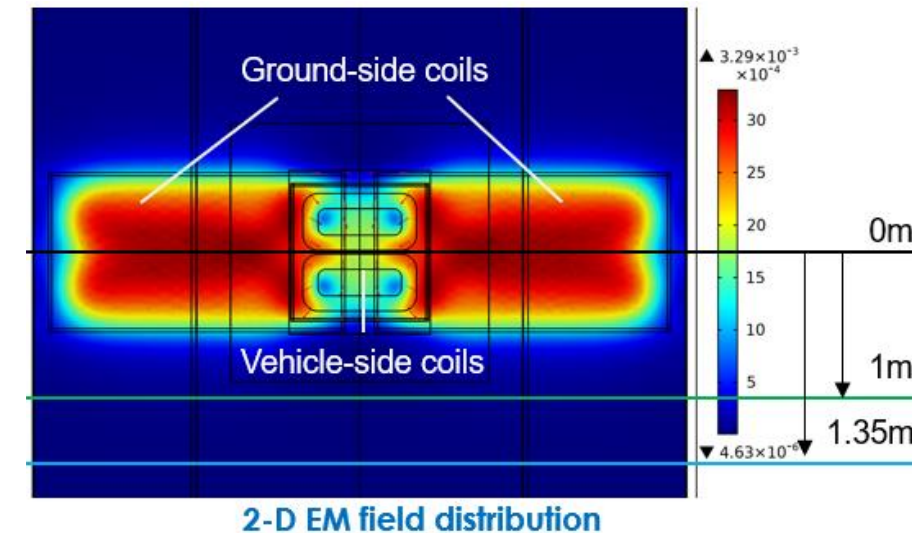
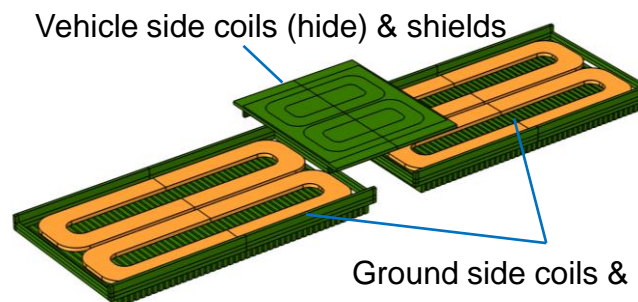
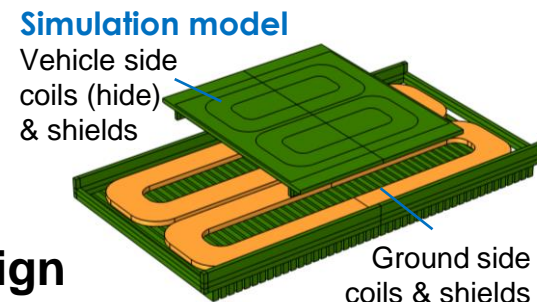
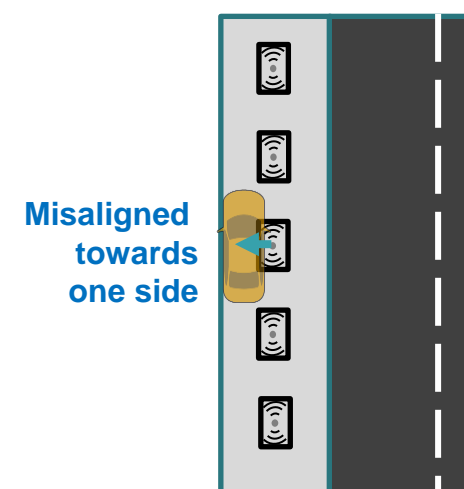
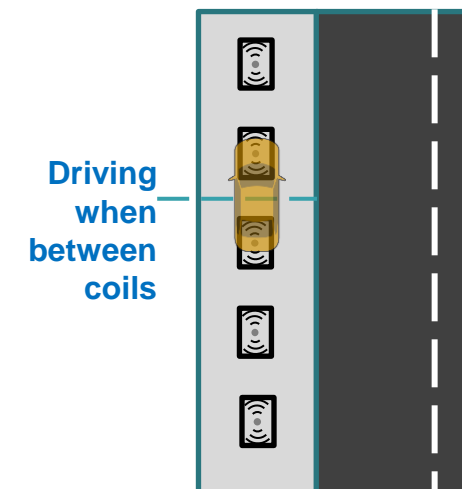
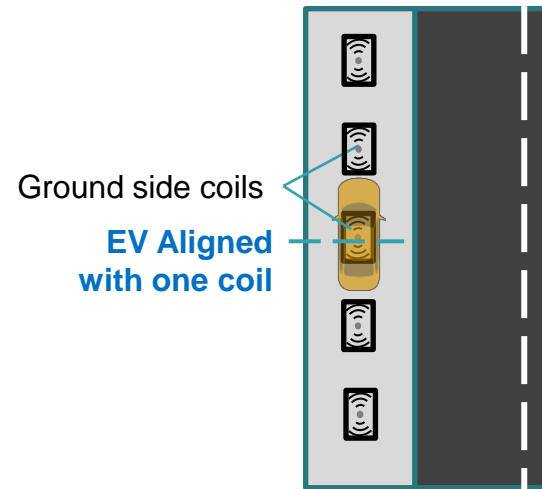
- A. EV is aligned with one ground-coil
- B. EV is positioned between two ground-coils
- C. EV is misaligned towards one side

- **Considerations**

- The edge of the roadway lane is proposed as EM safety boundary for evaluation
- Misalignment is considered
- 200 kW in-motion operation

- **Completed: EM-field shielding design for the 200kW in-motion dWPT**

- **Final testing will be at ACM site**



Technical Accomplishments FY21: DWPT Data Acquisition System Completed and Operational Functionality Verified

Goal: Complete data acquisition system for DWPT ground-side and vehicle-side measurements

Issue: Measurement of transient, high-speed in-motion power transfer requires synchronized high-speed data collection from many measurement sources (electrical, alignment, EM-field, veh. speed, etc.)

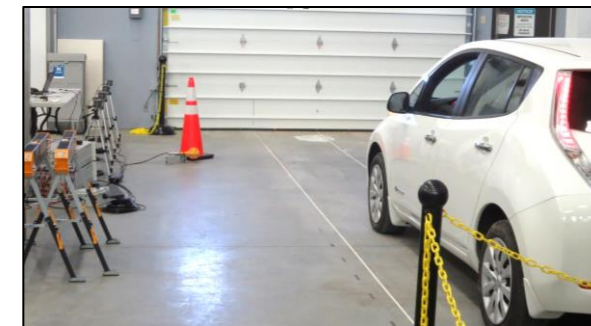
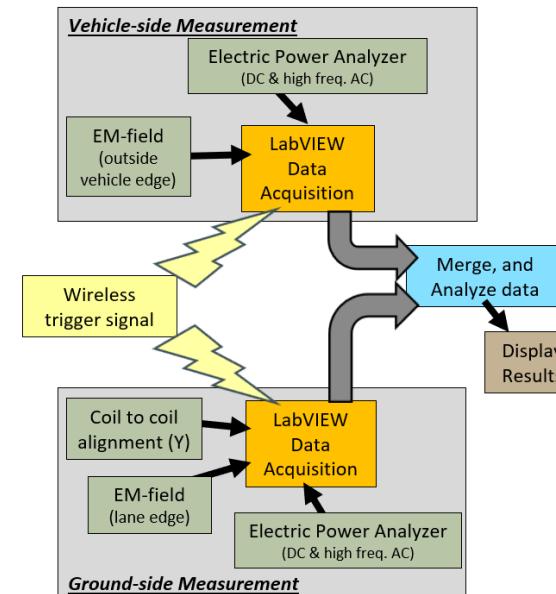
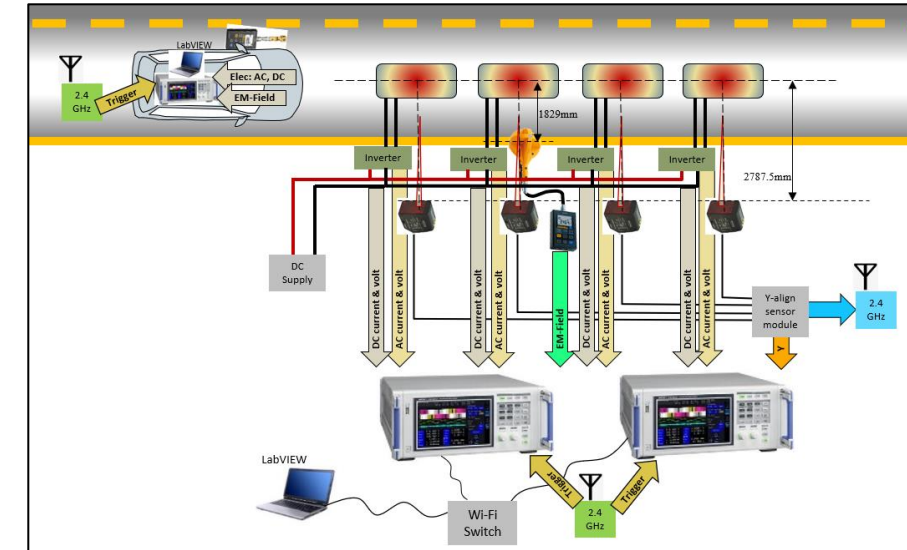
Data acquisition system completed and demonstrated functionality using a production EV

• Data Acquisition Features:

- Power analyzers for electrical measurements of the ground-side and vehicle-side power flow
- EM-field probes at the lane's edge and at the edge of the vehicle
- Wireless synchronous trigger to align data capture
- Non-contact distance sensors to measure the vehicle's lane alignment when traveling over each ground coil
- Driver's Alignment Aid (DAA) to enable testing with repeatable lane alignment or misalignment (i.e. coil to coil Y-alignment)

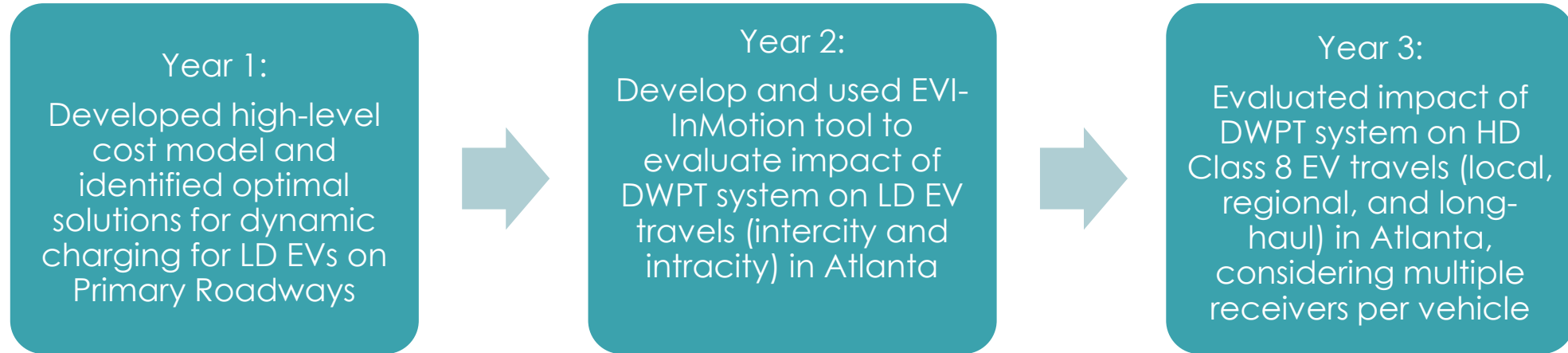
• Two rates of measurement

- 1MHz for waveform transient analysis, calibration tuning, and debug
- 100Hz calculated measurement values for fast results of power transfer, efficiency, EM-field, & misalignment



Technical Accomplishments FY21

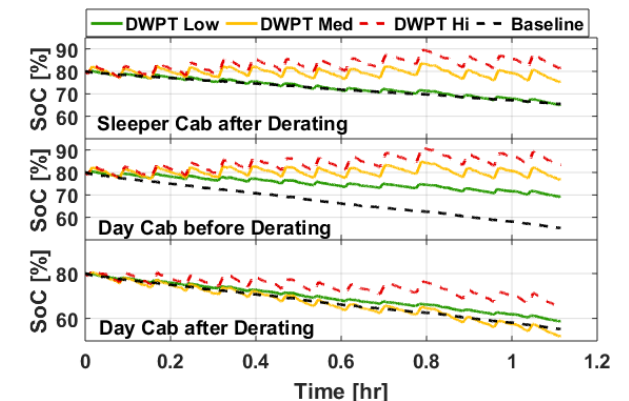
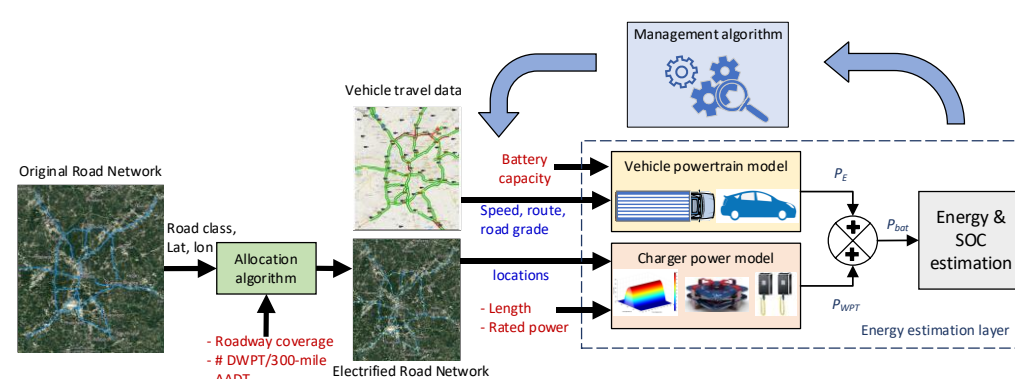
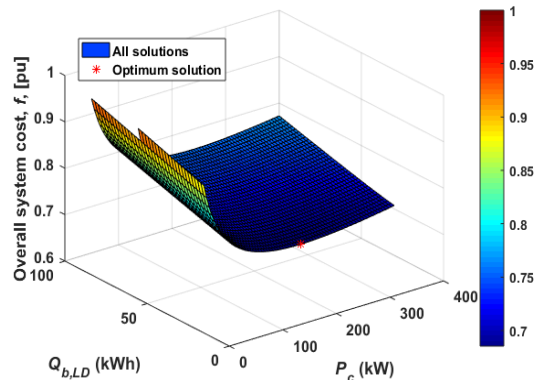
Overall Approach and Accomplishments



High-power (200-250 kW) and low-coverage (8-20%) DWPT with small battery (30-60 kWh for LD EVs and 200-500 kWh for Class 8 EVs) has the potential to allow CS operation on primary roadways (unlimited range)

Besides CS on primary roadways, DWPT system provides >2x range extension for ~33% of LD EVs, > 4x for 24% of LD EVs, and > 6x for 19% LD EVs in Atlanta metro area.

- Scaling DWPT system for class 8 EVs by using multiple receivers (4-6) per vehicle has the potential to provide CS operation on primary roadways with a much smaller battery size (up to 80 reduction).
- Exploring large scale impact in Atlanta??



Technical Accomplishments FY21

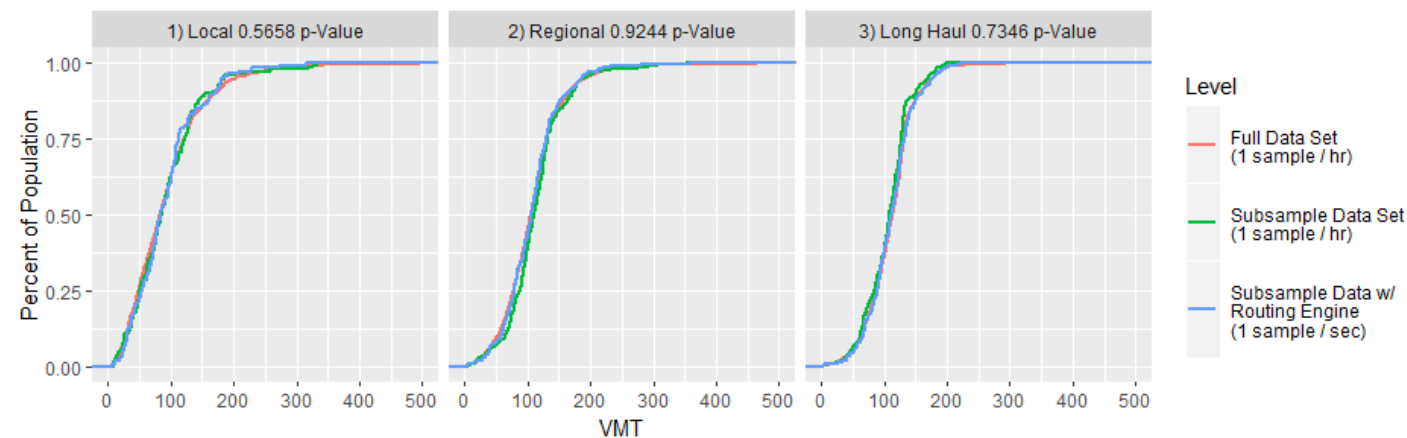
Development of High-Resolution HD Vehicle Travel Data using 1 Sample/Hour Waypoints

Goal: To develop high-resolution HD vehicle travel data (route and speed) to be used in exploring the impact of DWPT system on HD vehicle travel

Challenge: Available data set is low resolution (1 sample/hour)

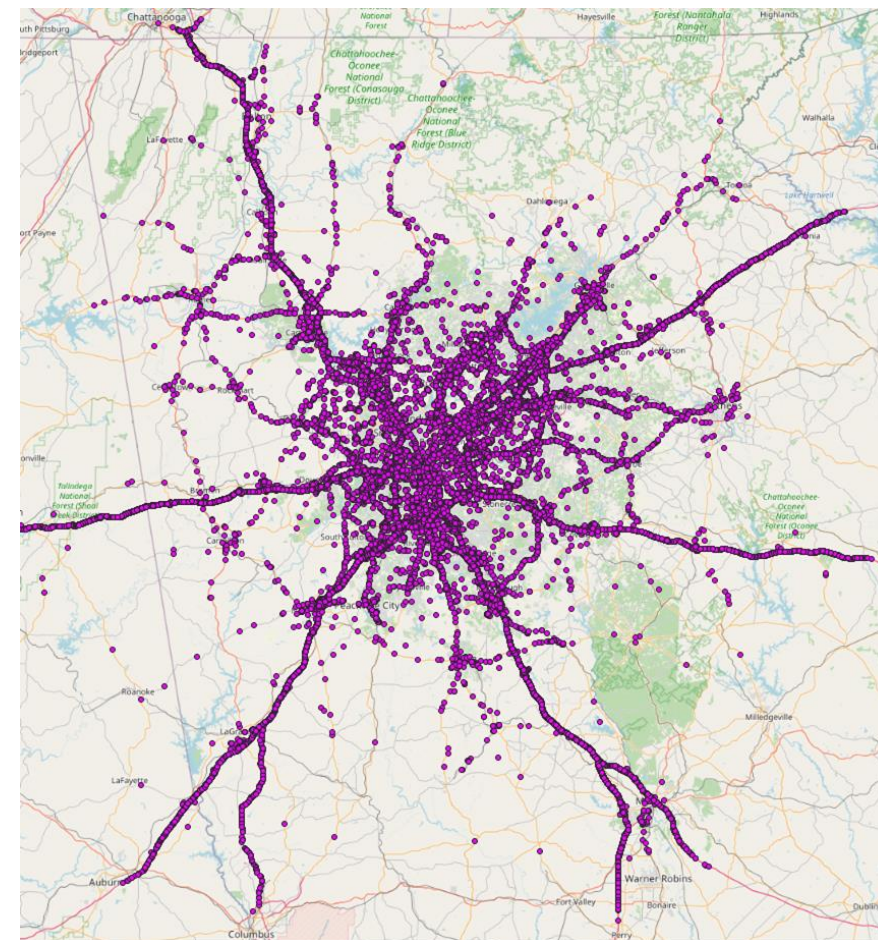
Data Methodology:

- **Classification:** classify HD travel data into local, regional, and long-haul based on the radius of operation
- **Subsampling:** select a representative subset of the total data set to reduce computational time
- **Route generation:** generate and validate route data using 1 sample/hour waypoints (Inverse weighted Dijkstra's algorithm)
- **Route discretization (1 Hz):** develop 1 Hz route and speed profiles



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Probability indicator (p-value) > 0.05 indicates the subsample is an acceptable representation of the population



Snapshot of real-world HD way-points in Atlanta

- The HD data set makes up ~4% of all VMT for national freight.
- 7.6K unique HD vehicles within the Atlanta region.
- ~30K unique trips within the Atlanta region.
- Original data set 1 Sample per hour.

Technical Accomplishments FY21

Identified HD Vehicle Models and Parameters Associated with DWPT System

Goal: Identify representative class 8 EV models with the associated battery size and number of receivers

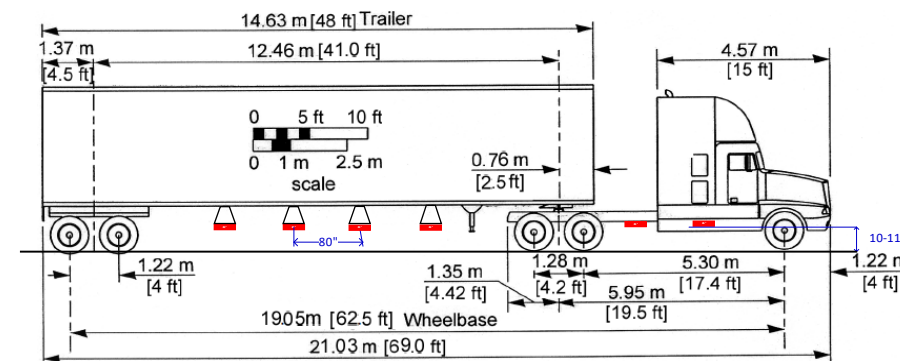
Class 8 EV Models:

- Two EV class powertrain models are considered:
 - Sleeper Cab: used with long-haul travel data
 - Day Cab: used with regional and local travel data
- Maximum number of receivers in each models is identified based on DWPT system and vehicle dimensions.
- Sleeper Cab (Models A: 2.4 kWh/mile): fit 6 receivers
- Day Cab (Models B: 2.3 kWh/mile): fit 4 receivers
- Receivers can be installed at lower level in the trailers

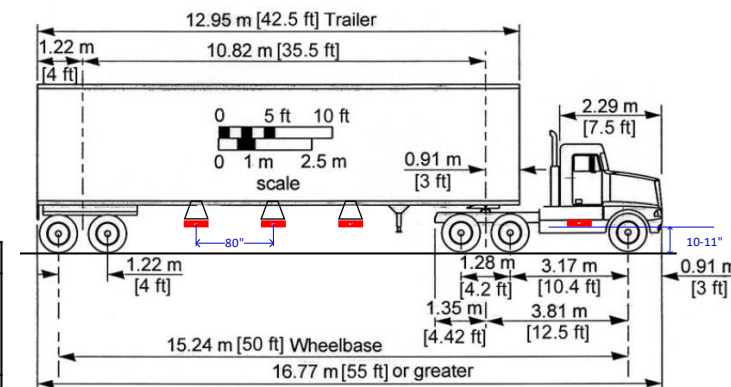
Test

Cases:

	Low requirements for LD EVs	Medium requirements for LD EVs	High requirements for LD EVs
Approach based on LD vehicles	- CS for intercity travels, - min road coverage, - low travel requirements (65 mph, 270 Wh/mile)	- CS for intercity travels, - min overall system cost, - medium travel requirements (74 mph, 310 Wh/mile)	- CS for intercity travels, - min overall system cost, - high travel requirements (86 mph, 350 Wh/mile)
Roadway coverage (%)	8.2	14.56	16.6
Transmitter power (kW)	235	200	225
Sleeper Cab EV	Battery size (kWh)	497.8	222.2
	# receivers	7→6	6
	Received Power (kW)	~235 x 7/6 = 1,645/1,410	~200 x 6 = 1,200
Day Cab EV	Battery size (kWh)	494.2	220.6
	# receivers	7→4	6→4
	Received Power (kW)	~235 x 7→4 = 1,645→940	~200 x 6→4 = 1,200→800
#DWPT/300-mile	20, 40, 60, 80, 100, optimized	20, 40, 60, 80, 100, optimized	20, 40, 60, 80, 100, optimized
Elec. Segment (mile)	1.23, 0.62, 0.41, 0.31, 0.25, x1	2.18, 1.09, 0.73, 0.55, 0.44, x2	2.49, 1.25, 0.83, 0.62, 0.5, x3
Non-elec. Segment (mile)	13.77, 6.88, 4.59, 3.44, 2.75, y1	12.82, 6.41, 4.27, 3.2, 2.56, y2	12.51, 6.25, 4.17, 3.13, 2.5, y3



Model A



Model B

DWPT Receivers in Different Class 8 Vehicles

Comparable 600-mile non-DWPT vehicle could require up to ~1.4 MWh battery

Technical Accomplishments FY21

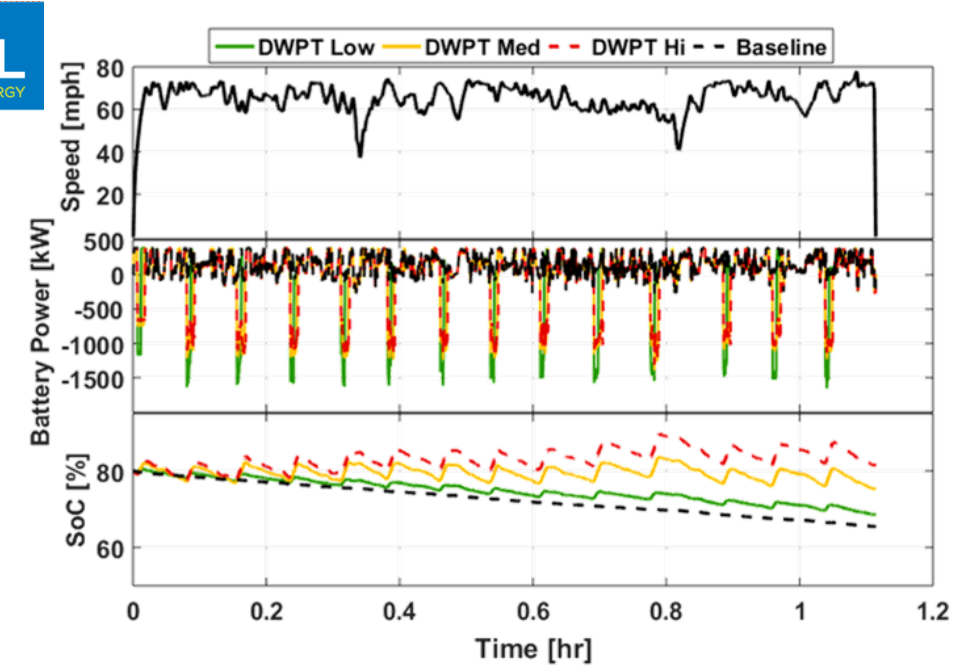
Preliminary Results: Analyzed Class 8 EV Performance on Primary Roadways in Atlanta with DWPT system



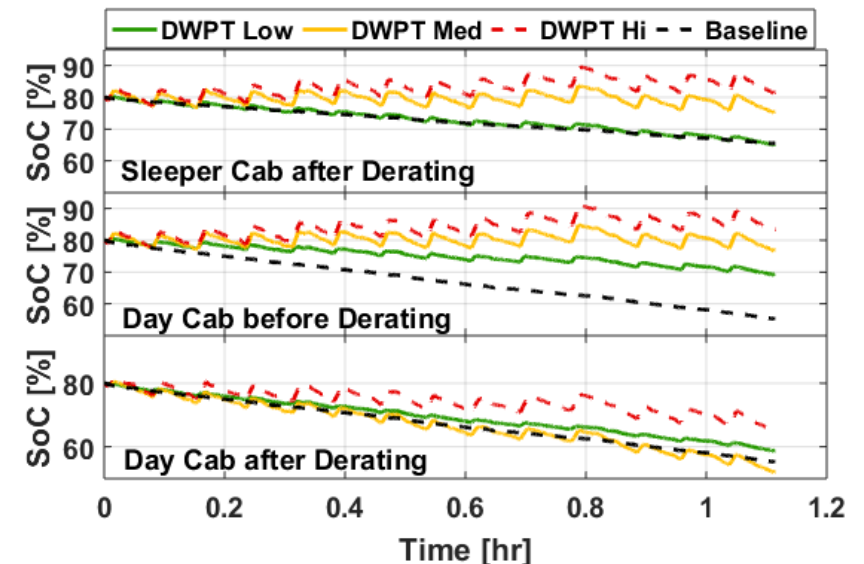
Goal: Test the travel performance of class 8 vehicles in primary roadways

- Small sample of real-world trips for class 8 trucks on primary roadways in Atlanta from NREL's FleetDNA are used.
- In most cases DWPT system is able to compensate for vehicle consumption leading to near zero kWh/mile on primary roadways
- DWPT system design with higher road converge (DWPT Hi) shows consistent charge-sustaining (CS) in sleeper and day cab EVs.
- Space constraint on vehicles leads to lowering the number of receivers and impacts the CS performance

Energy Consumption [kWh/mi]			DWPT Low	DWPT Med	DWPT Hi
Sleeper Cab	Original	min	0.635	0.029	-0.135
		mean	0.763	0.171	-0.003
		max	0.926	0.339	0.187
	Derated	min	0.869	0.029	-0.135
		mean	0.994	0.171	-0.033
		max	1.143	0.339	0.187
Day Cab	Original	min	0.586	-0.021	-0.179
		mean	0.713	0.124	-0.049
		max	0.875	0.312	0.161
	Derated	min	1.287	0.713	0.301
		mean	1.407	0.848	0.418
		max	1.525	0.995	0.6



Sleeper cab EV performance on primary roadway with and without DWPT system (60 segment/300- mile)



Sleeper and Day cab EV performance on primary roadway before and after derating
2021 VTO AMR Peer Evaluation Meeting

Response to Previous Year Reviewers' Comments

Reviewer Comment: There is a good approach, but some intermediate verification of the dynamic aspect would be helpful.

Reply: Dynamic inductive charging evaluation rig has been installed to aid in dynamic testing before vehicle implementation

- Can emulate vehicle movement across 20 m track with velocity up to 8 m/s
- Can emulate vehicle misalignment and different magnetic airgap

Reviewer Comment: The future research looks appropriate and logical. It would be good to hear more about the work needed on the pavement side of the system and the implications (both technical and cost) to the roadways when that information is ready to be presented.




Reply: We have initiated discussions with Virginia Tech Transportation Institute to leverage their expertise in evaluation and preparation for roadworthiness.

Reviewer Comment: More focus on the dynamic aspects is needed.




Reply: The control and dynamics of the secondary side dc-dc converter and the 200 kW DWPT system is being analyzed with a design-oriented approach. The dynamic inductive charging evaluation test rig will also be used extensively for experimental validation.

Collaboration and Coordination with Other Institutions

Laboratory partners:

	<ul style="list-style-type: none">• Project lead• 200 kW power dynamic EV charging system design, simulation, hardware development, vehicle integration and validation
	<ul style="list-style-type: none">• Design of active and passive shielding and data acquisition system for 200 kW dynamic EV charging system
	<ul style="list-style-type: none">• High level cost study of high-power dynamic wireless EV charging• Study of large-scale deployment scenarios of high-power dynamic EV charging

Coordination with Other Institutions:

	<ul style="list-style-type: none">• Kona EV for high power dynamic wireless EV charging demonstration• Engineering support and guidance for integration of DWPT system with the vehicle
	<ul style="list-style-type: none">• Site for 'electrified mile' dynamic charging demonstration (FY21)• Infrastructure and support for demonstration
	<ul style="list-style-type: none">• Evaluation and guidance of making the ground side coils and power electronics roadworthy

Remaining Challenges and Barriers

- Evaluate and overcome the effect of vehicle body interference on power transfer efficiency
- Evaluate the effect of embedding couplers in roadway has on power transfer efficiency

Any proposed future work is subject to change based on funding levels

Proposed Future Research

Research:

- Evaluate performance of WPT couplers embedded in roadway and plan for road-worthiness from both civil engineering and electrical performance perspectives
- Explore the possibility of replacing secondary passive rectifier and DC-DC converter with a single active rectifier

Tasks/Milestones:

• FY 2021

- Validate 200 kW dynamic wireless charging capability in laboratory using dynamic inductive charging emulator
- Complete vehicle integration and validation of 200 kW dynamic wireless EV charging system
- Integrate INL's passive EM-field shielding solution with ORNL's 200kW DWPT system
- Complete analysis of impact of DWPT system on HD class 8 vehicle travel in Atlanta.

• FY 2022

- Validate and map performance of vehicle integrated 200 kW dynamic charging system at ACM

Any proposed future work is subject to change based on funding levels

Summary

- **Relevance:** Dynamic EV charging can significantly alleviate range anxiety and concurrently reduce the on-board battery requirement (weight and cost reduction)
- **Approach:**
 - Optimal range of power transfer level for feasible dynamic wireless EV charging system has been identified (150 kW – 235 kW)
 - Key R & D necessary to realize a practicable 200 kW dynamic charging system have been identified and being pursued for hardware development
 - Benchtop validation of power electronics and couplers validated to rated power thereby validating 200 kW power transferring capability
 - Dynamic inductive charging is operational and will be used to perform controlled dynamic charging tests to optimize control and efficiency
- **Technical Accomplishments:**
 - Completed high-Level cost and feasibility studies and identified architecture suitable for 200 kW DWPT
 - Completed design, development, and laboratory benchtop validation of primary and secondary side power electronics design of 200 kW DWPT system
 - Completed design, development, and validation of DWPT coils and tuning network
 - Planned for 200 kW dynamic charging tests in laboratory and for real-world validation at ACM
 - Identified and developing active and passive EM-field shielding solutions for 200kW DWPT system
 - Developing data acquisition system necessary for real-world implementation of 200 kW DWPT system
 - Analyzed Feasibility of Large-Scale Deployment of DWPT system on Primary Roadways in Atlanta
 - Developed E-Roads Tool for Analyzing Large-Scale Deployment of DWPT system on Roadways in a Region
- **Collaborations and Coordination with Other Institutions:**
 - HATCI providing an EV and support and guidance on vehicle-integration of DWPT system
 - ACM providing infrastructure and physical proving grounds for validation of 200 kW DWPT system
 - VTTI providing guidance and support to develop roadworthy DWPT coils
- **Future Work:**
 - Validate functionality of 200 kW DWPT system in laboratory
 - Demonstrate practicability by means of vehicle integrated demonstration at ACM

Any proposed future work is subject to change based on funding levels