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# VOLTTRON: Development Primer

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# Installing the Platform

- ▶ Clone project from Git: <https://github.com/VOLTTRON/volttron.git>
- ▶ Run: `./bootstrap`
  - Can take some time
- ▶ Launch platform
- ▶ Build and deploy ListenerAgent
  - `volttron/scripts/build-agent.sh ListenerAgent`
  - `chmod +x Agents/listeneragent-0.1-py2.7.egg`
  - `bin/volttron-ctrl install-executable Agents/listeneragent-0.1-py2.7.egg`
  - `bin/volttron-ctrl load-agent Agents/ListenerAgent/listeneragent.launch.json`
  - `bin/volttron-ctrl start-agent listeneragent.launch.json`
  - To see that it's running: `bin/volttron-ctrl list-agents`
  - Publishes a heartbeat message
  - Subscribes to all messages

# Drivers

```
1 Point Name,PNNL Point Name,Units,Units Details,Modbus Register,Writable,Point Address,Notes
2 CO2Sensor,ReturnAirCO2,PPM,0.00-2000.00,>f,FALSE,1001,CO2 Reading 0.00-2000.0 ppm
3 FanSpeed,SupplyFanSpeed,%,0.00 to 100.00,>f,FALSE,1003,Fan speed from drive
4 Cool1Spd,CoolSupplyFanSpeed1,%,0.00 to 100.00 (75 default),>f,TRUE,1005,Fan speed on cool 1 call
5 Cool2Spd,CoolSupplyFanSpeed2,%,0.00 to 100.00 (90 default),>f,TRUE,1007,Fan speed on Cool2 Call
6 DaTemp,DischargeAirTemperature,F,(-)39.99 to 248.00,>f,FALSE,1009,Discharge air reading
7 CO2Stpt,ReturnAirCO2Stpt,PPM,1000.00 (default),>f,TRUE,1011,Setpoint to enable demand control ventilatio
8 ESMEconMin,ESMDamperMinPosition,%,0.00 to 100.00 (5 default),>f,TRUE,1013,Minimum damper poistion during
9 FanPower,SupplyFanPower, kW,0.00 to 100.00,>f,FALSE,1015,Fan power from drive
10 Heat1Spd,HeatSupplyFanSpeed1,%,0.00 to 100.00 (75 default),>f,TRUE,1017,Fan speed on heat 1 Call
```

- ▶ Modbus and BACnet drivers use a CSV file to specify points and names
- ▶ Initial BACnet driver can be created using a configuration grabbing utility
- ▶ No additional code needed for devices using these protocols

<https://github.com/VOLTTRON/volttron/wiki/BacnetDriver>  
<https://github.com/VOLTTRON/volttron/wiki/ModbusDriver>

# sMAP Driver

```
[[report 0]
  ReportDeliveryLocation = http://_____ /backend/add/g
[/]
  type = Collection
  Metadata/SourceName = Jereme's Test Transactional Network
  uuid =
[/datalogger]
  type = volttron.drivers.data_logger.DataLogger
  interval = 1
[/LBNL]
  type = Collection
  Metadata/Location/Campus = LBNL
[/LBNL/Building46]
  type = Collection
  Metadata/Location/Building = Building 46
[/LBNL/Building46/RTU1]
  type = volttron.drivers.modbus.Modbus
  ip_address =
  port=502
  slave_id = 8
  interval = 60
  register_config = /home/kyle/workspace/rtunetwork/volttron/drivers/catalyst372.csv
```

- ▶ sMAP Driver to push collected data to historian
- ▶ Specifies topics data will be published to on Message Bus

<https://github.com/VOLTTRON/volttron/wiki/BacnetDriver>  
<https://github.com/VOLTTRON/volttron/wiki/ModbusDriver>

# ListenerAgent Walkthrough

- ▶ ListenerAgent – Simple agent which publishes a heartbeat and listens to all messages. Useful for testing install and listening to agents being developed.

- BaseAgent

- Init
- Setup
- Loop
- Etc.

- PublishMixin

- Topic Matching

- Matching.py

```
class ListenerAgent(PublishMixin, BaseAgent):
    """Listens to everything and publishes a heartbeat according to the
    heartbeat period specified in the settings module.
    """

    def __init__(self, config_path, **kwargs):
        super(ListenerAgent, self).__init__(**kwargs)
        self.config = utils.load_config(config_path)

    def setup(self):
        # Demonstrate accessing a value from the config file
        _log.info(self.config['message'])
        self.agent_id = self.config['agentid']
        # Always call the base class setup()
        super(ListenerAgent, self).setup()

    @matching.match_all
    def on_match(self, topic, headers, message, match):
        """Use match_all to receive all messages and print them out."""
        _log.debug("Topic: {topic}, Headers: {headers}, "
                  "Message: {message}".format(
                      topic=topic, headers=headers, message=message))

    # Demonstrate periodic decorator and settings access
    @periodic(settings.HEARTBEAT_PERIOD)
    def publish_heartbeat(self):
        """Send heartbeat message every HEARTBEAT_PERIOD seconds.

        HEARTBEAT_PERIOD is set and can be adjusted in the settings module.
        """
        now = datetime.utcnow().isoformat(' ') + 'Z'
        headers = {
            'AgentID': self._agent_id,
            headers_mod.CONTENT_TYPE: headers_mod.CONTENT_TYPE.PLAIN_TEXT,
            headers_mod.DATE: now,
        }
        self.publish('heartbeat/Listeneragent', headers, now)

def main(argv=sys.argv):
    """Main method called by the eggsecutable."""
    try:
        utils.default_main(ListenerAgent,
                           description='Example VOLTRON Lite™ heartbeat agent',
                           argv=argv)
    except Exception as e:
        _log.exception('unhandled exception')

if __name__ == '__main__':
    # Entry point for script
    try:
        sys.exit(main())
    except KeyboardInterrupt:
        pass
```

# Scheduler

```
def publish_schedule(self):  
    headers = {  
        'AgentID': self._agent_id,  
        'type': 'NEW_SCHEDULE',  
        'requesterID': self._agent_id, #The name of the requesting agent.  
        'taskID': self._agent_id + "-TASK", #The desired task ID for this task.  
        #It must be unique among all other scheduled tasks.  
        'priority': 'LOW', #The desired task priority, must be 'HIGH', 'LOW', or 'LOW_PREEMPT'  
    }  
  
    msg = [  
        ["campus/building/device1", #First time slot.  
         "2014-1-31 12:27:00", #Start of time slot.  
         "2014-1-31 12:29:00"], #End of time slot.  
        ["campus/building/device1", #Second time slot.  
         "2014-1-31 11:26:00", #Start of time slot.  
         "2014-1-31 11:30:00"], #End of time slot.  
        ["campus/building/device2", #Third time slot.  
         "2014-1-31 12:30:00", #Start of time slot.  
         "2014-1-31 12:32:00"], #End of time slot.  
        #etc...  
    ]  
    self.publish_json(topics.ACTUATOR_SCHEDULE_REQUEST, headers, msg)
```

- ▶ Steps for using Scheduler
  - Publish schedule request
  - Get success/error
  - If success, wait for schedule announce and then take action via Actuator
- ▶ Priorities
  - High, Low, Low\_Preempt

# Actuator

```
def command equip(self, point_name, value, timeout=None):
    _log.debug('set_point({}, {}, {})'.format(point_name, value, timeout))
    headers = {
        'Content-Type': 'text/plain',
        'requesterID': agent_id,
    }
    self.publish(topics.ACTUATOR_SET(point=point_name, **rt_path),
                 headers, str(value))
    try:
        return self.value_queue.wait(timeout)
    except green.Timeout:
        return True
```

- ▶ Listen for schedule announce
- ▶ Send command
- ▶ Listen for error
- ▶ Check that value changed

# Weather

```
{
  "agent": {
    "exec": "weatheragent-.1-py2.7.egg --config \"%c\" --sub \"%s\" --pub \"%p\"**
  },
  "agentid": "Weather1",
  "poll time": 600,
  "minute_threshold" : 5,
  "daily_threshold" : 200,
  "zip" : "99352"
}
```

```
weather/location/display_location/elevation, Headers: Headers({u'Content-type': u'text/plain', u'From': u'Weather1'}), Message: ['121.00000000']
weather/location/local_tz_long, Headers: Headers({u'Content-Type': u'text/plain', u'From': u'Weather1'}), Message: ['America/Los Angeles']
weather/location/observation_location/all, Headers: Headers({u'From': u'Weather1', u'Content-Type': [u'application/json']}), Message: ['"{\\"cit
weather/location/observation_location/city, Headers: Headers({u'Content-Type': u'text/plain', u'From': u'Weather1'}), Message: ['Cottonwood, Ric
weather/location/observation_location/full, Headers: Headers({u'Content-Type': u'text/plain', u'From': u'Weather1'}), Message: ['Cottonwood, Ric
weather/location/observation_location/elevation, Headers: Headers({u'Content-Type': u'text/plain', u'From': u'Weather1'}), Message: ['407 ft']
weather/location/observation_location/country, Headers: Headers({u'Content-Type': u'text/plain', u'From': u'Weather1'}), Message: ['US']
weather/location/observation_location/longitude, Headers: Headers({u'Content-Type': u'text/plain', u'From': u'Weather1'}), Message: ['-119.30519
weather/location/observation_location/state, Headers: Headers({u'Content-Type': u'text/plain', u'From': u'Weather1'}), Message: ['Washington']
weather/location/observation_location/country_iso3166, Headers: Headers({u'Content-Type': u'text/plain', u'From': u'Weather1'}), Message: ['US']
weather/location/observation_location/latitude, Headers: Headers({u'Content-Type': u'text/plain', u'From': u'Weather1'}), Message: ['46.286606']
weather/location/station_id, Headers: Headers({u'Content-Type': u'text/plain', u'From': u'Weather1'}), Message: ['KWAAT0041']
```

- ▶ Obtain WeatherUnderground key
- ▶ Edit settings.py to use that key
- ▶ Agent publishes all weather data from the site for a given zipcode
- ▶ Serves as an example for a proxy agent



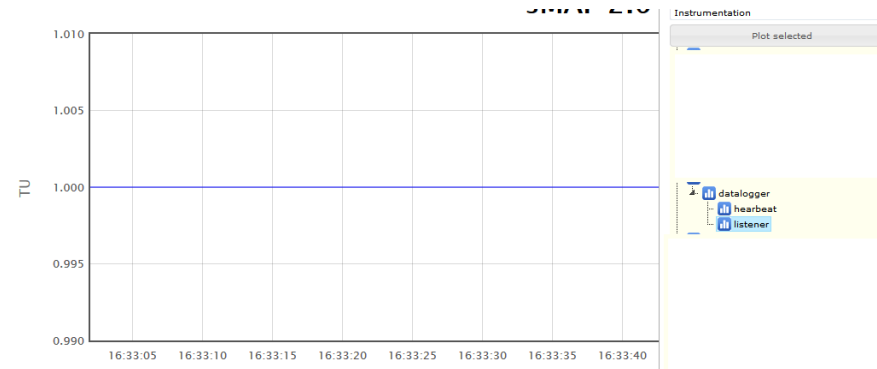
# Logging

```
headers = {}
headers[headers_mod.FROM] = self.agent_id
headers[headers_mod.CONTENT_TYPE] = headers_mod.CONTENT_TYPE.JSON

mytime = int(time.time())

content = {
    "listener": {
        "Readings": [[mytime, 1.0]],
        "Units": "TU",
        "data_type": "double"
    },
    "heartbeat": {
        "Readings": [[mytime, 1.0]],
        "Units": "TU",
        "data_type": "double"
    }
}

self.publish('datalogger/log/', headers, json.dumps(content))
```



- ▶ Publish message to the logging topic
  - Topic after /log/ used in point or defaults to /datalogger
- ▶ Dynamically creates topics as needed

# Archiver

- ▶ Publish request to archiver topic
  - Point
  - Timerange
  - Note: best to chunk large requests
  - `publish('archiver/request/campus1/building1/realcatalyst1/CoolCall1',{},'now - 1h, now')`  
`publish('archiver/request/campus1/building1/realcatalyst1/CoolCall1',{},'1374192541000.0, 1374193541000.0')`
- ▶ Receive answer on response topic in a list of time/value pairs
  - `[[1371851254000.0,1.0],[1371851314000.0,1.0],[1371851374000.0,1.0]]`

# Multi-Node

```
{
  "agent": {
    "exec": "multibuildingagent-0.1-py2.7.egg --config \"%c\" --sub \"%s\" --pub \"%p\""
  },

  "building-publish-address" : "tcp://0.0.0.0:12201",
  "building-subscribe-address" : "tcp://0.0.0.0:12202",

  "hosts": {"PNNL/hardware1": {"pub": "tcp://xxx.xxx.xxx.xxx:12201",
                                "sub": "tcp://xxx.xxx.xxx.xxx:12202"},
            "PNNL/hardware2": {"pub": "tcp://yyy.yyy.yyy.yyy:12201",
                                "sub": "tcp://yyy.yyy.yyy.yyy:12202"},
            "PNNL/hardware3": {"pub": "tcp://zzz.zzz.zzz.zzz:12201",
                                "sub": "tcp://zzz.zzz.zzz.zzz:12202"},
            "PNNL/hardware4": {"pub": "tcp://aaa.aaa.aaa.aaa:12201",
                                "sub": "tcp://aaa.aaa.aaa.aaa:12202"}
          },

  "uuid" : "MultiBuilding"
}
```

- ▶ MultiBuildingAgent provides multi-node communication
  - Listens on it's own pub/sub channels and passes messages between platforms
  - Can be encrypted

# VOLTRON 2.0 Changes

- ▶ Optional Features:
  - Resource Management
  - Agent signature validation
- ▶ Packing format changed to Wheel
- ▶ New configuration file and options
- ▶ New command structure

# FY15 Plans

- ▶ Centralized Management Console
- ▶ Enhanced modularization to easily swap out different component implementations
- ▶ Supervisory Agent
  - Monitor other platforms
  - Return appliances to a known state in case of abnormal agent condition
- ▶ Scalability Study
  - Investigate large scale deployment of platform
- ▶ Penetration Testing and Security Enhancements

# Resources

- ▶ VOLTTRON Resources
  - Wiki: <https://github.com/VOLTTRON/volttron/wiki>
  - Email: [voltron@pnnl.gov](mailto:voltron@pnnl.gov)
- ▶ If you are interested please contact us to be added to:
  - Mailing list: [voltron-dev@lyris.pnnl.gov](mailto:voltron-dev@lyris.pnnl.gov)
  - Office hours
    - Twice monthly telecon with VOLTTRON development team



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