

Advanced Grid Modeling 2014 Peer Review

GridPACK™ Framework for Developing Power Grid Applications on High Performance Computing Architectures

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Advancement is needed in grid modeling

- ➤ The power grid, despite it size and complexity, is still being modeled primarily using workstations
- Serial codes are limited by memory and processor speed, and this limits the size and complexity of existing models
- Modeling large systems using small computers involves substantial aggregation and approximations
- ➤ Parallel computing can potentially increase memory and computing power by orders of magnitude, thereby increasing the size and complexity of power grid models that can be simulated using computing
- ➤ Parallel computing is more complex than writing serial code and the investment costs are relatively high
- Parallel software is a rapidly changing field and keeping up with new developments can be both expensive and time consuming

Outline

- **≻**Objectives
- **≻**Impact
- ➤ GridPACK™ Framework
- > Performance Results

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Objectives

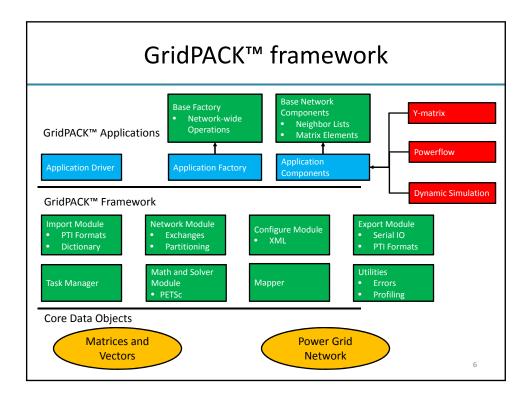
- Simplify development of HPC codes for simulating power grid
- Create high level abstractions for common programming motifs in power grid applications
- ➤ Incapsulate high performance math libraries and make these available for power grid simulations
- Promote reuse of power grid software components in multiple applications to reduce development and maintenance costs
- Incorporate as much communication and indexing calculations as possible into high level abstractions to reduce application development complexity
- Compartmentalize functionality to reduce maintenance and development costs

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Impact

- Access to larger computers with more memory and processing power
- Models containing larger networks and higher levels of detail can be simulated
- Reduced time to solution
- Greater capacity for modeling contingencies and quantifying uncertainty

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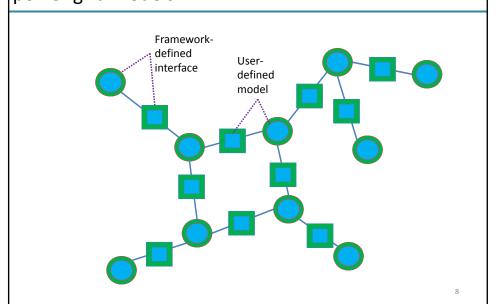


GridPACK™ network module

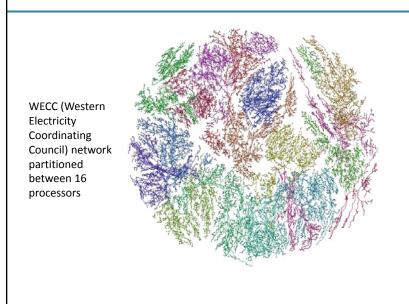
- Network: Manages the topology and partitioning of the network
 - Provides a framework for inserting application specific bus and branch models
 - Keeps track of neighbor relationships
 - Partitions network between processors (the partitioner is built on top of the Parmetis library)
 - Manages ghost buses and branches representing parts of the network on other processors and implements data exchanges between processors

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Network component templates to describe arbitrary power grid models



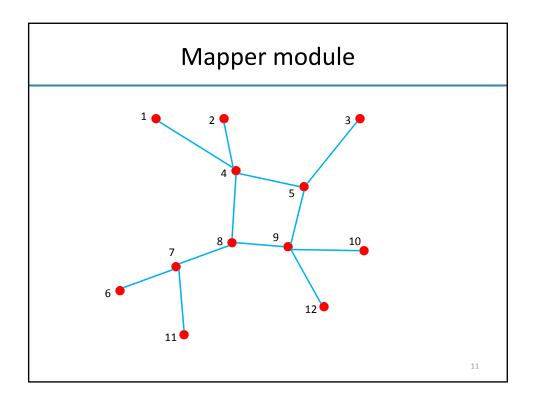
Partition of the WECC network

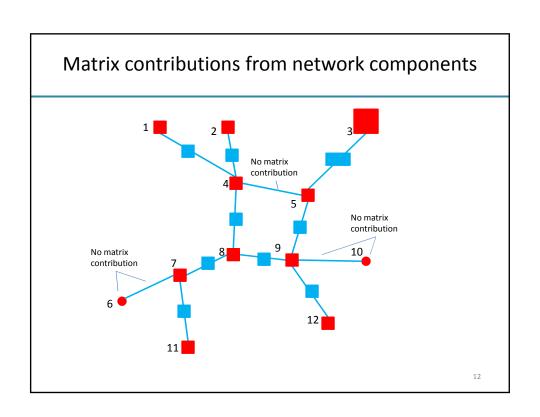


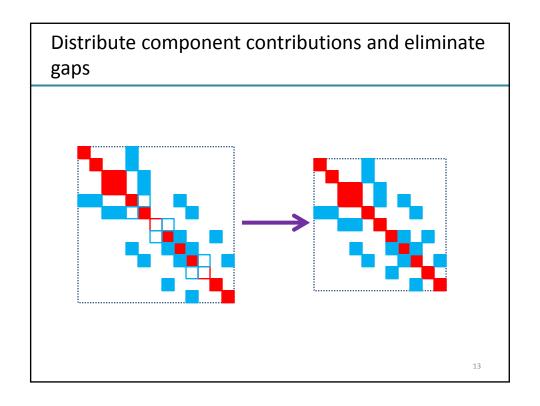
Mapper module

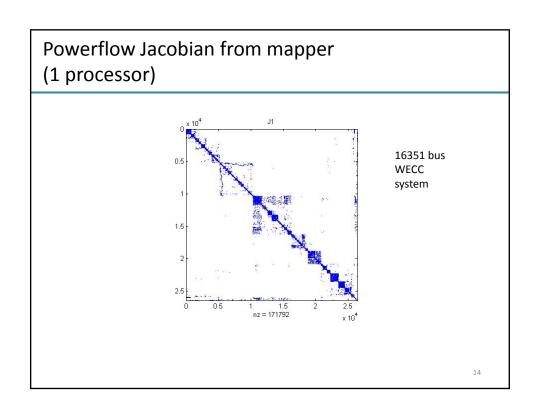
- Generic tool for generating vectors and matrices from network components (buses and branches)
 - Network components are responsible for evaluating their local contributions to vector or matrix
 - Calculations are usually simple and involve only elements that are immediately connected to the contributing component
 - Mapper is responsible for identifying the global location of the contribution in the matrix

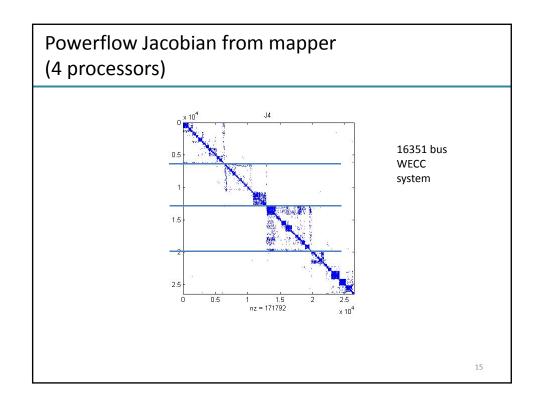
$$Y_{ii} = -\sum_{j} Y_{ij}$$
 Sum over branches to get bus entry

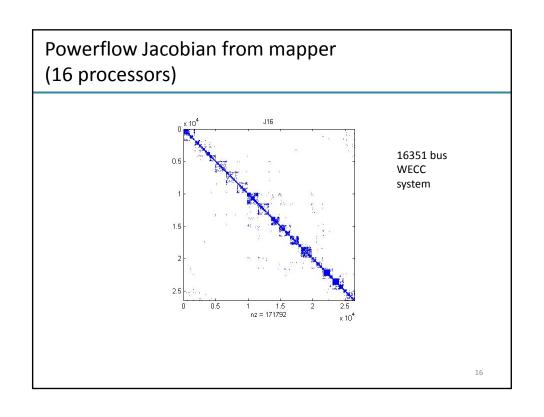












Other modules

- Math: Provide high level abstractions for distributed matrices and vectors
 - Built on top of PETSc math libraries
 - Creation of distributed matrices and vectors
 - Access to the complete suite of linear and non-linear solvers in PETSc
 - Supports basic algebraic operations (matrix-vector multiply, transpose, etc.)
- > Factory
 - Implements operations that run over entire network
 - Initializations, function evaluations on all buses and branches, etc.
- Parser: ingest network from external configuration file
 - Currently supports PTI v23 format, other formats are being developed
- Output
 - Organizes output from buses and branches in a consistent manner

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Applications

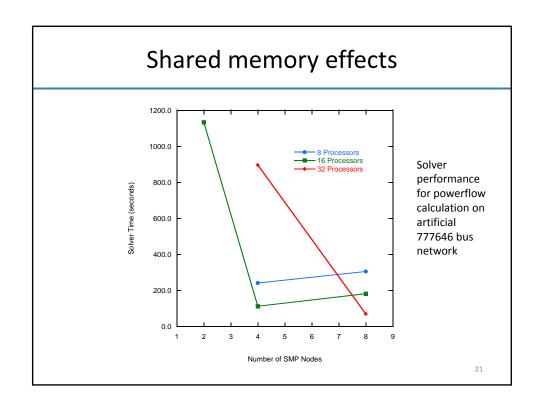
- Powerflow
 - Demonstrates basic functionality of GridPACK™, including networks, mappers and solvers
 - Hand-coded Newton-Raphson loop and non-linear solver implementation
- > Dynamic simulation
 - Dense matrices
 - Algebraic manipulations
 - Local modifications of matrices
- Static Contingency Analysis
 - Managing multiple independent tasks
- Dynamic Contingency Analysis
 - Multiple levels of parallelism

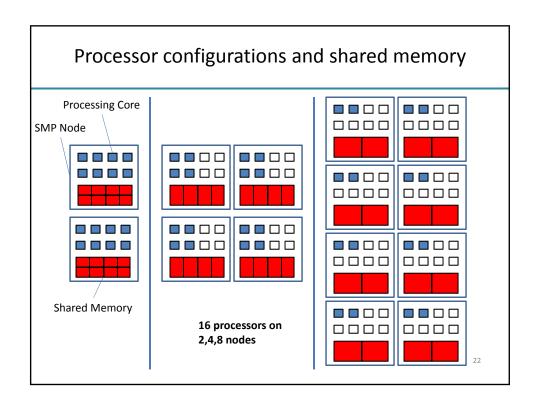
Performance results

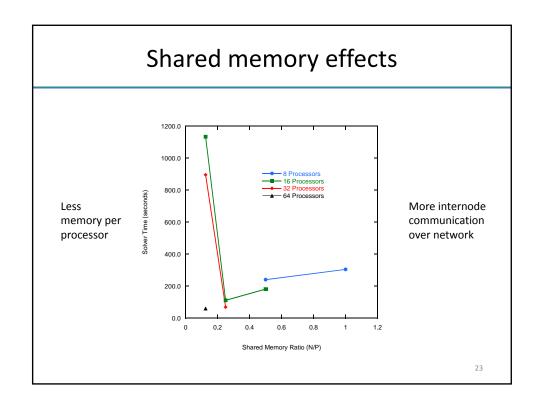
- **≻** Applications
 - Powerflow
 - Dynamic Simulation
 - Dynamic Contingency Analysis
- ➤ Strong scaling performance
 - Fixed size problem, increasing number of processors

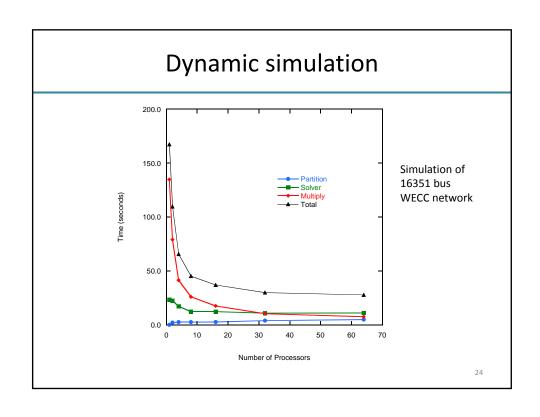
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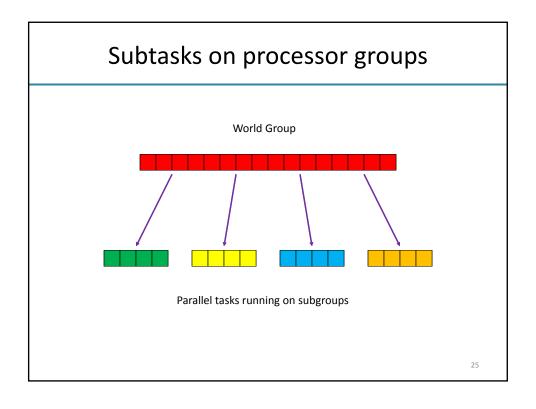
Powerflow scaling for artificial 777646 bus network A00.0 A00.0

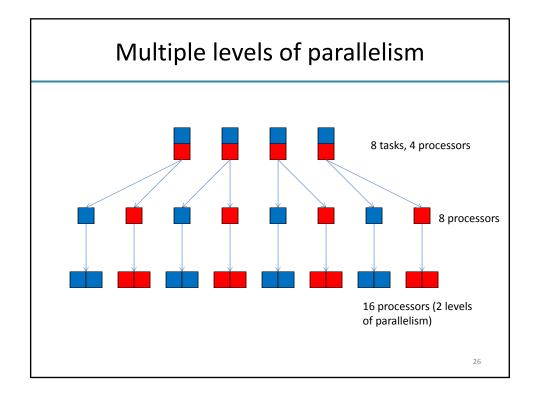


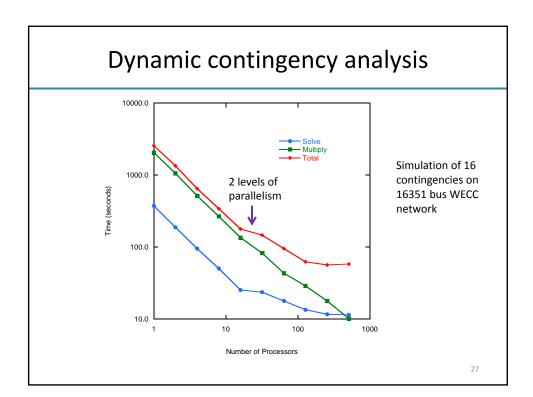












Development team

- > Bruce Palmer (PI): Parallel code development
- > William Perkins: Parallel code development
- Yousu Chen: Power grid application development
- Shuangshuang Jin: Power grid application development
- > David Callahan: Data integration
- Kevin Glass: Data integration and optimization
- ➤ Ruisheng Diao: Power grid engineering and model validation
- Stephen Elbert: Optimization and economic modeling
- Mallikarjuna Vallem: Synthetic data and model validation
- Nathan Tenney: Automatic builds and testing
- Zhenyu (Henry) Huang: Program management

Conclusion

- ➤ GridPACK[™] has been successfully deployed and is available to the public at https://gridpack.org, along with documentation
- ➤ Multiple demonstration programs of power grid applications have been developed with GridPACK[™] and have shown scaling behavior. These include
 - Powerflow
 - Dynamic Simulation
 - Static Contingency Analysis
 - Dynamic Contingency Analysis
- Development of state estimation calculation and Fortran interface is underway
- ➤ Mini-tutorial at 3rd at Workshop on Next-Generation Analytics for the Future Power Grid, PNNL, Richland, WA, July 17-18, 2014

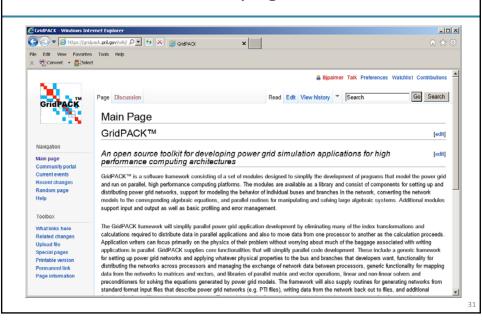
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Contacts

Bruce Palmer (PI): bruce.palmer@pnnl.gov

GridPACK™ webpage: https://gridpack.org

Webpage



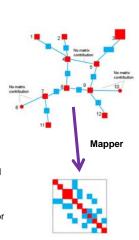
GridPACK™ Toolkit

> Research Objective:

 GridPACK[™] is a collection of modules designed to simplify the development of power grid programs that can run on today's high performance computing architectures

> Research Highlights

- Base modules for the GridPACK[™] toolkit have been developed and include
 - Network module for creating and distributing power grid network models over multiple processors
 - Network component interfaces that define how bus and branch models interact with the rest of the GridPACK™ framework
 - Math modules that support the creation of distributed matrices and vectors and implement linear and non-linear solvers
 - Mapper modules that support the creation of matrices and vectors from network models.
- Completed development of a parallel power flow, dynamic simulation and contingency analysis applications using the GridPACK™ functionality and demonstrated parallel speedup for all applications
- GridPACK[™] software is available on website https://gridpack.org, along with substantial documentation



Powerflow code

```
typdef BaseNetwork<PFBus,PFBranch> PFNetwork;
                                                                  29 shared_ptr<Vector> X(PQ->clone());
         nunicator world;
    shared ptr<PFNetwork>
                                                                  31 double tolerance = 1.0e-6;
         network(new PFNetwork(world));
                                                                  32 int max_iteration = 100;
                                                                  33 ComplexType tol = 2.0*tolerance;
    PTI23_parser<PFNetwork> parser(network);
                                                                  34 LinearSolver isolver(*J);
    parser.parse("network.raw");
                                                                  35
                                                                  36 int iter = 0;
                                                                  37
10 PFFactory factory(network);
                                                                  38 // Solve matrix equation J*X = PQ
39 isolver.solve(*PQ, *X);
40 tol = X->norm2();
11 factory.load();
12 factory.setComponents();
13 factory.setExchange();
                                                                  41
                                                                  42 while (real(tol) > tolerance &&
15 network->initBusUpdate();
                                                                  43 iter < max_iteration) {
                                                                  44 factory.setMode(RHS);
44 vMap.mapToBus(X);
16 factory.setYBus();
17 factory.setMode(YBus);
18 FullMatrixMap<PFNetwork> mMap(network);
                                                                  45 network->updateBuses();
46 factory.setMode(RHS);
47 vMap.mapToVector(PQ);
19 shared_ptr<Matrix> Y = mMap.mapToMatrix();
20
                                                                  48 factory.setMode(Jacobian);
49 jMap.mapToMatrix(J);
21 factory.setSBus();
22 factory.setMode(RHS);
22 factory.setMode(RHS);
23 BusVectorMap<PFNetwork> vMap(network);
                                                                       LinearSolver solver(*J);
24 shared_ptr<Vector> PQ = vMap.mapToVector();
26 factory.setMode(Jacobian);
                                                                  51 solver.solve(*PQ, *X);
                                                                  52 tol = X->norm2();
27 FullMatrixMap<PFNetwork> jMap(network);
                                                                       iter++;
28 shared_ptr<Matrix> J = jMap.mapToMatrix();
                                                                                                           33
```

