

Power Electronics Architecture R&D

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2013 U.S. DOE Hydrogen and Fuel
Cells Program and Vehicle
Technologies Program Annual Merit
Review and Peer Evaluation Meeting

May 14, 2013

Project ID: APE056

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or otherwise restricted information



Overview

Timeline

- Start – FY13
- Finish – FY15
- 22% complete

Budget

- Total project funding
 - DOE share – 100%
- Funding for FY13: \$ 375K

Barriers

- Boost ratio/range and efficiency that can drive dc-dc converter architectural choices,
- Potential cost addition due to choice of dc-dc converter and hybrid energy storage systems

Targets Addressed

- Traction Drive Power Electronics DOE 2020 targets
 - Power density: >13.4 kW/l
 - Specific power: >14.1 kW/kg
 - Service life: >15 years or 13000 hours

Partners

- ORNL - Burak Ozpineci, Bradley Brown, Jianlin Li, Lixin Tang, Tim Burrell, Madhu Chinthavali, Cliff White, Larry Seiber, Steven Campbell



Project Objective

• Overall Objective

- Develop a bi-directional buck/boost dc-dc converter between the regenerative energy storage systems (RESS) and the dc link (traction drive inverter),
 - Active energy management, inverter efficiency improvement, better RESS utilization.
- Design a hybrid battery/ultra-capacitor energy storage system architecture,
 - Improved regenerative braking performance, improved overall fuel economy (all-electric range), improved power density, peak power capability, and improved battery lifetime.
- Design a modular reconfigurable battery and dc-dc converter architecture,
 - Lower overall power electronics kVA rating and cost reduction on dc-dc converter.

• FY13 Objective

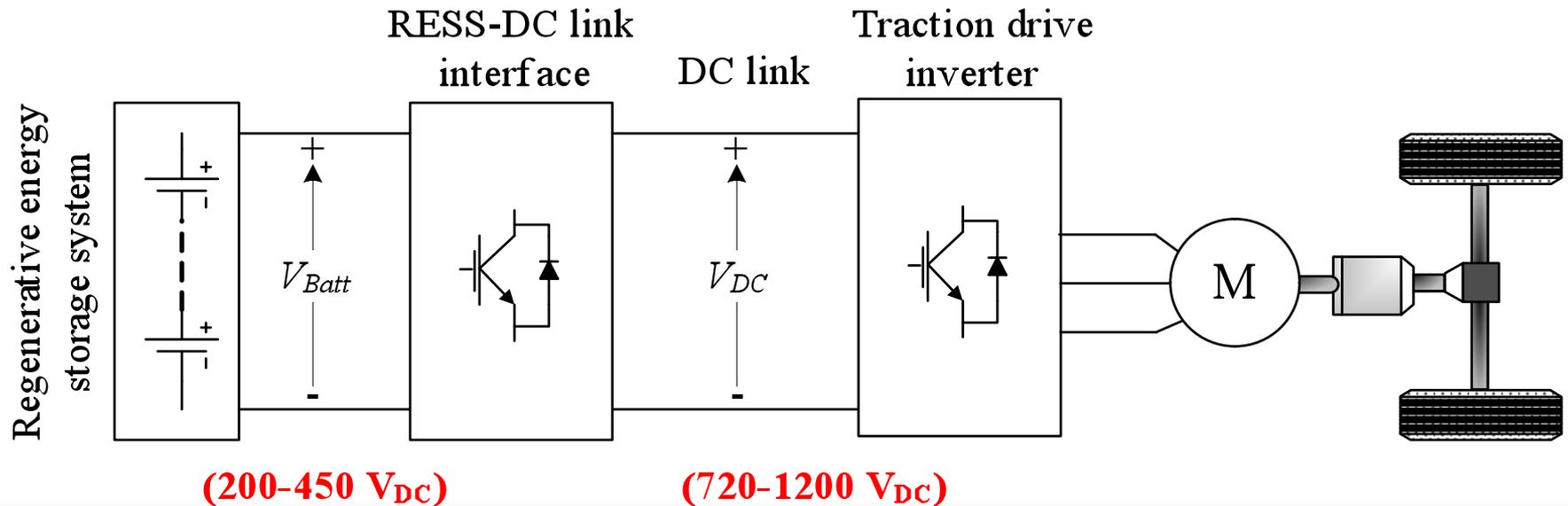
- Model, simulate, and analyze a modular reconfigurable dc-dc converter architecture.

Milestones

| Date | Milestones and Go/No-Go Decisions | Status |
|----------------|---|----------|
| April 2013 | <u>Milestone</u> : Model and simulate the modular reconfigurable dc-dc converter structures that are best utilized to meet the vehicle power demand. | On track |
| August 2013 | <u>Milestone</u> : Model and simulate various hybrid RESS architectures. | On track |
| August 2013 | <u>Go/No-Go decision</u> : <i>CHANGE if simulation results show that hybrid RESS approach outperforms the reconfigurable and modular RESS battery approach.</i> | |
| September 2013 | <u>Milestone</u> : Prepare a summary report that documents the results, findings, performance comparisons, and recommendations to be incorporated into the annual VTO report. | On track |

Approach/Strategy

- **Current State-of-the-art Traction Drive System**
 - Single battery pack utilized regardless of the power demand,
 - Single energy storage system (batteries) → Coupled power and energy requirement,
 - Regenerative Energy Storage System (RESS) - Motor drive inverter interface converter High inverter current → Lower efficiency
- **Future traction drive system layout**

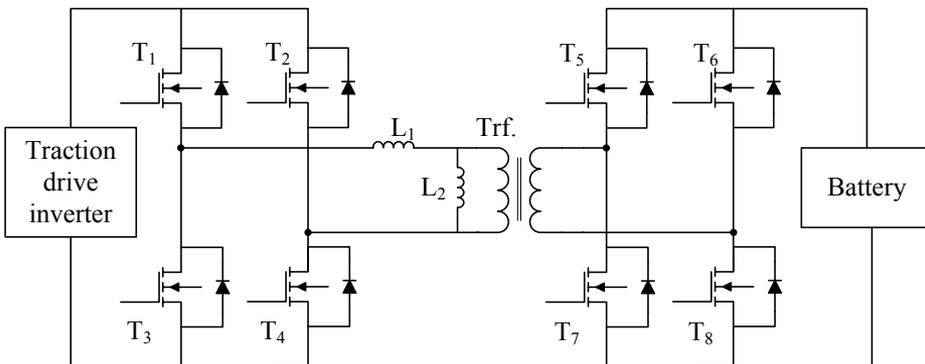


Approach/Strategy

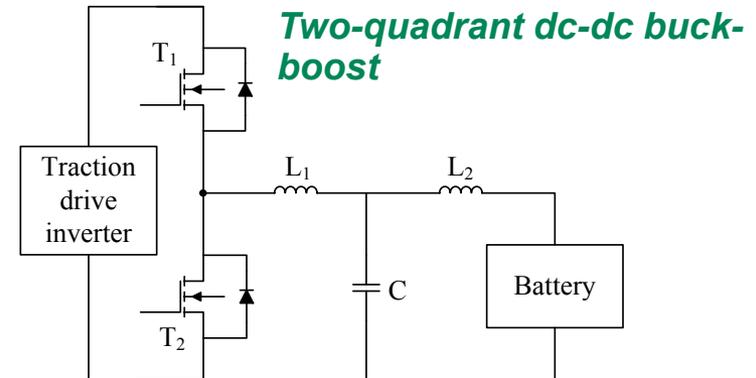
- Develop bidirectional dc-dc converter architectures:

- Dual active bridge dc-dc converter,
- Two-quadrant dc-dc buck-boost converter,
- Resonant/improved dual active bridge converter,
- Single stage dual active half-bridge dc-dc converter,
- Current boosted active clamp forward dc-dc converter,
- Bi-directional four switch buck-boost dc-dc converter,
- Bi-directional dc-dc CUK converter,
- Integrated buck/boost converter,
- Multi-phase interleaved ZVS dc-dc converter.

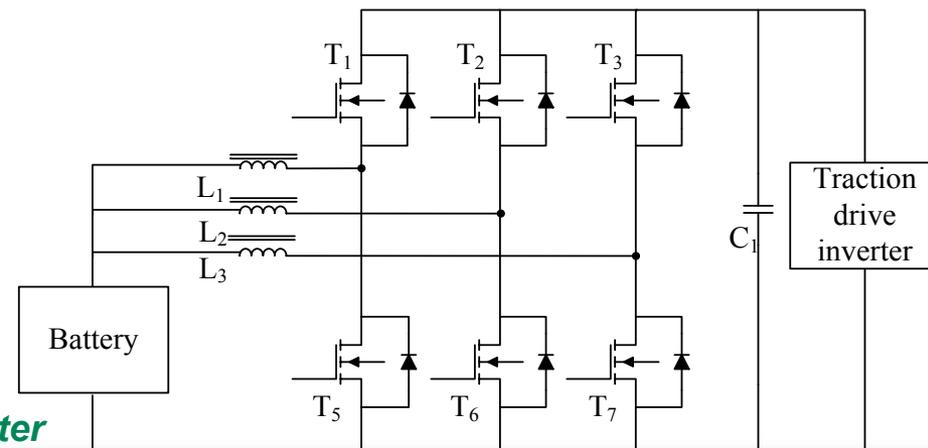
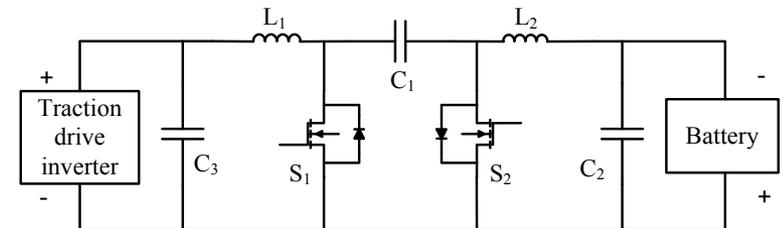
Dual active-bridge dc-dc converter



Interleaved 3-phase dc-dc converter

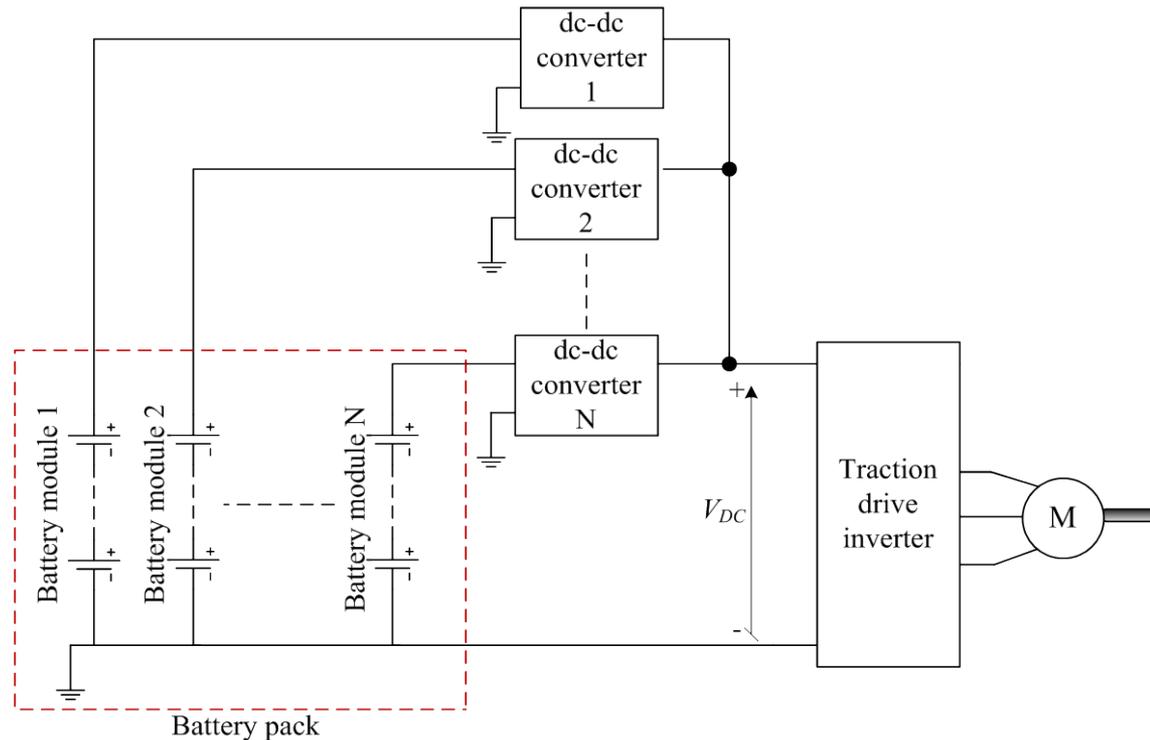


Bi-directional CUK



Approach/Strategy (Cont'd)

- Develop control systems for active energy management that have potential for cost reduction and efficiency improvement.
- The RESS and modular dc-dc converters will be best utilized to meet the vehicle power demand.
- Utilize wide bandgap devices,
- Design for lower overall kVA rating and cost,
- Improved service life,
- Reduce the thermal management burden.



Modular reconfigurable RESS and dc-dc converters

Technical Accomplishments and Progress – Overall

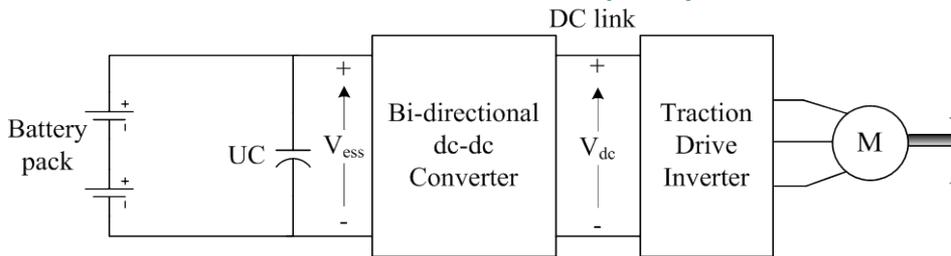
- Reviewed and modeled bi-directional dc-dc converter architectures that interface the RESS to the traction drive inverter and created a summary report discussing on the operation principles, controls, advantages and drawbacks.
- Reviewed and modeled hybrid RESS architectures and created a summary report based on the advantages, drawbacks, control systems, performance, number of parts, etc.
- Selected and modeled four battery/UC hybridization strategies.
 - Built simulation models of the battery and UC.
 - Modeled hybridization architectures.
 - Due to simulation time constraints, a portion of the UDDS drive cycle, $t=[690, 760]$ that includes acceleration, braking, and idling simulated for these hybridization architectures.
 - Collected and compared simulation results.
 - Created a comparison results table for these RESS hybridization architectures.

Technical Accomplishments and Progress

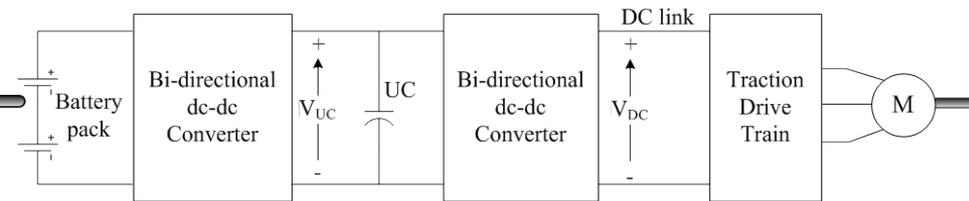
- Developed power electronic interfaces for hybrid RESS:

- Decoupled energy and power: battery/ultra-capacitor (UC)
- Active power and energy management based on the drive train power demand

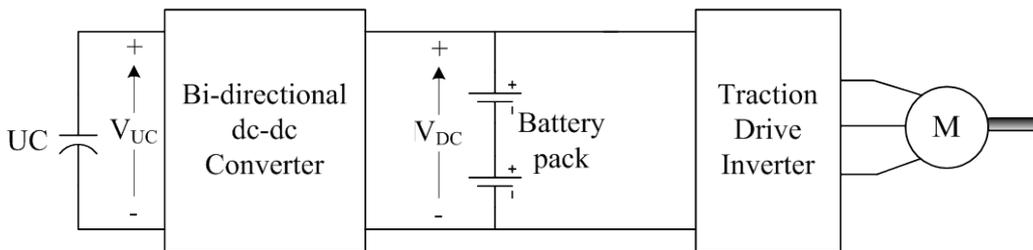
Passive Parallel Architecture (PPA)



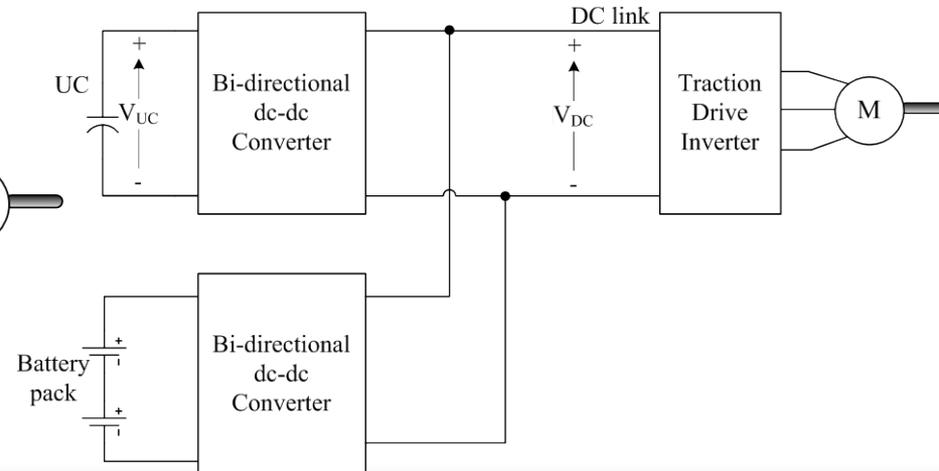
Cascaded Converters Architecture (CCA)



UC – dc-dc Converter – Battery Architecture (UCDCBA)

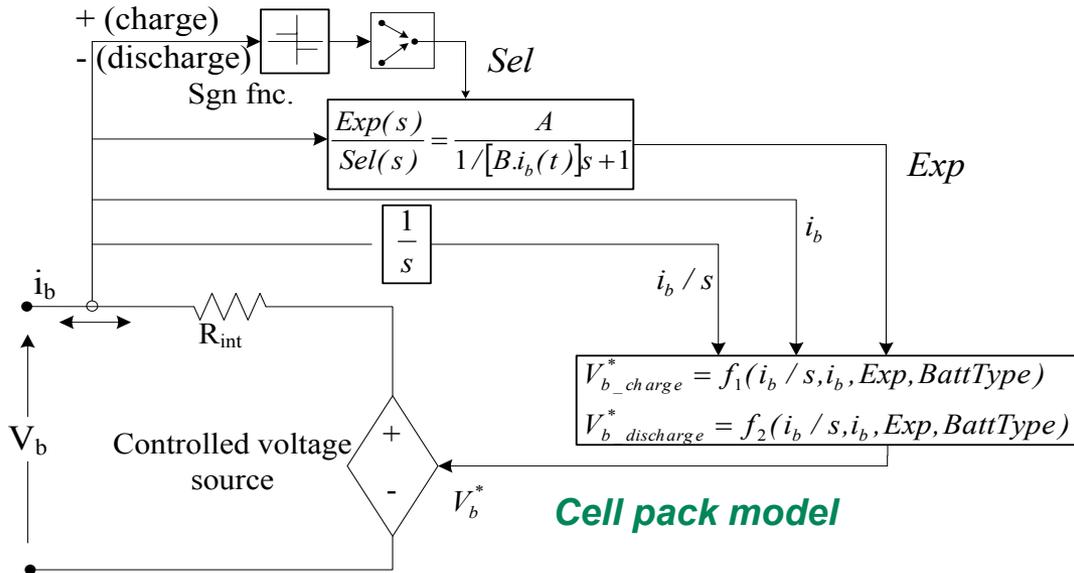


Parallel with Multi-Converters Architecture (PMCA)

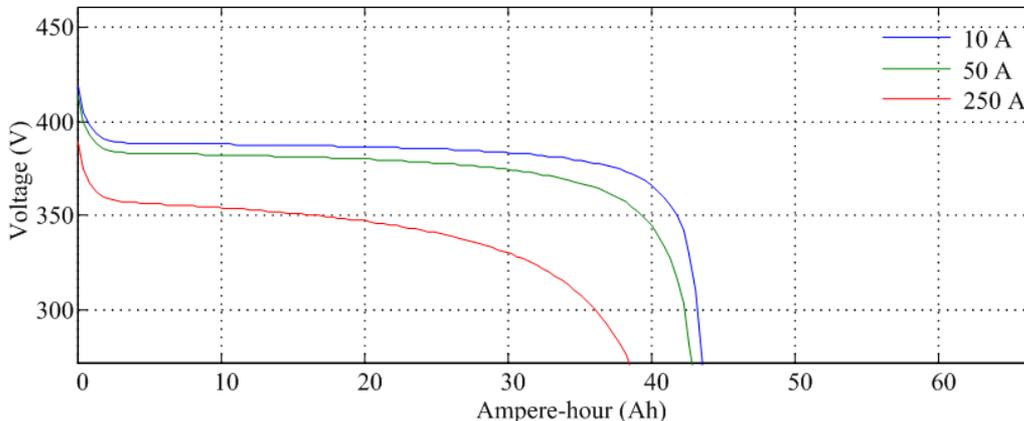


Technical Accomplishments and Progress

- Implemented a cell pack model needed in dynamic system simulations



E0 = 390.0156, R = 0.081008, K = 0.045728, A = 30.585, B = 1.374

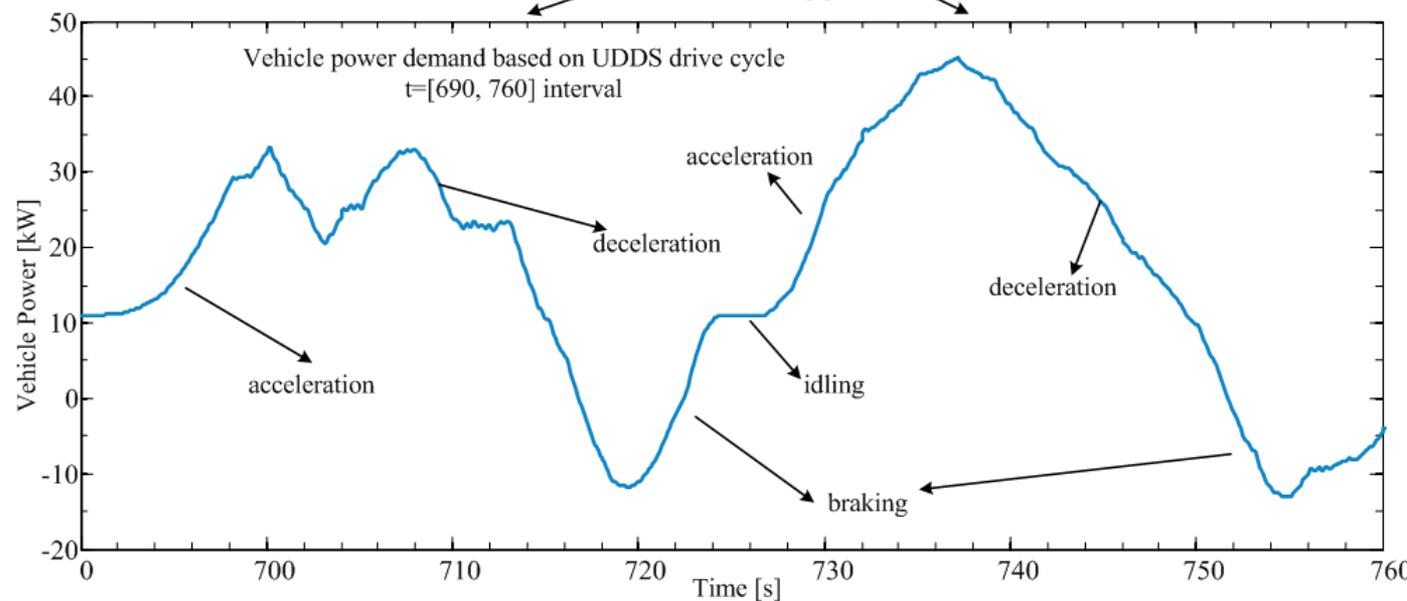
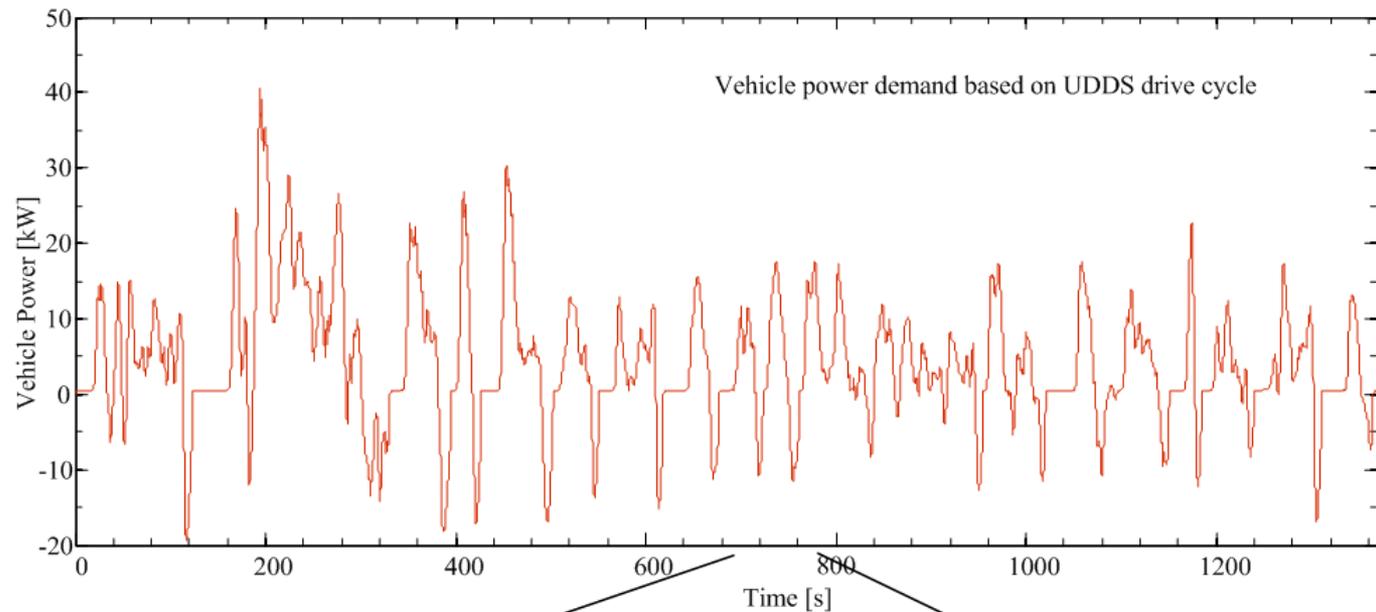


Example discharge curves

- Utilized the governing charge and discharge equations of the model
- A controlled voltage source was used (current controlled voltage source to represent $V=f(I)$ cell characteristics)
- Voltage was calculated with a non-linear equation based on the state-of-charge (SOC) of the cell; $V=f(I, SOC)$
- Reference: O. Tremblay and L. -A. Dessaint, "Experimental Validation of a Battery Dynamic Model for EV Applications," *World Electric Vehicle Journal*, vol. 3, May 13 - 16, 2009.

Technical Accomplishments and Progress

- Completed simulations for the passive parallel, cascaded, modified cascaded, and the multiple parallel converters architectures under same conditions.
- Due to simulation time constraints, a portion of the UDDS drive cycle, $t=[690, 760]$ that includes acceleration, braking, and idling simulated for these hybridization architectures.

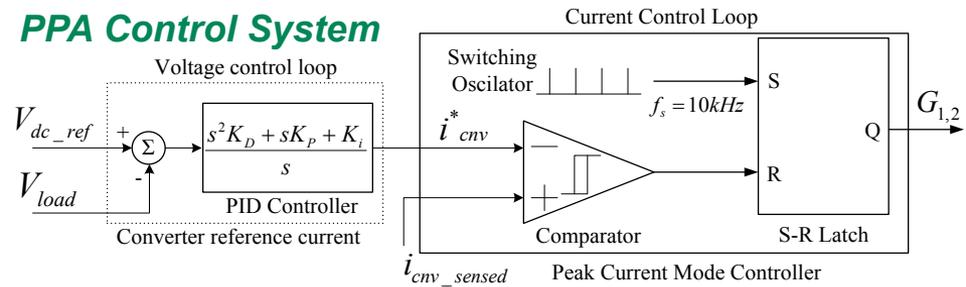


UDDS drive cycle power demand

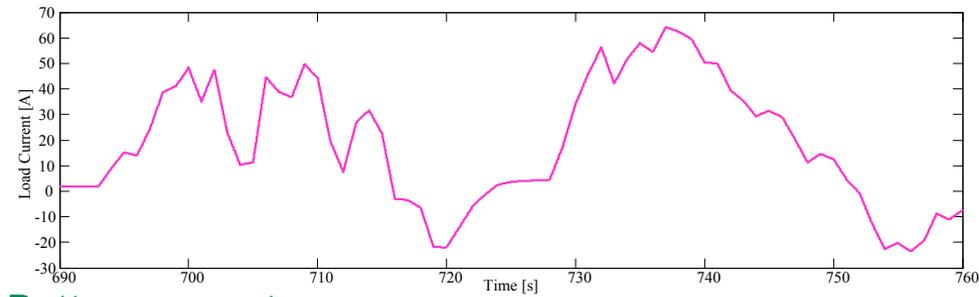
Technical Accomplishments and Progress

- Completed PPA (Passive Parallel Architecture) Simulations

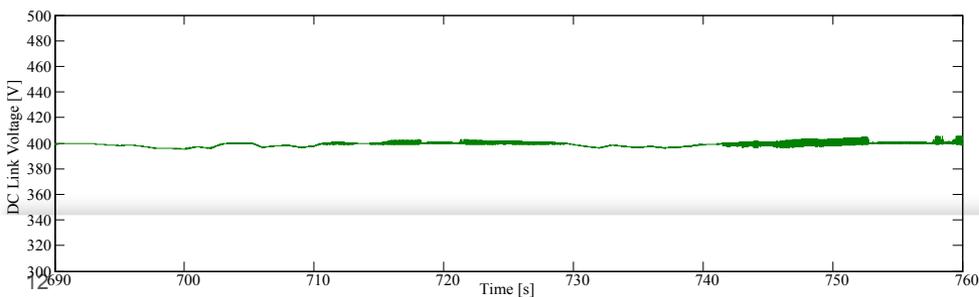
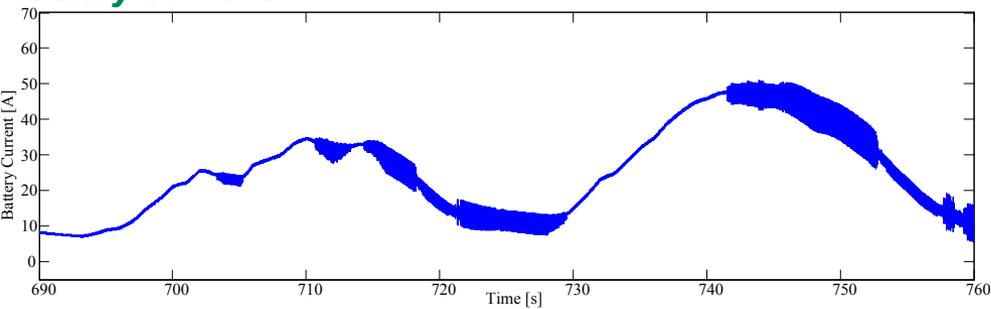
PPA Control System



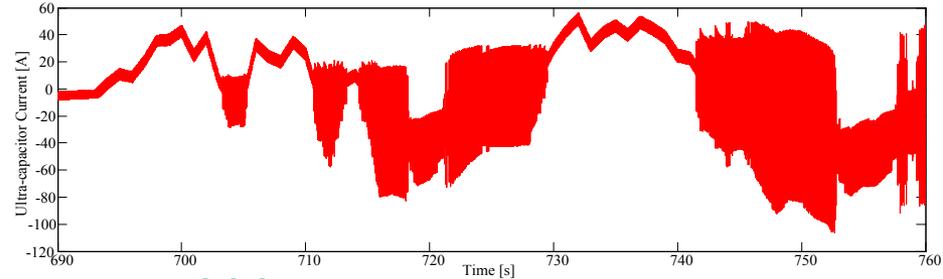
Load current



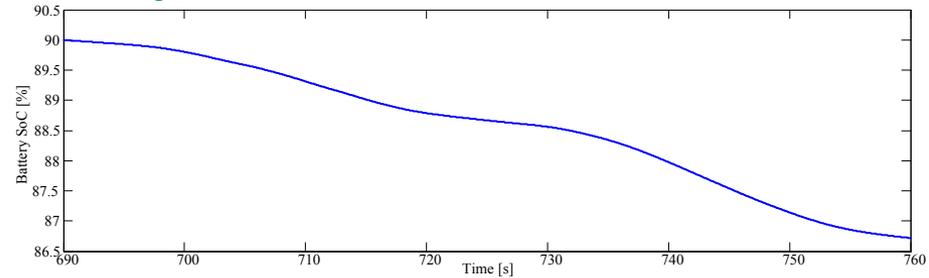
Battery current



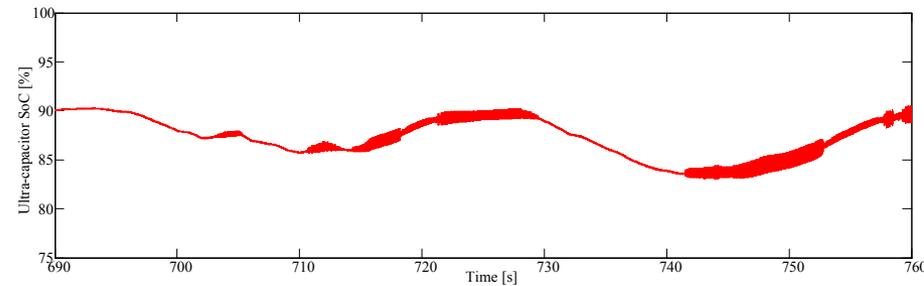
UC current



Battery SoC



UC SoC

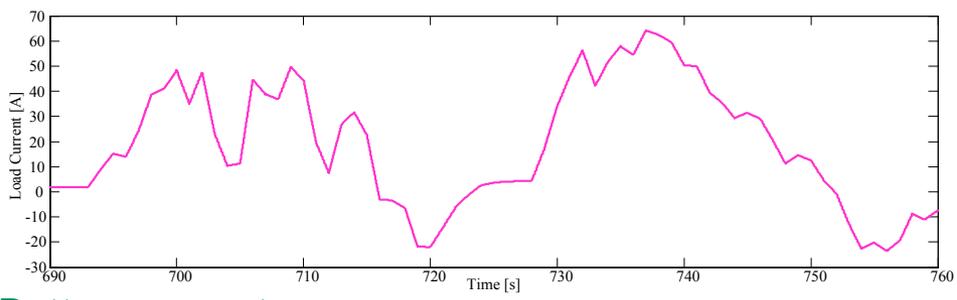


DC link voltage

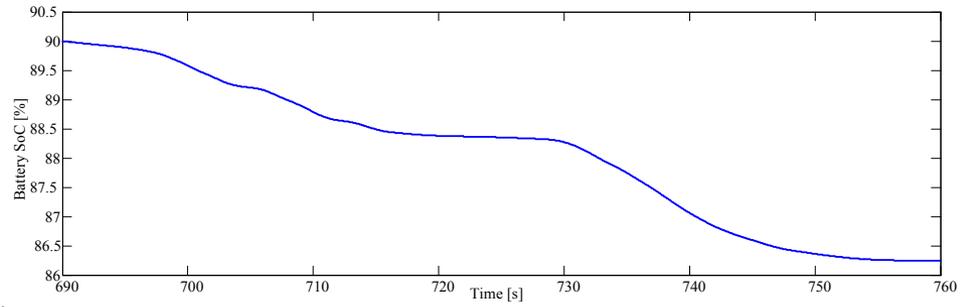
Technical Accomplishments and Progress

- Completed CCA (Cascaded Converters Architecture) Simulations

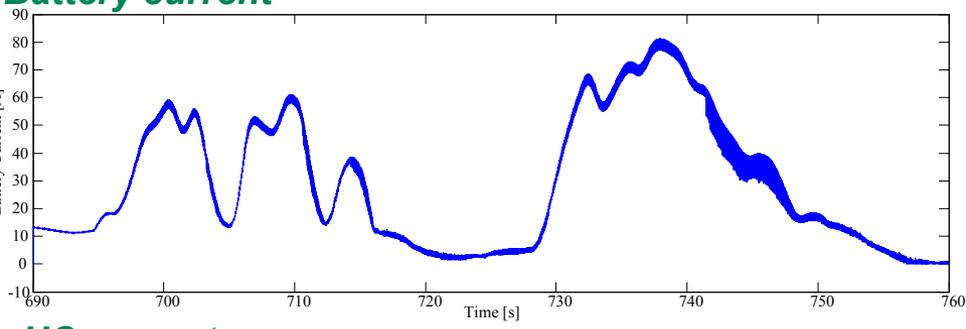
Load current



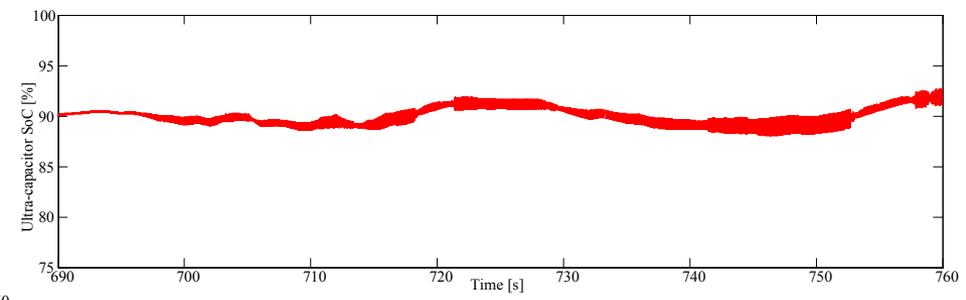
Battery SOC



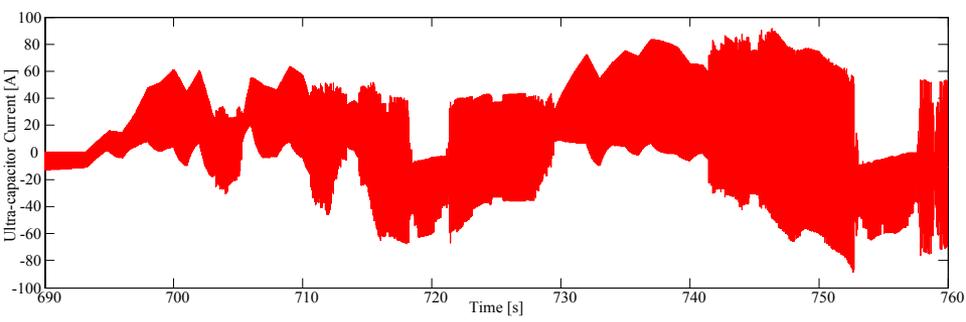
Battery current



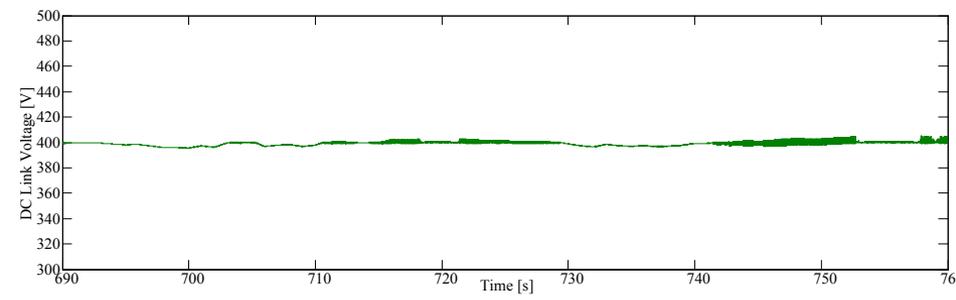
UC SOC



UC current



DC link voltage

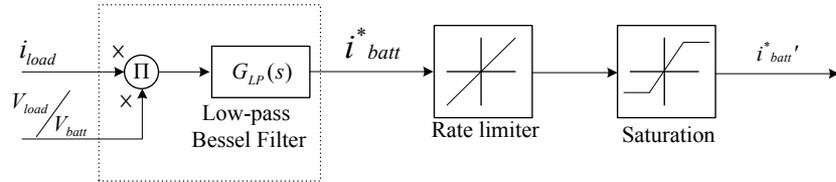


Technical Accomplishments and Progress

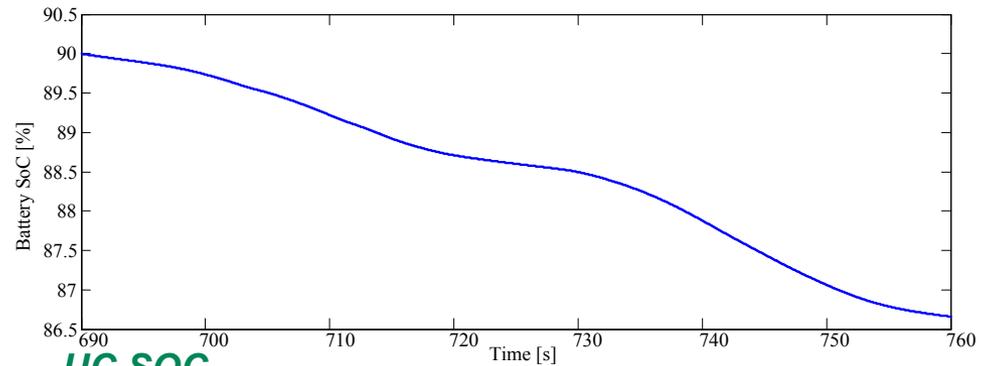
- Completed CCA (Cascaded Converters Architecture) Simulations with modified controls

CCA Modified Control System

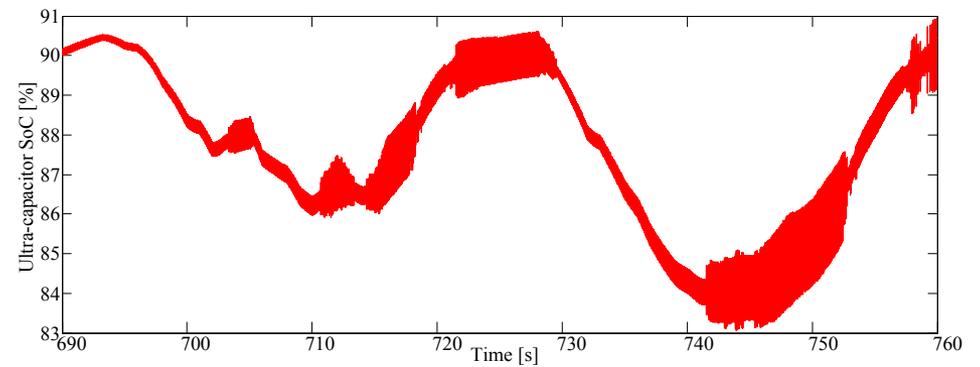
Battery reference current computation



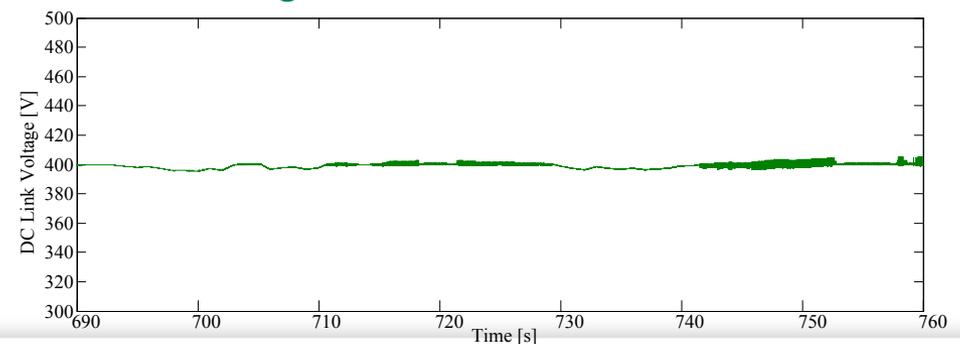
Battery SOC



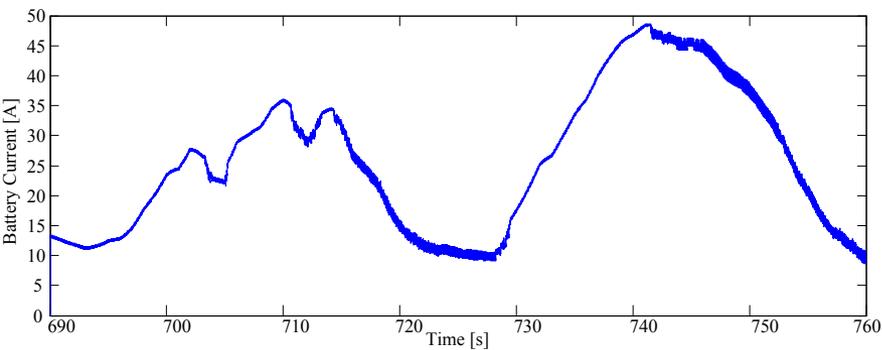
UC SoC



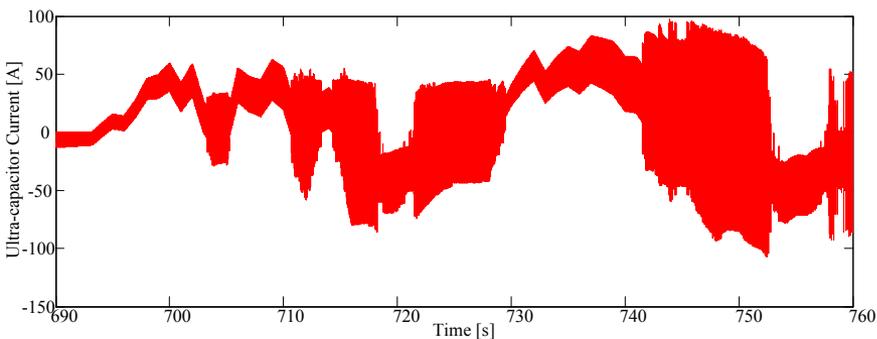
DC link voltage



Battery current



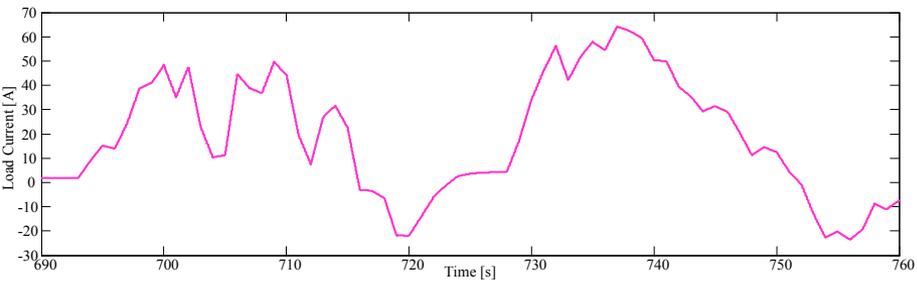
UC current



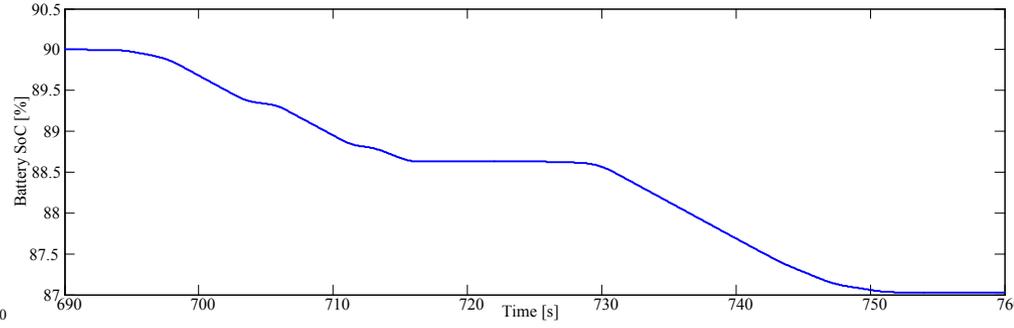
Technical Accomplishments and Progress

- Completed MPCA (Multiple Parallel Converters Architecture) Simulations

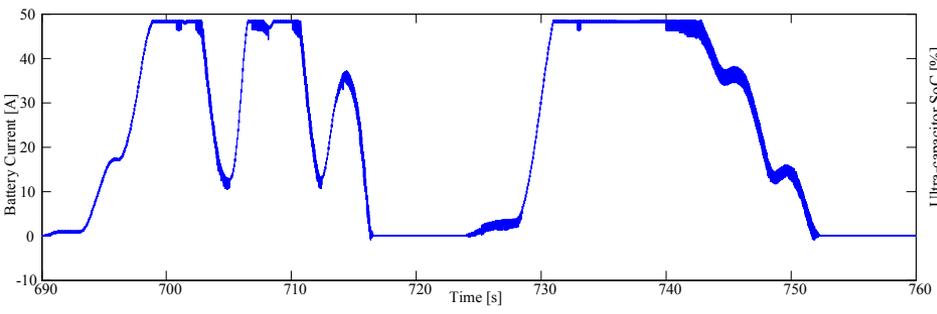
Load current



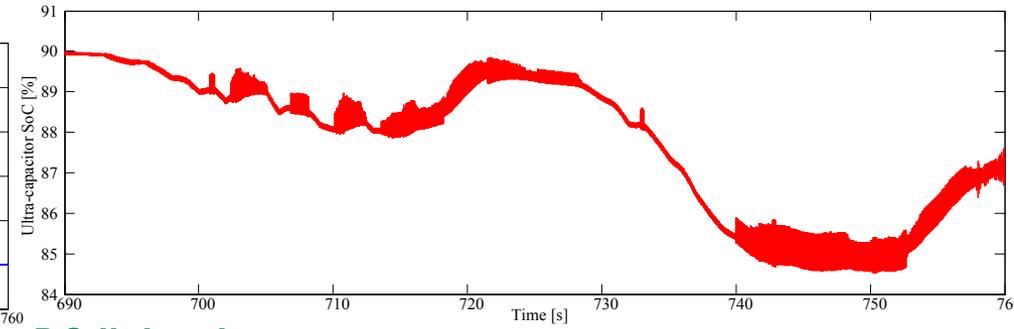
Battery SOC



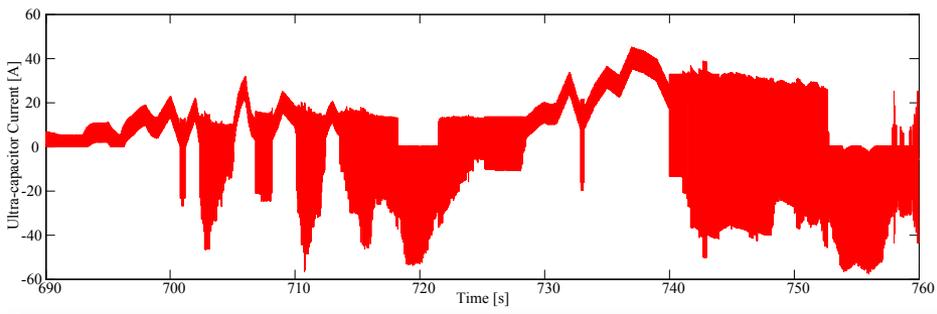
Battery current



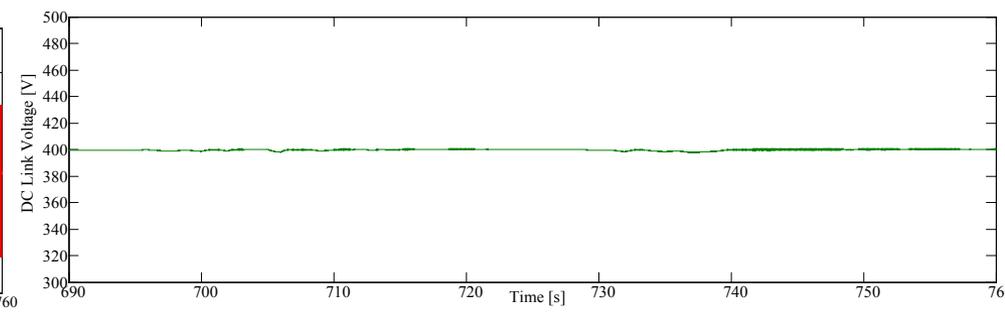
UC SOC



UC current



DC link voltage



Technical Accomplishments and Progress (Cont'd)

- Created Results Table

| Criteria | Passive Parallel (PPA) | Cascaded Converters (CCA) | Cascaded (manipulated controls) (CCA) | Parallel Converters (MPCA) |
|--|------------------------|---------------------------|---------------------------------------|----------------------------|
| Control simplicity | 1 | 2 | 3 | 3 |
| Structure complexity | 1 | 2 | 2 | 2 |
| Number of converters | 1 | 2 | 2 | 2 |
| Number of inductors | 1 | 2 | 2 | 2 |
| Total inductor mass | 2 | 3 | 3 | 2 |
| Number of transducers | 5 | 6 | 6 | 6 |
| Cycle-end battery SoC | 86.7194% | 86.2462% | 86.6598% | 87.0305% |
| Cycle-end ultra-capacitor SoC | 89.8995% | 91.9084% | 90.4502% | 87.1022% |
| Maximum battery current ripple | ~7 [A] | ~9 [A] | ~1.7 [A] | ~1.8 [A] |
| Cycle based energy efficiency (RESS and dc-dc converters combined) | 95.25% | 90.34% | 90.72% | 95.25% |
| Maximum DC link voltage variation percentage | 2.52% | 2.42% | 2.51% | 0.77% |

Conclusions

- According to the simulation results, PPA has the simplest structure and the least number of parts and components.
- The high efficiency of PPA is mainly due to the simple configuration and to the fact that there is no additional dc-dc converters used for hybrid RESS.
- Although PPA has high efficiency, it does not provide control flexibility and the battery current ripple and DC link voltage ripple values are not as good as MPC architecture.
- MPCA provides the highest efficiency (as high as the PPA) and the best DC link voltage and battery current ripples.
- Improving the controls with an additional current rate limiter for the CCA improved the efficiency and the overall performance.
- Efficiency is computed as the cycle based energy efficiency; i.e., the input and output power of the system is integrated over the time period of simulation.

Collaboration and Coordination

| Organization | Type of Collaboration/Coordination |
|---|--|
| Maxwell, IOXUS   | Fast response electrochemical capacitor development |
| Chrysler  | Power electronics dc-dc interface trends for RESS |
| ORNL Energy Storage Program | Design guidelines and research on modular battery pack configuration |
| ORNL Battery Manufacturing Facility | Manufacturing research on modular battery development |

Proposed Future Work

- **Remainder of FY13**

- Modeling, simulations, and analysis of modular reconfigurable dc-dc converter architectures. Share results with APEEM team members.

- **FY14**

- Fabricate and test a candidate 10 kW reconfigurable dc-dc converter architecture for experimental validation of models and simulations. Share results with APEEM team members.

- **FY15**

- Fabricate and test a full rated (55 kW) reconfigurable dc-dc converter architecture. Share results with APEEM team members.

Summary

- **Relevance:** This project is targeted toward active energy management and reduced size and cost of the power electronic converters that interface RESS and traction drive inverter.
- **Approach:**
 - Develop a bi-directional buck/boost dc-dc converter between the regenerative energy storage systems (RESS) and the dc link (traction drive inverter),
 - Design a hybrid battery/ultra-capacitor energy storage system architecture,
 - Design a modular reconfigurable dc-dc converter architecture,
- **Collaborations:** Collaborations with Chrysler, Maxwell, IOXUS, and ORNL's Energy Storage Programs and Battery Manufacturing Facility are being used to maximize the impact of this work.
- **Technical Accomplishments:**
 - Reviewed and modeled bi-directional dc-dc converters.
 - Reviewed and modeled hybrid RESS architectures and created a summary report based on the advantages, drawbacks, control systems, performance, number of parts, etc.
 - Selected and modeled four battery/UC hybridization strategies. Run the simulations and compared the performance results.