

Evaluating Real World Drive Cycles to Support APRF Technology Evaluations

2012 DOE Hydrogen Program and Vehicle Technologies

Annual Merit Review

May 14, 2012

Eric Rask, Aymeric Rousseau

Argonne National Laboratory

Project ID # VSS091



Overview

■ **Timeline**

- Literature search of recent real-world cycles and assessment procedures
- Coordination with M&S for test schedule and vehicle behavior insight
- Evaluation of Argonne test vehicles over select real-world cycles
- Analysis of select cycles
- Refinement of real-world testing cycles/procedures
- Continued vehicle testing

■ **Budget**

- FY 2011 \$200k
 - \$100k Vehicle Testing and Analysis
 - \$100k Modeling and Simulation

■ **DOE strategic goals/barriers addressed**

- **F:** Constant advances in technology
 - Fuel /energy consumption variability of different technologies to driving variation
- **D:** Lack of standardized test protocols
 - Existing test protocols evaluate specific facets of vehicle operation...to the exclusion of others
 - Regulatory developments toward harmonized real-world cycle

■ **Partners**

- DOE and other National Laboratories
- USDrive, OEMs, and Suppliers
- World Forum for Harmonization of Vehicle Regulations (WP.29)
- EU, DOT, EPA

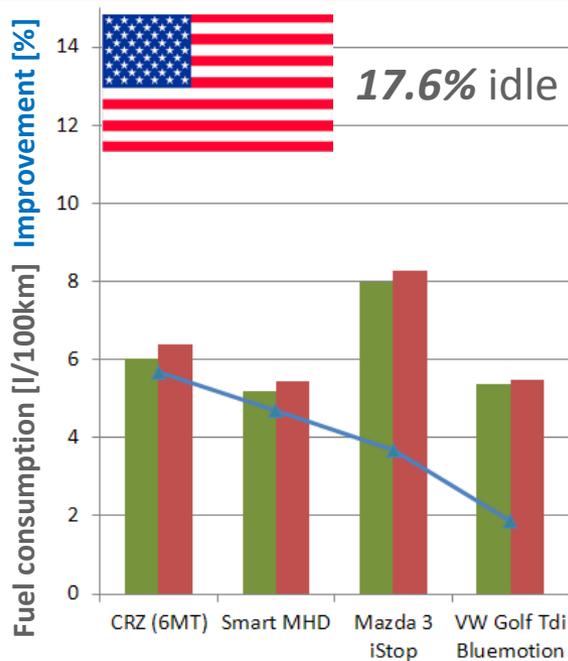


Relevance: The Importance of Real-world Cycles

- Research has consistency shown that the benefit of a particular vehicle technology is dependent on the evaluation cycle

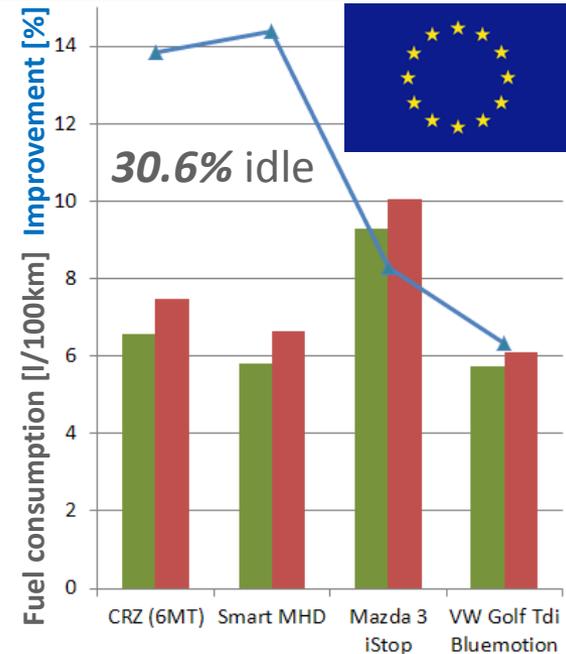
UDDS

→ Average start stop improvement **4%**



NEDC (City)

→ Average start stop improvement **10%**

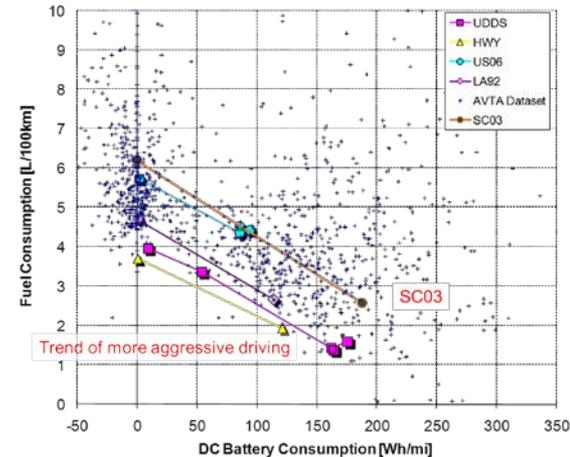
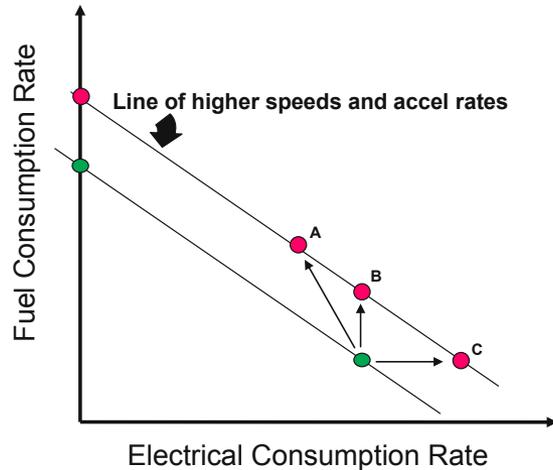


- Manufacturers are continually seeking to improve real-world fuel consumption:**
 - “This system was developed with the main purpose to improve fuel consumption, especially for better real world fuel consumption” – Toyota 2010 SAE Paper [1]

[1] T. Matsubara, et al, Development of New Hybrid System for Compact Class Vehicles, SAE World Congress, 2009-01-1332

Relevance: The Importance of Real-world Cycles

- **Generally, these issues become more complicated with greater vehicle electrification**
 - Blended PHEVs are particularly sensitive to driving style



- **Worldwide, regulatory agencies are seeking to update procedures for real-world usage**
 - WLTP Drive cycle will likely become a regulatory cycle for multiple countries (EU, China, India)
 - EPA 5-cycle adjustment for real-world driving and ambient conditions
 - Utility weighting assumes all distances are driven in a similar style, this is typically not the case
 - The technology implications of real-world regulatory cycles needs to be compared to the existing regulatory procedure and cycles



Approach/Strategy: Real-world Cycle Selection Process

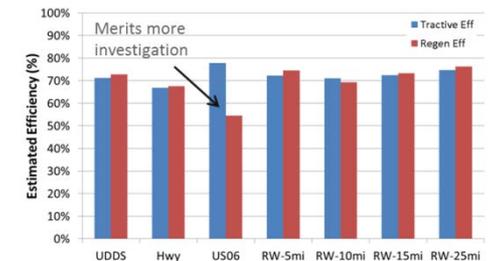
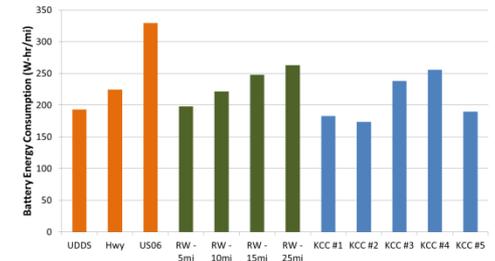
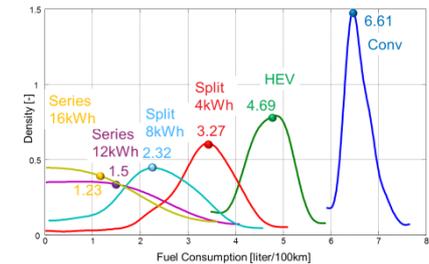
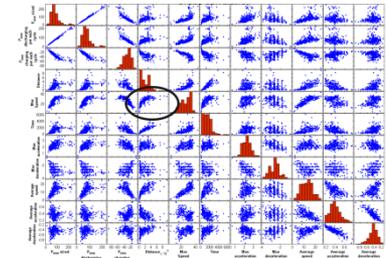
Simulation assessment of various technologies over numerous cycles

Distribution analysis of energy consumption trends

Assessment of select cycles

Confirmation of efficiency trends

Selection of APRF evaluation cycles



Approach/Strategy: Dynamometer Based Vehicle Evaluation

- **Real-world cycles are typically evaluated in large batches using vehicle simulation: What are the implications for dynamometer testing?**
 - Technology and energy consumption implications
 - Practical issues related to real-world cycle testing on a dynamometer
 - Selection method for applicable/useful supplemental real-world cycles and overlap
 - Behavior and performance due to vehicle warm-up and related issues
- **Leverage APRF research vehicles to evaluate several sets of real-world drive cycles on a range of vehicle technologies**

Conventional Vehicle



Hybrid



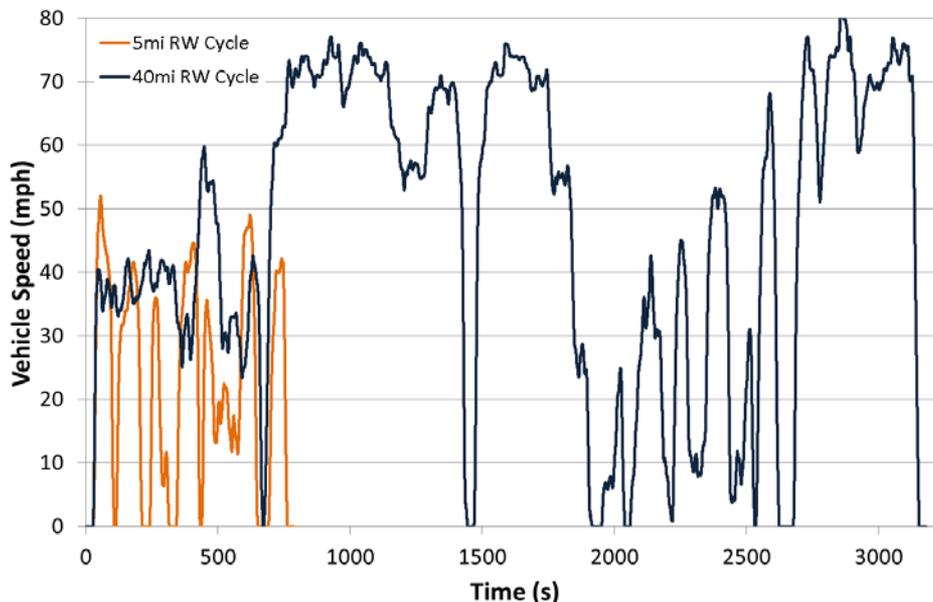
BEV



- On-going assessment with Chevrolet Volt, Hyundai Sonata Hybrid, and VW Jetta TSI
- Supplement dynamometer testing with Modeling and Simulation results/analysis

Approach/Strategy: Stochastic Driving Cycle Assessment

- **Leverage University of Michigan developed Stochastic Drive Cycles [1] for preliminary assessment of real-world cycles**
 - Drive cycles developed using a statistical procedure to create a representative cycle having similar characteristics to real-world driving
 - 5, 10, 15, 25, 40 mile distance cycles evaluated
 - > 5mi real-world cycles exhibit much less idling
 - UDDS ~18% idle



Short Distance Statistics

Statistical parameters	Real Cycles*	Synthetic Cycle
Distance (mile)	-	6.077
Mean pos. vel. (mph)	28.9463	28.9764
std. vel. (mph)	17.6774	17.7453
Mean pos. acc. (m/s ²)	1.0599	1.0787
std. acc. (m/s ²)	1.3535	1.3388
Perc. driving time under pos. acc. (%)	40.3848	39.8714
Perc. driving time under neg. acc. (%)	39.5487	36.8703
Perc. Idle time (%)	21.1607	19.0782
# stops/mile (1/mile)	1.3866	1.3164

* Mean values are presented for real cycles

Moderate Distance Statistics

Statistical parameters	Real Cycles*	Synthetic Cycle
Distance (mile)	-	23.2247
Mean pos. vel. (mph)	47.5074	48.0236
std. vel. (mph)	22.7512	23.5011
Mean pos. acc. (m/s ²)	0.6693	0.7312
std. acc. (m/s ²)	1.0931	1.0296
Perc. driving time under pos. acc. (%)	46.3879	38.9124
Perc. driving time under neg. acc. (%)	44.9012	32.6822
Perc. Idle time (%)	8.6135	8.0781
# stops/mile (1/mile)	0.3058	0.1722

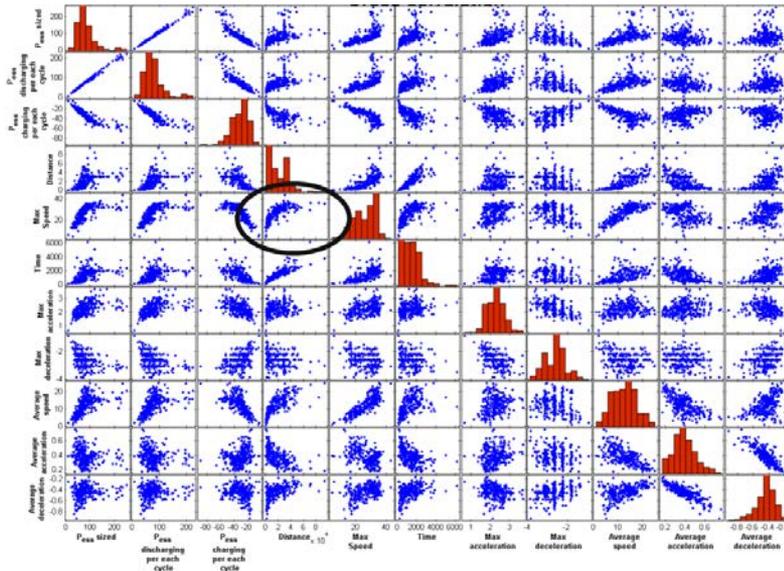
* Mean values are presented for real cycles

[1] T.-K. Lee, and Z.S. Filipi, "Synthesis of Real-World Driving Cycles Using Stochastic Process and Statistical Methodology", in the review of the Int. J. Vehicle Design, 2010

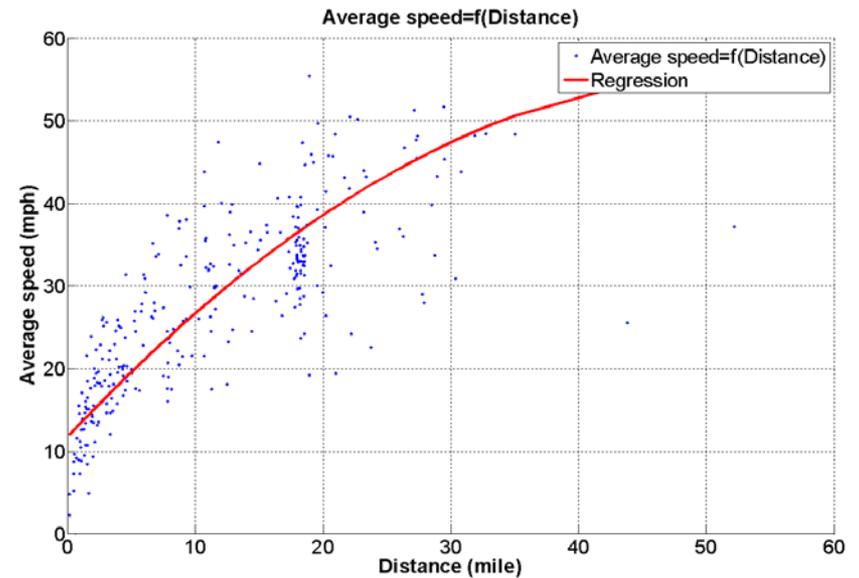
Approach/Strategy: Select EPA real-world Cycles Assessment

- In addition to the stochastic cycles, assess a sub-set of EPA's real-world drive cycles from vehicle data collection in and around Kansas City
 - Wide range of distances, speeds and driving styles
 - Evaluate methodologies to select “relevant” dynamometer cycles
 - Leverages previous Modeling and Simulation analysis efforts

M&S Cycle Cross Correlations



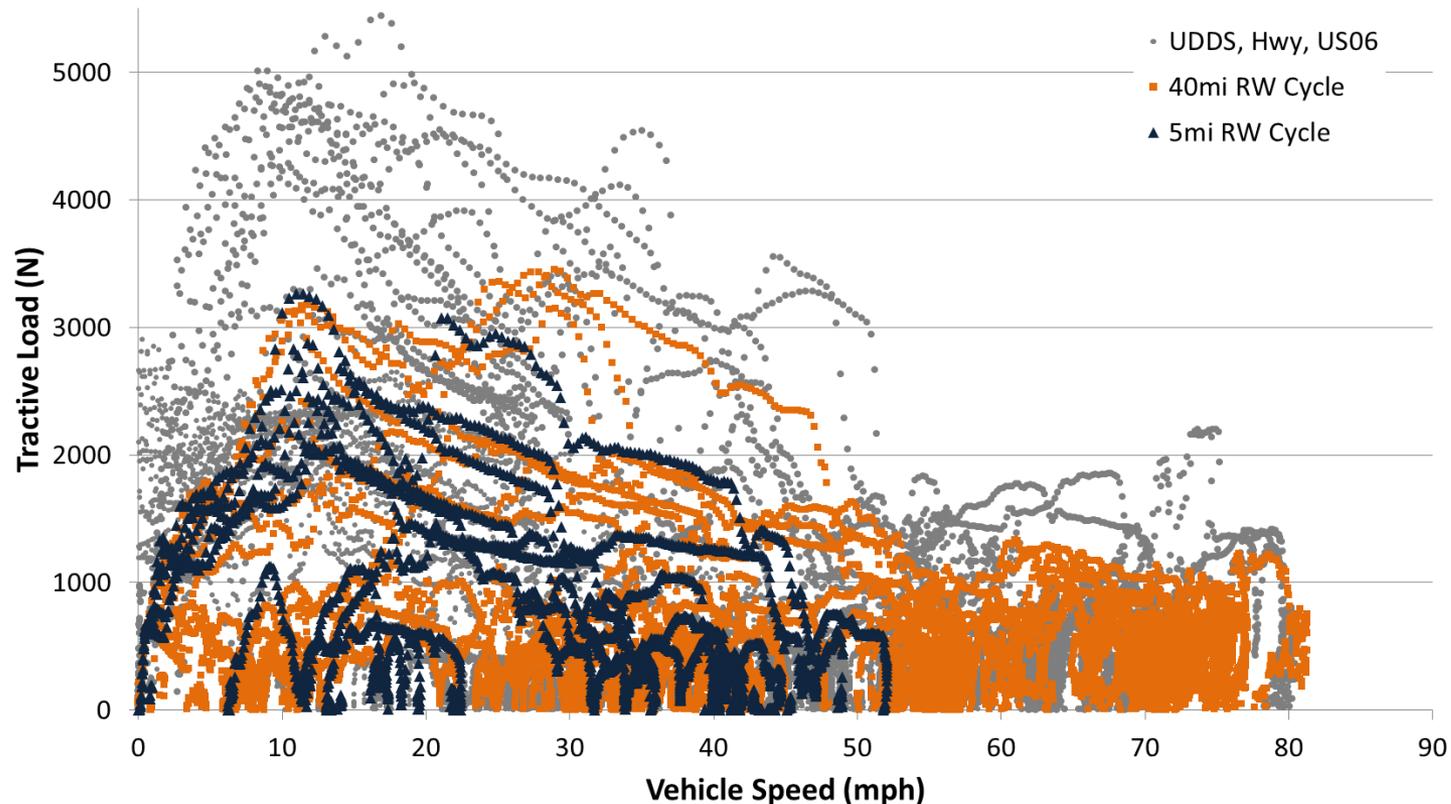
Increasing Average Speed with Distance



Accomplishments: Basic Insights from Real-world Cycles

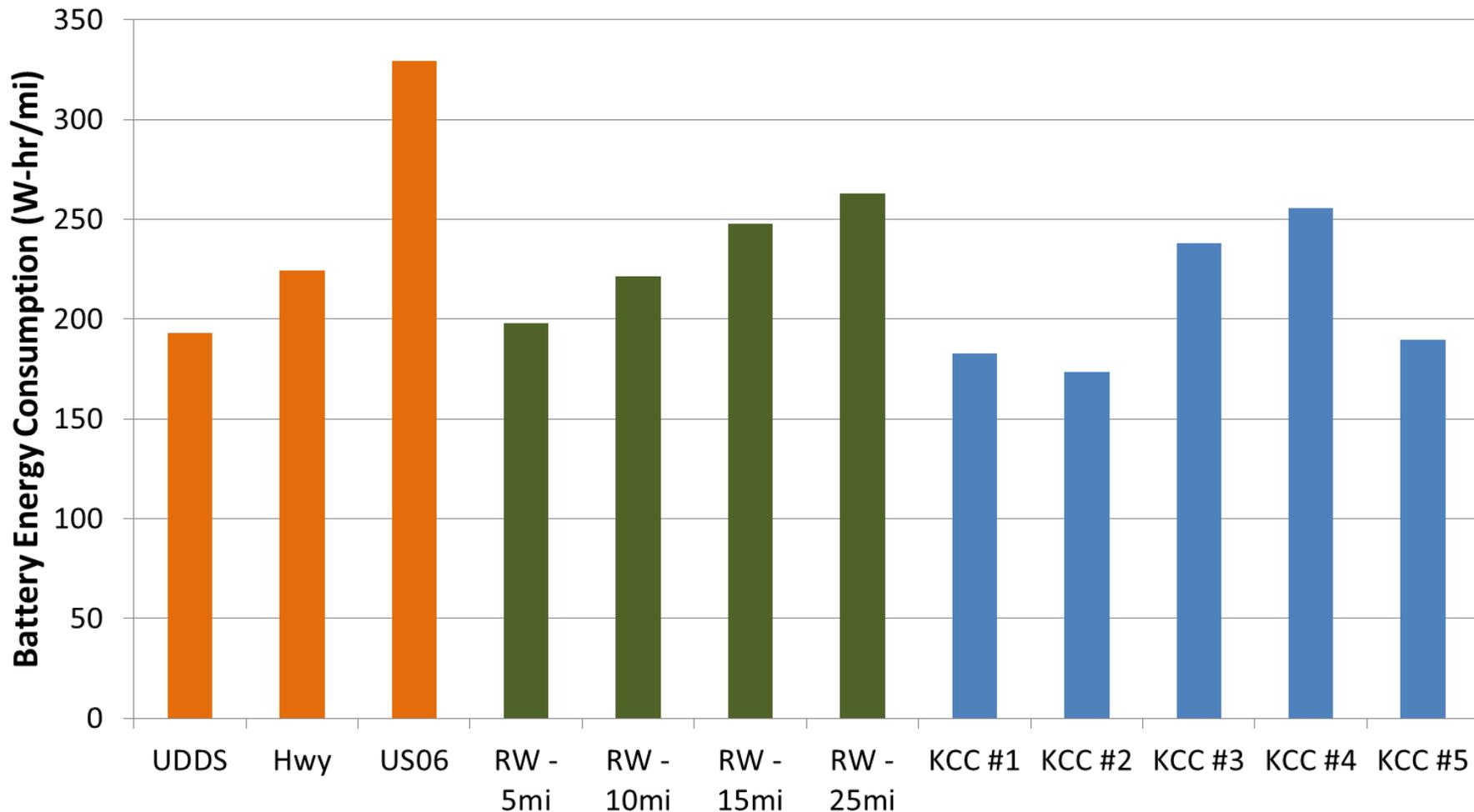
Real world cycles provide improved coverage of moderate load points across a wide range of vehicle speeds (especially moderate/high speeds)

- Limited information regarding component operational limits
- Improved information for efficiency map generation
- Many cycles much too long for frequent dynamometer operation
 - Need to develop process to synthesize shorter (time) cycles



Accomplishments: Leaf Real-world Evaluation

Real-world cycles are fairly comparable in terms of energy consumption...US06 still appears to represent the upper threshold of an aggressive, higher consumption cycle

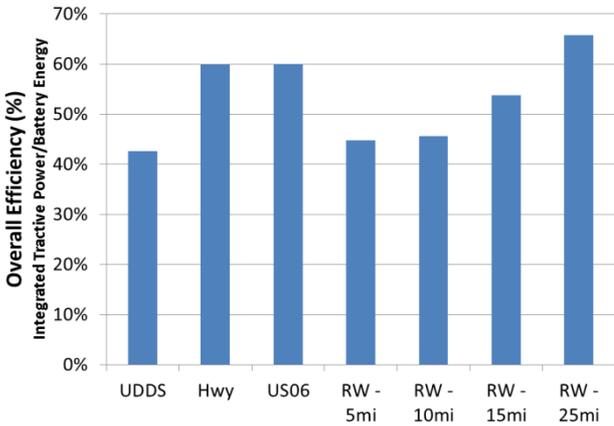


Accomplishments: Leaf Real-world Evaluation

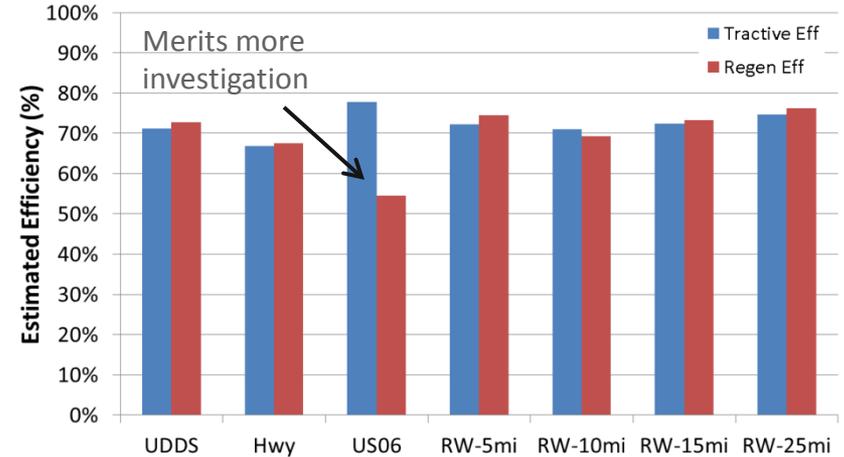
Using some intelligent processing, real-world energy efficiency trends can be fairly well estimated for cycles similar to the UDDS and outliers can be further investigated

Overall efficiency trends appear scattered

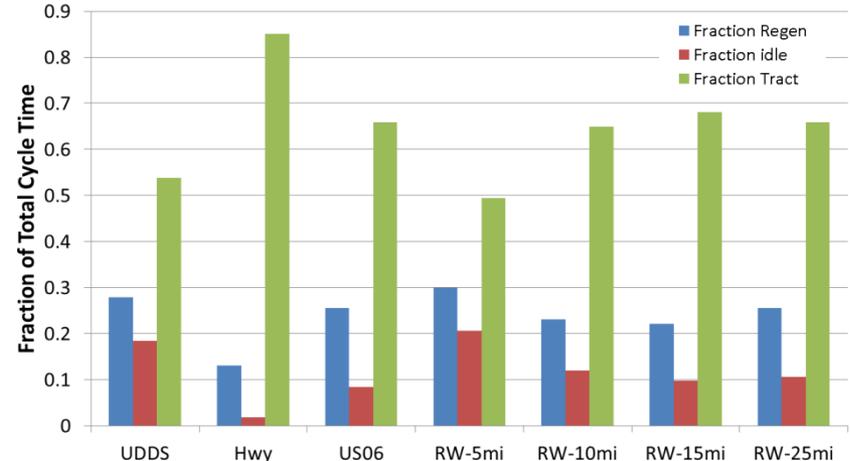
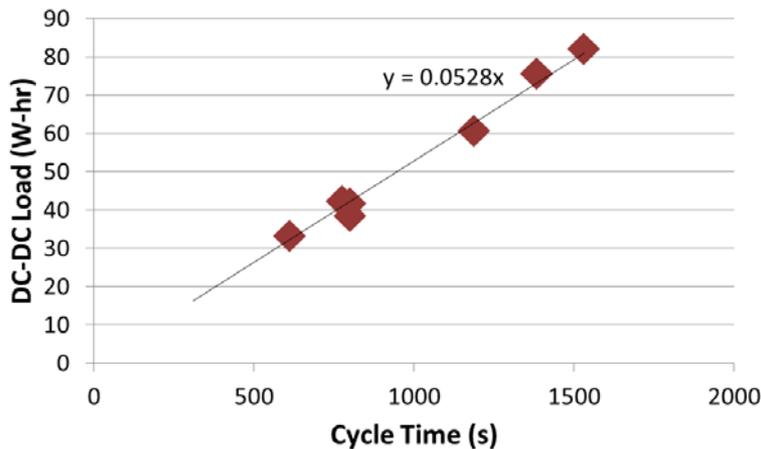
Integrated tractive power / Battery energy



Improved Efficiency Estimates



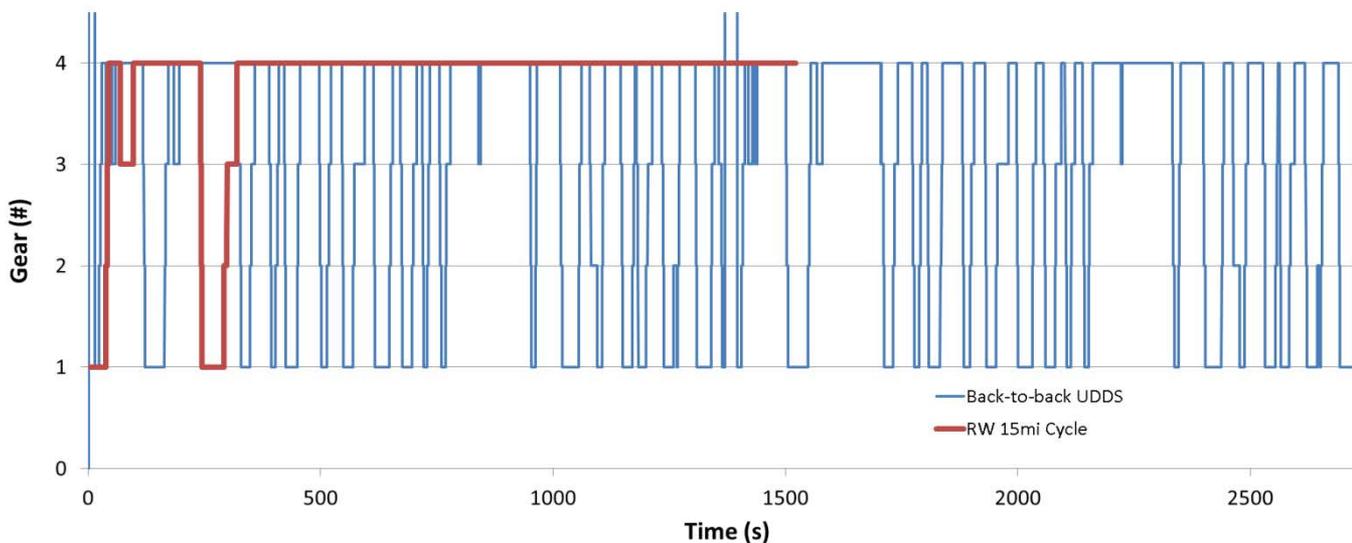
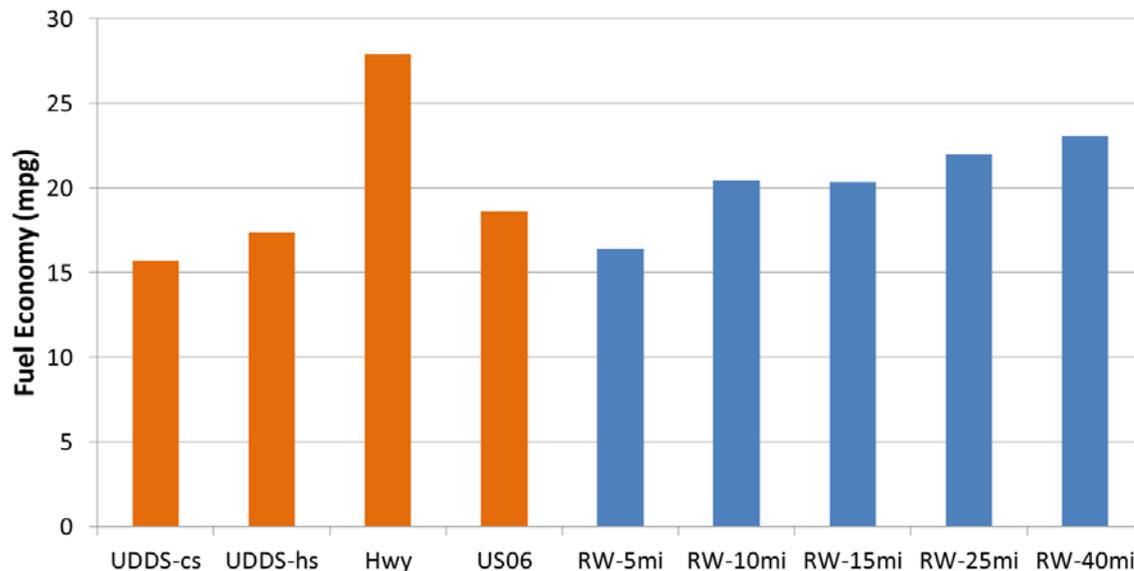
Excluding accessory loads and allocating braking vs. propulsion energy greatly aids in clarifying efficiency trends



Accomplishments: Conventional Vehicle Analysis

Conventional vehicle operation differs dramatically between Hwy and RW operation

- Conventional vehicle shows elevated Highway fuel economy compared to real-world cycles
- Vehicle also shows considerably different transmission operation for two 15 mile trips: UDDS 2X (15mi) and RW-15mi cycle

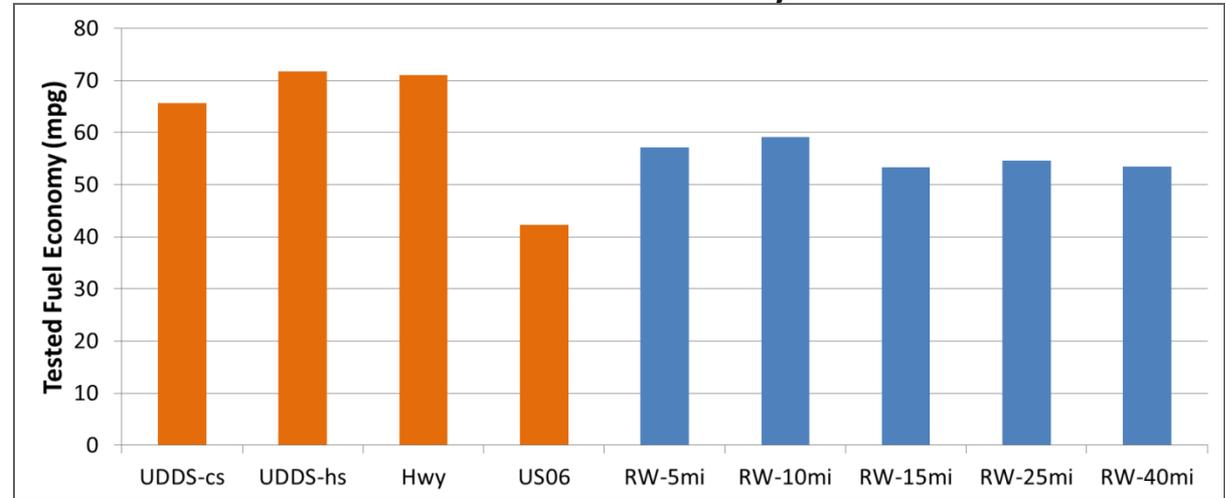


Accomplishments: Prius Operation Analysis

Testing provides insight into operational and economy differences due to real-world cycles

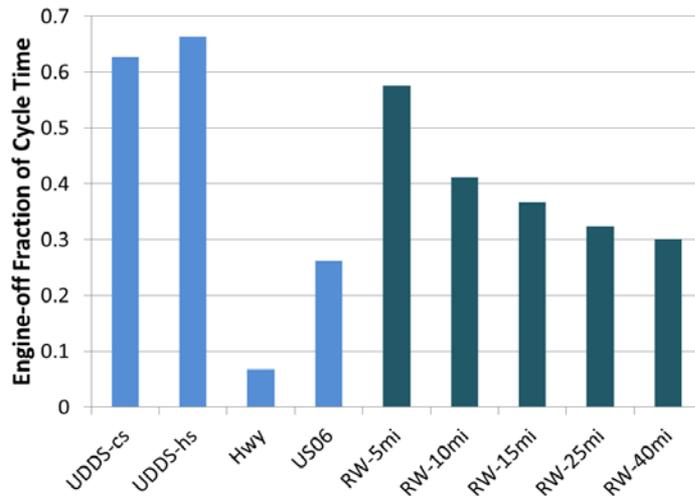
- Vehicle shows different trends in both engine-off fraction and maximum battery swing...suggests different vehicle operation compared to UDDS

Tested Fuel Economy



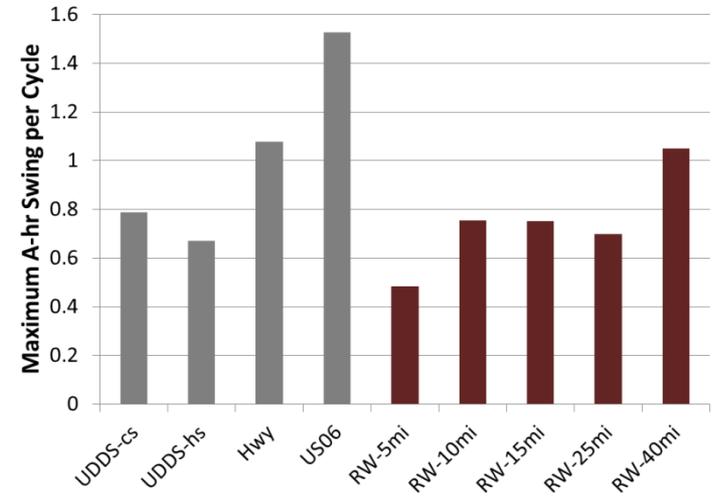
Engine On/Off differs significantly versus UDDS

Higher vehicle speeds results in less engine-off



Maximum A-hr swing also indicates different operation

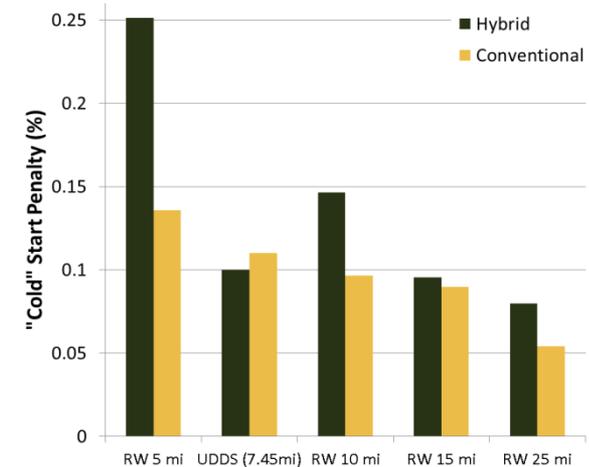
Larger A-hr swing often suggests more opportunity charging



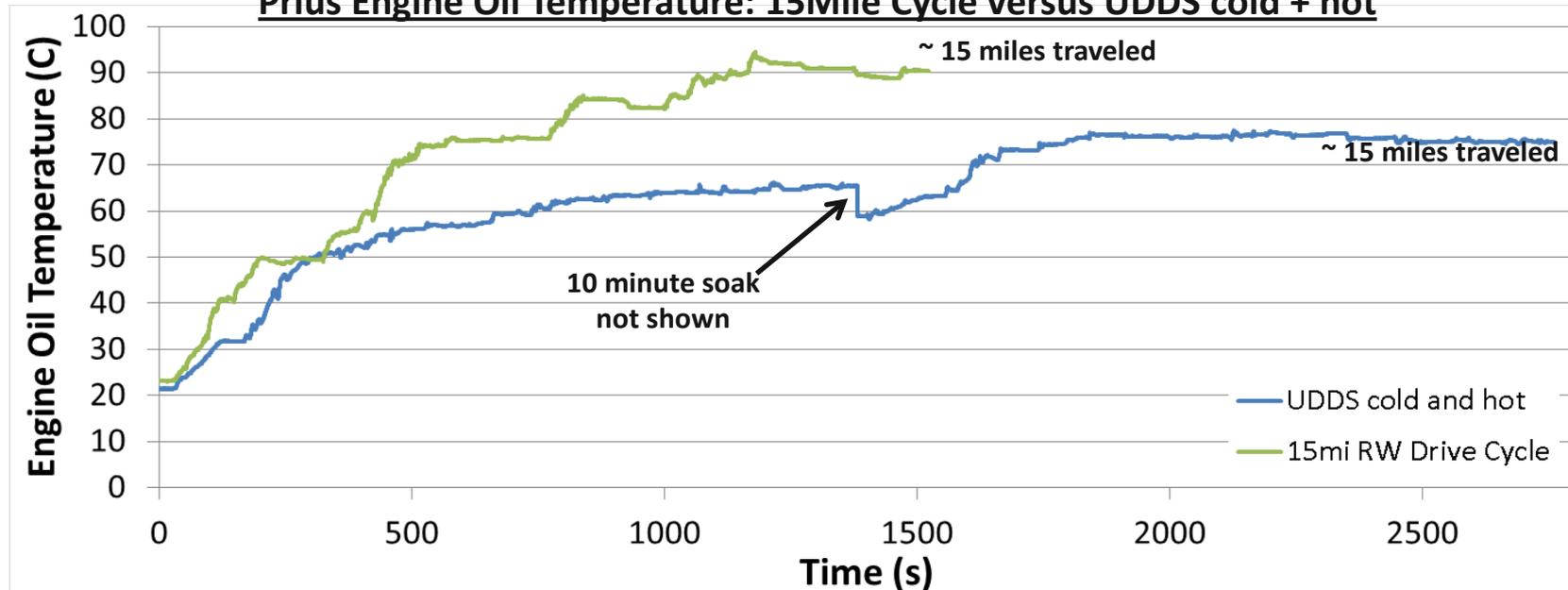
Accomplishments: Preliminary Cold Start Analysis

Impact of vehicle warm-up varies with distance (fraction of cold vs. warm) and engine usage/power

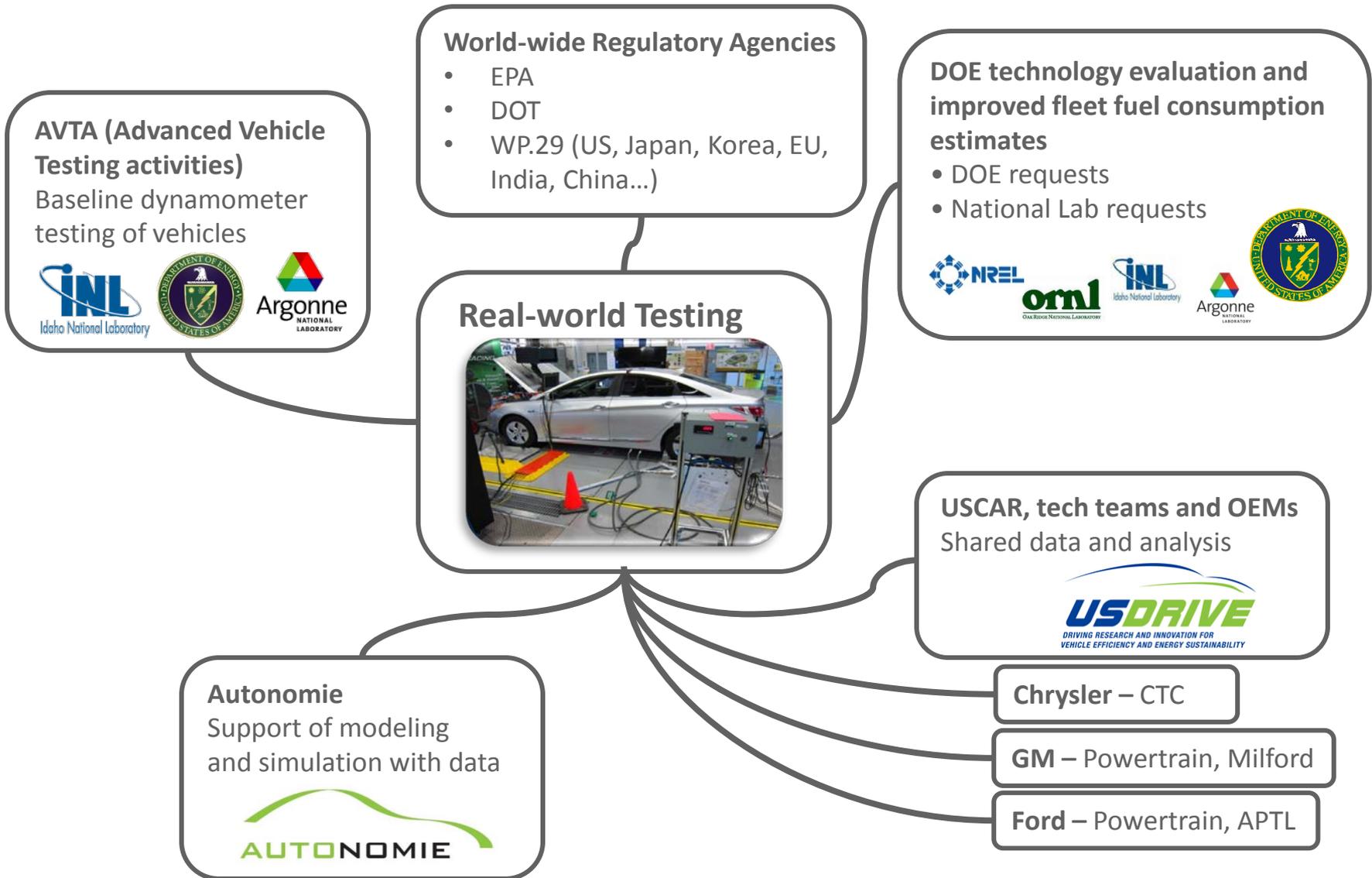
- Both hybrid and conventional vehicles show a varied impact of vehicle warm-up depending on cycle driven
- Prius 5mile cycle shows a significant impact due to vehicle warm-up and a larger penalty for 10 mile cycle as well
- Conventional vehicle shows similar RW trends, but UDDS shows a larger penalty versus 10mile cycle (likely engine usage related)



Prius Engine Oil Temperature: 15Mile Cycle versus UDDS cold + hot



Collaboration: Real-world Testing Aids Vehicle Benchmarking



Future/On-going Work

Continued evaluation of RW cycles using APRF research vehicles

- **Assessment of “real-world” regulatory cycles – World Lightweight Test Cycle (WLTP)**
 - Cycle is rapid gaining traction as a harmonized evaluation cycle
 - Assessment of “real-world” regulatory cycles to US driving (both regulatory and real-world)
- **Evaluation of Chevrolet Volt over real-world drive cycles**
 - Regulatory versus real-world EV to charge-sustaining transition of particular interest
 - Creation of distance-based, driving specific utility adjusted fuel consumption estimate
- **Real-world performance benchmarking of Hyundai Sonata hybrid**
 - Interesting contrast to the Prius (power-split) type system...regulatory versus real-world
- **Evaluation of real-world driving under hot/cold ambient temperatures**
 - The impact of different driving styles and distances on the impact of vehicle warm-up and cool-down is particularly relevant to estimating the impact of different technologies
- **Development of improved cycle synthesis procedures for practical dyno. testing**



Summary

Testing vehicles on real-world as well as regulatory cycles provides further insight into vehicle behavior, energy consumption, and important areas of operation

- Selected real-world cycle improve coverage for efficiency maps
 - Cycles provide higher-speed moderate load points, not contained in US06
 - Many real-world cycles are extremely time-consuming
 - Additional processing/synthesis required for frequent assessment on dyno.
- BEV efficiency is fairly consistent for most real-world cycles
 - Processing to allocate energy between accessories, braking, and propulsion helpful
 - US06 shows interesting differences in efficiency and regen. capture (system limitations)
- Conventional vehicle shows dramatically different transmission operation
- Given the higher-speed/moderate load driving of the real-world cycles, selected HEV shows fairly different operation compared to the UDDS
 - Vehicle exhibits different engine on/off control and battery utilization

Leveraging Level-1 and Level-2 research vehicles for evaluation of real-world cycles provides additional insight for both technology assessment and component map generation

