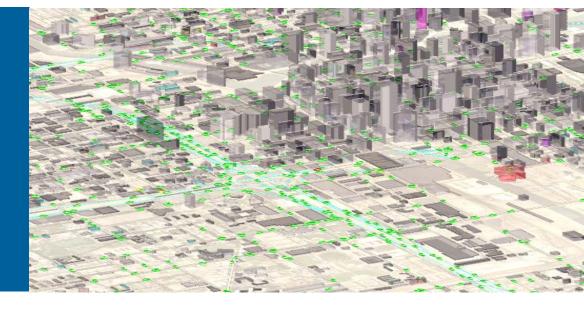
PROJECT ID # EEMS013



ANL CORE TOOLS SIMULATION



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Argonne National Laboratory 9700 S Cass Ave Lemont, IL

Annual Merit Review 2020, Washington DC

This presentation does not contain any proprietary, confidential, or otherwise restricted information

PROJECT OVERVIEW

Timeline	Barriers	
 Project start date: Oct. 2018 Project end date: Sep. 2021 Percent complete: 50% 	 High uncertainty in technology deployment, functionality, usage, impact at system level Computational models, design and simulation methodologies Lack of data on individual behaviors relating to e-commerce and freight Integration of disparate model frameworks 	
Budget	Partners	
Total funding: \$3,750,000FY20 funding received: \$1,250,000	ArgonneFordUS Drive Partnership21CTP Partnership	

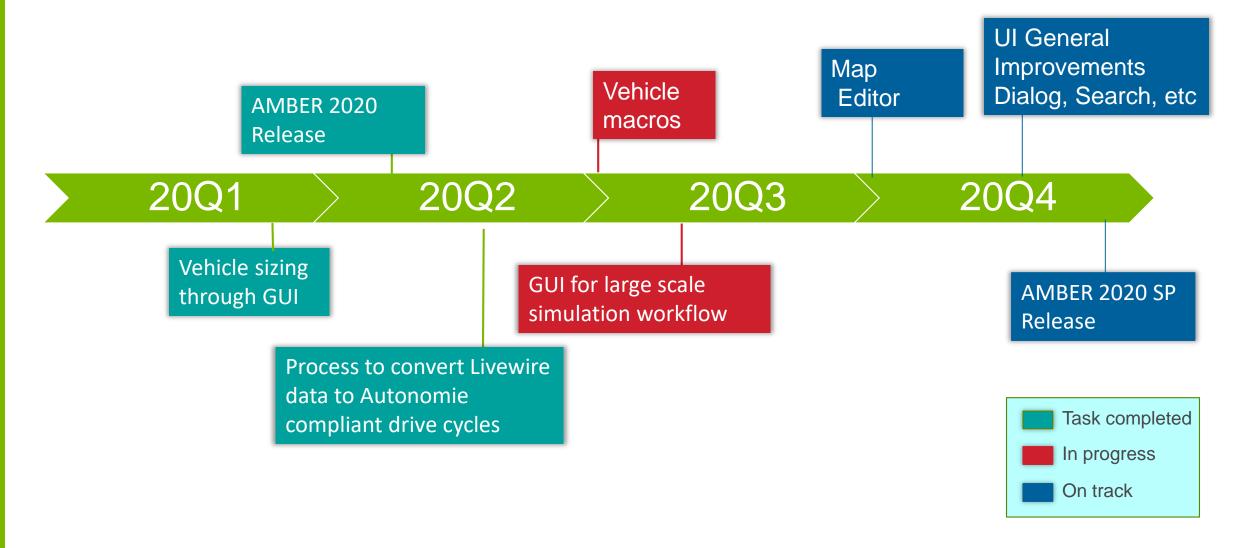
PROJECT RELEVANCE

Argonne simulation tools and results are used to support a very large number of VTO projects as well as organizations throughout the world to define R&D targets, evaluate the benefits of advanced technologies, provide R&D guidance...

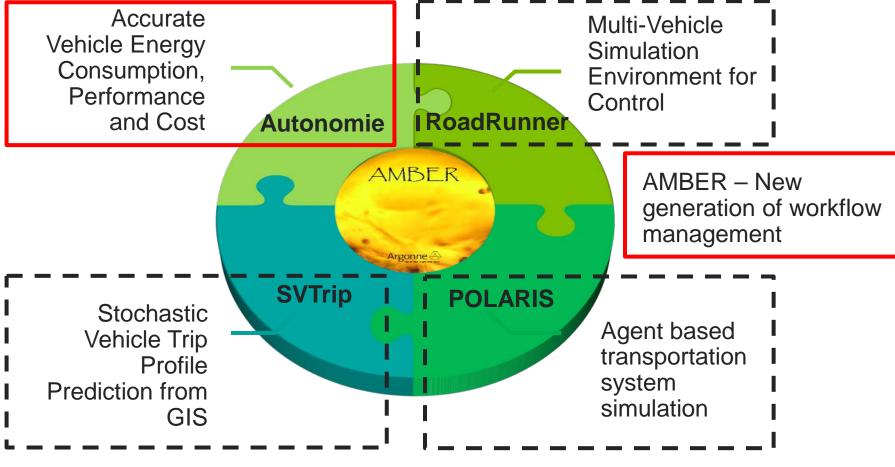
- During the 2019 AMR, 28+ projects were related to Autonomie:
 - Provided inputs to Autonomie:
 - E.g. New data from SMART Consortium, vehicle testing...
 - Used Autonomie to perform studies:
 - E.g. Advanced technology impacts (e.g., CAVs, Co-Optima)
 - Used Autonomie results to perform further studies / analysis:
 - E.g. VTO Benefit Energy Impact, US Drive...
- Autonomie was also used to support ARPA-E NEXTCAR, FCTO, DOT and DOD



MILESTONES



APPROACH – AMBER WORKFLOW MANAGER

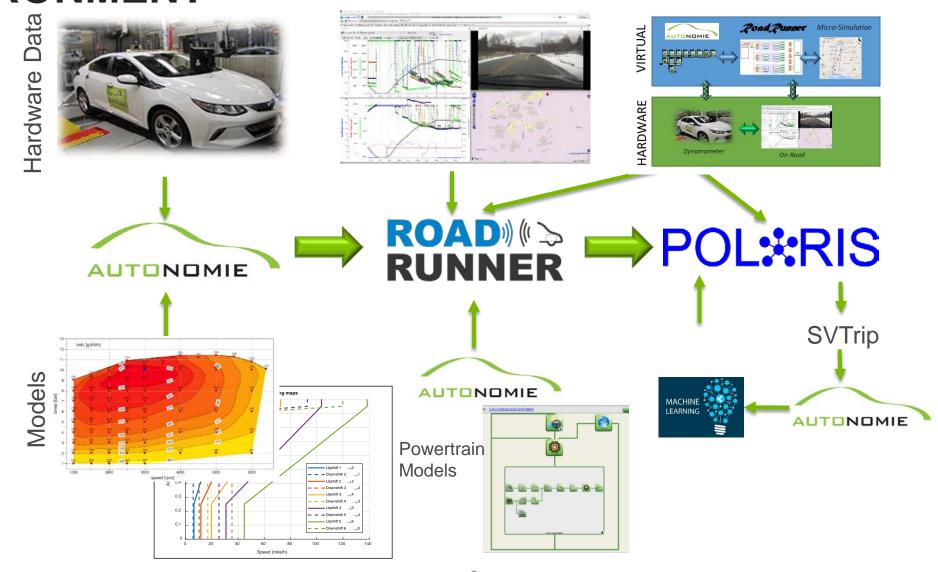




EEMS058 (SMART Mobility Consortium Tools and Process Development)



APPROACH - TOOLS ARE PART OF AN INTEGRATED ENVIRONMENT

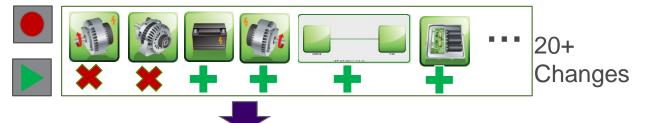


TECHNICAL ACCOMPLISHMENTS AND PROGRESS



REUSE PART OF A VEHICLE TO CREATE A NEW ONE FROM 2 HOURS DOWN TO 5 SECONDS

ALL changes in the interface are recordable



Starter

Engine

Mechanical Accessory Llutch/Torque Converter

Gearbox

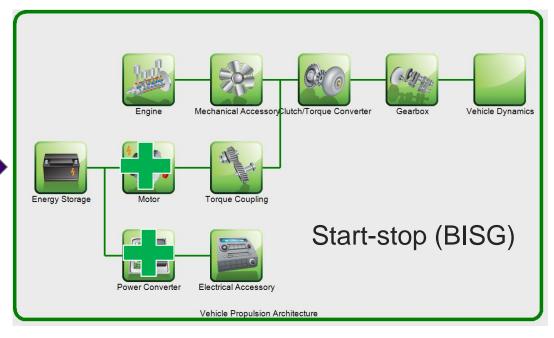
Vehicle Dynamics

Conventional

Electrical Accessory

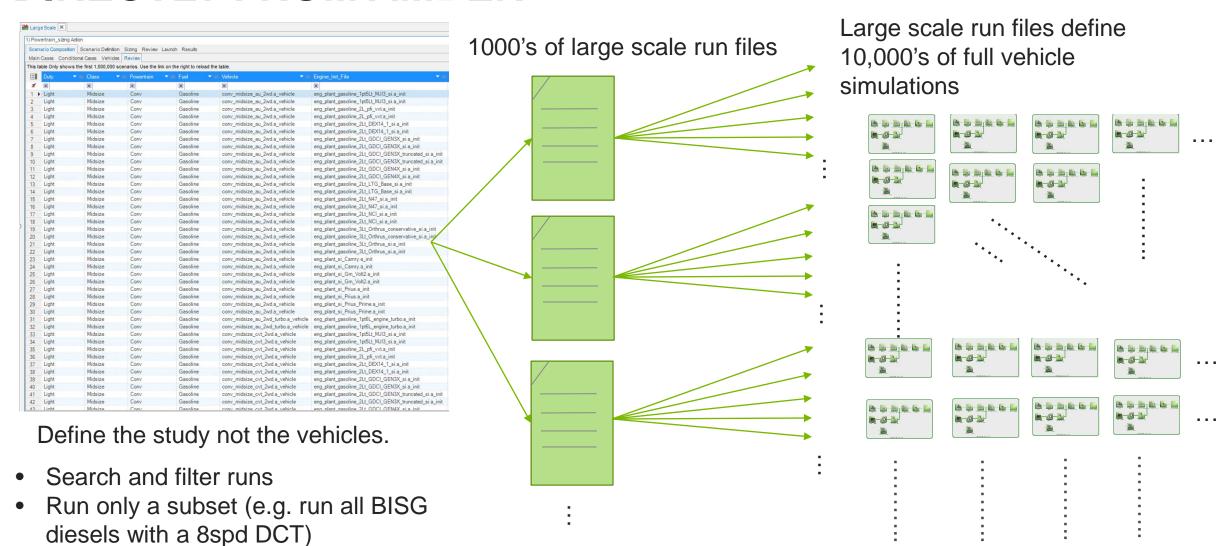
Vehicle Propulsion Architecture

- 1. PI Driver to Human Driver for RoadRunner
- 2. Manual to Autonomic
- 3. Gasoline to Diesel
- 4. Conventional to BISG
- 5. Two wheel drive to Four wheel drive
- 6. ...



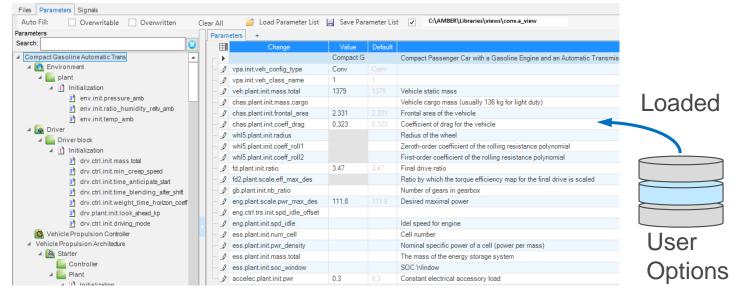


CUSTOMIZE AND RUN MILLIONS OF SIMULATIONS DIRECTLY FROM AMBER

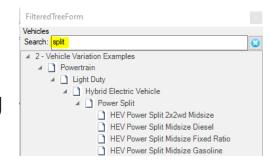


WORK FASTER AND BETTER WITH IMPROVEMENTS THROUGHOUT THE USER INTERFACE

- Based on user feedback
 - Redesigned dialogs
 - Searchable
 - Informative
 - Visual
 - Additional tool tips
 - Preloading editors with user defined favorites
 - Edit a Vehicle
 - Run a Vehicle
 - Import Test Data
 - More interactive suggestions about files, parameters, buses to guide users when modifying vehicles



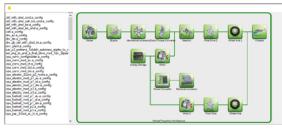
Find files faster with search



More informative dialogs

I do with video control of the contr

See configurations before selection









USE LIVEWIRE DATA IN AUTONOMIE (FLEETDNA → LIVEWIRE → AUTONOMIE)

- Use real world drive cycles shared through Livewire
- Quantify real world benefits of electrified powertrains using Autonomie
- Share the platform independent models and cycles for wider usage.

NREL

- Real World Data
- Drive cycles for multiple types of trucks
- Test weight estimates

Livewire



Argonne

- Vehicle Simulation
- Vehicle models
- Drive cycles formatted to daily work trips
- Energy consumption estimates on real world use cases

Autonomie

Argonne

- Data Dissemination
- Compiled vehicle models that can run as an executable file
- Daily drive cycles formatted for vehicle simulation*

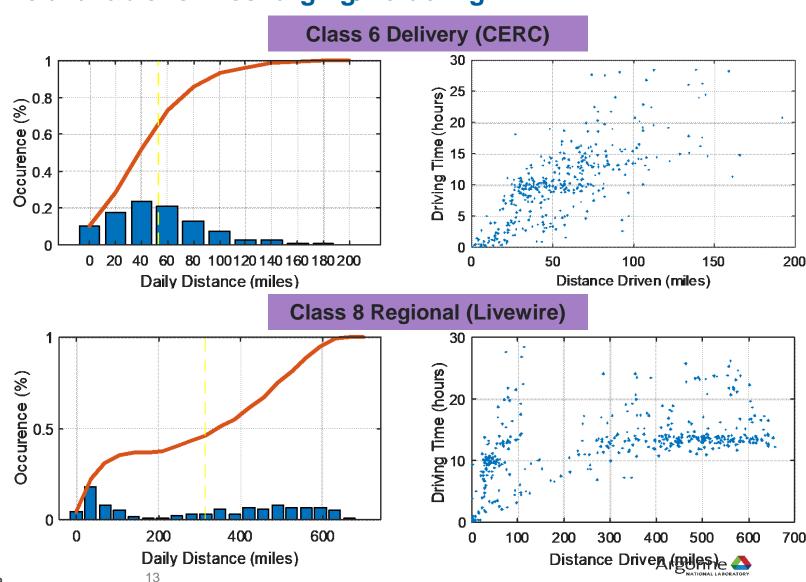
Globus



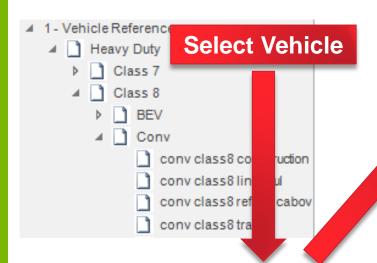
REAL WORLD DRIVE CYCLES (RWDC) INFORMATION USED TO IMPROVE VEHICLE REQUIREMENTS

Range, Payload estimates, Downtime available for Recharging/Refueling

- RWDC was collected from fleets across US by NREL. This data is shared through Livewire
- Daily driving range –Multi shift operations can have some work days extending beyond 24 hours.
 Downtime available between trips will guide charging or refueling rates needed for vocations
- Other information
 - Cruising speed requirements
 - Payload estimates,
 - Test weight estimated by NREL
 - Vehicle curb weight is known
 - Location & duration of stops could identify the opportunities for charging or refuelling.

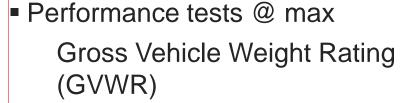


POWERTRAIN SIZING PROCESS FULLY INTEGRATED



Default	Tec	h Specs.
size_HD_vehicle.	Sizing Angorithm	
	Powertrain	
13.33	0-30mph Acceleration Speed	
14	0-30mph Acceleration Time	
26.6667	0-60mph Acceleration Speed	
50	0-60mph Acceleration Time 2	
31.2	Target Cruising Speed	
35	Target Max Speed	
16.54	Target Grade Speed	
6	Percent Grade	
400	Battery Pack Voltage	





- Cruising speed
- Sustainable Grade @ 65mph
- Sustainable speed at 6%
 Grade climb for 11 miles
- Launch @ 15% grade
- Acceleration & Passing
 - 0-30mph & 0-60mph
- All Electric/Driving Range

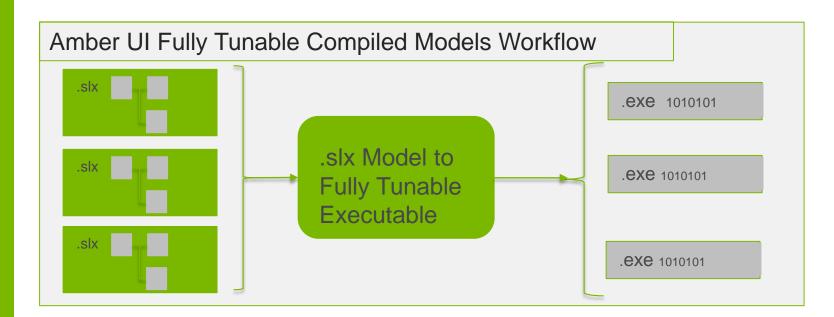




- Fuel economy tests @ regular load
 - EPA regulatory cycles
 - Real World Cycles (Livewire, FleetDNA, CERC)
- Total Cost of Ownership (TCO)
 - Component Cost:
 - DOE targets
 - Other sources (actual, ML etc)



FULLY TUNABLE COMPILED MODELS ALLOW RAPID EVALUATION OF HUNDREDS OF REAL WORLD CYCLES



The ability to run compiled (.exe) models enables:

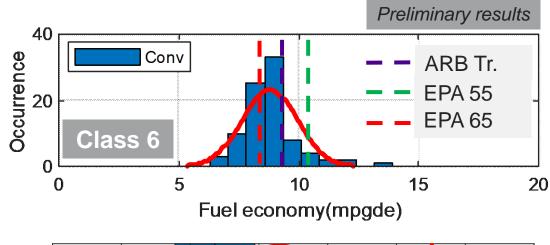
- Faster simulations (min to sec)
- Cost savings (no 3rd party licenses)
- Scale up on HPC
- Deployment to larger number of users
- Necessary inputs and outputs have been identified for compiled models
- Post-processing scripts are been developed to analyze the output
- Matlab tables, plots and tableau dashboards have been developed to analyze and visualize simulation results

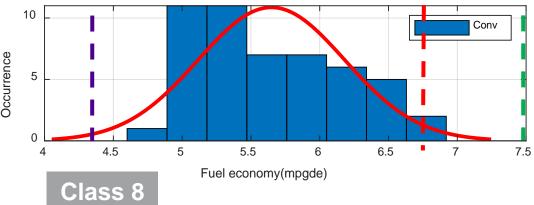


REAL WORLD FUEL ECONOMY EVALUATION OF VEHICLES

Regulatory cycles are fairly good representation of real world cycles.

- Class 6 cycles are from CERC Project (Cummins)
- Class 8 cycles are from Livewire for Sanger, TX
 - Two more locations were processed.
- EPA weighs the regulatory cycles according to use cases: Urban, Multipurpose, Regional
- RWDC characteristics help identify the appropriate weighing factors.
 - Class 6 Delivery is more multi-purpose, than Urban (in terms of driving behavior)
 - Class 8 runs in Texas yields lower mpg values due to the speeds >70mph. More locations are being evaluated.
- Q: Can we use regulatory cycles?
 - Prima facie, we see that the EPA weighting works well for conventional vehicles.
 - Weighing method needs to be determined for each vocation



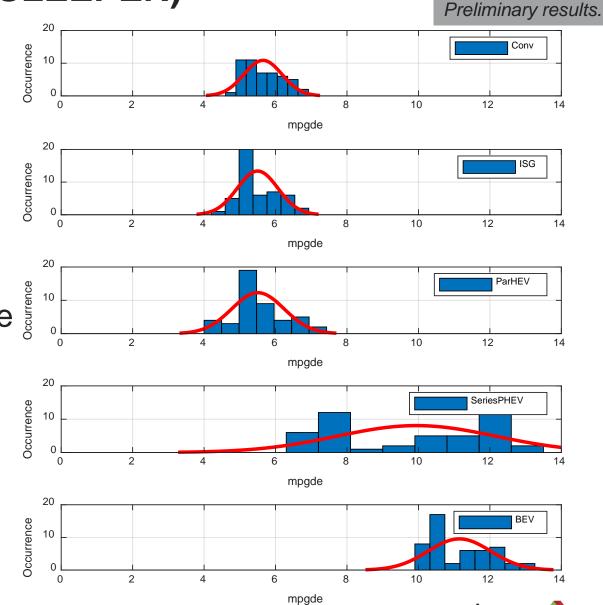




POWERTRAIN SPECIFIC FUEL ECONOMY IMPROVEMENTS ON REAL WORLD CYCLES (CLASS 8 SLEEPER)

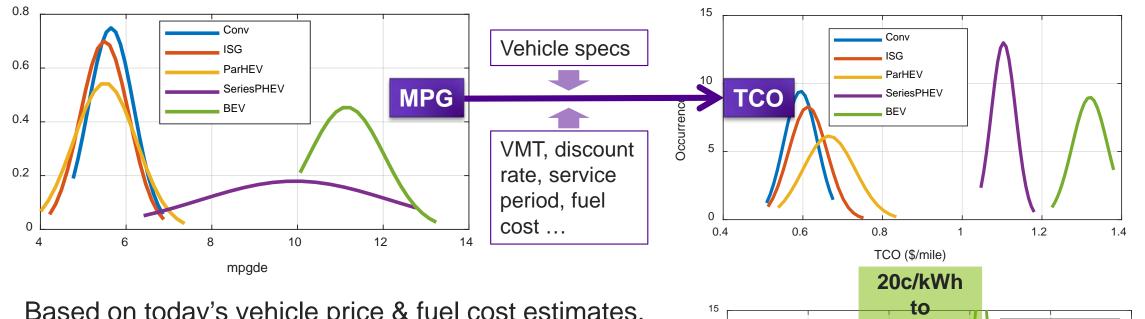
Improvements are dependent on drive cycles

- Class 8 Sleeper data from Livewire*.
 - Integrated Starter Generator (ISG) & HEVs have limited advantages on highway driving, due to increase in curb weight.
 - Series PHEVs are heavier, but having
 250 mile of Charge Depleting (CD) range
 helps in improving overall fuel economy
 - BEVs are sized for 500 mile range.
- Vehicles are tested with 38k lbs. of cargo mass
- NREL will provide data for more classes and vocations through Livewire

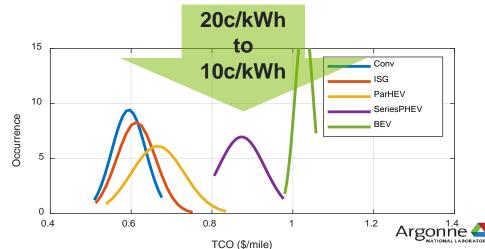


ESTIMATED POWERTRAIN SPECIFIC TCO FOR EACH DAILY DRIVE CYCLE / ROUTE

Cycle properties affecting the powertrain specific Total Cost of Ownership (TCO) are being investigated.



- Based on today's vehicle price & fuel cost estimates,
 TCO is lowest for conventional vehicles.
- Further analysis will quantify the impact of technology progress & fuel costs on the powertrain choice
- Impact of battery cost changes and electricity prices will be quantified as well.



RESPONSES TO PREVIOUS YEAR REVIEWERS' COMMENTS

Comments from 2019 AMR

Overall, the reviewer stated that there is a good plan going forward.
 Developing workflows that do not require software licenses would be a huge benefit...

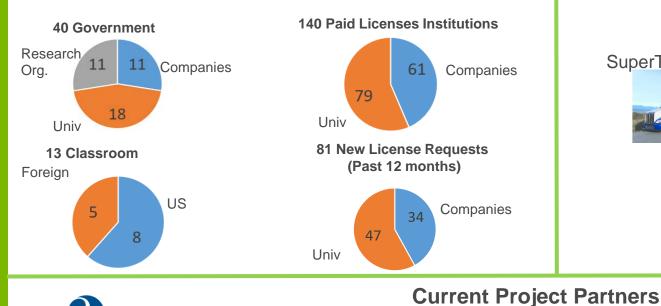
Response

- The compiled workflow & models will be freely distributed



COLLABORATION AND COORDINATION

Users Overview (# of Institutions)



Main Programs Supported











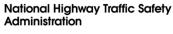








U.S. Department of Transportation











The National Transportation Systems Cents



Federal Transit

Administration

























REMAINING CHALLENGES AND BARRIERS OF THIS PROJECT

- ■The diversity of electrified powertrains is quickly increasing. Our goal is to develop full vehicle models for various types of powertrains. Prototype powertrain examples will be added based on feedback from DOE and industry
- Maintain latest versions of different tools (30+ software currently used)
- Access to latest component and vehicle test data is required to maintain state-of-the art models and controls



NEXT STEPS

- Continue to enhance AMBER functionalities based on users feedback and DOE needs
- Evaluate the benefits of advanced technologies across different vehicle classes, timeframes, uncertainties and scenarios (standards, real world...)
- Develop and deploy compiled tunable vehicle models of representative vehicles (license free)



PROPOSED FUTURE RESEARCH BEYOND THIS PROJECT

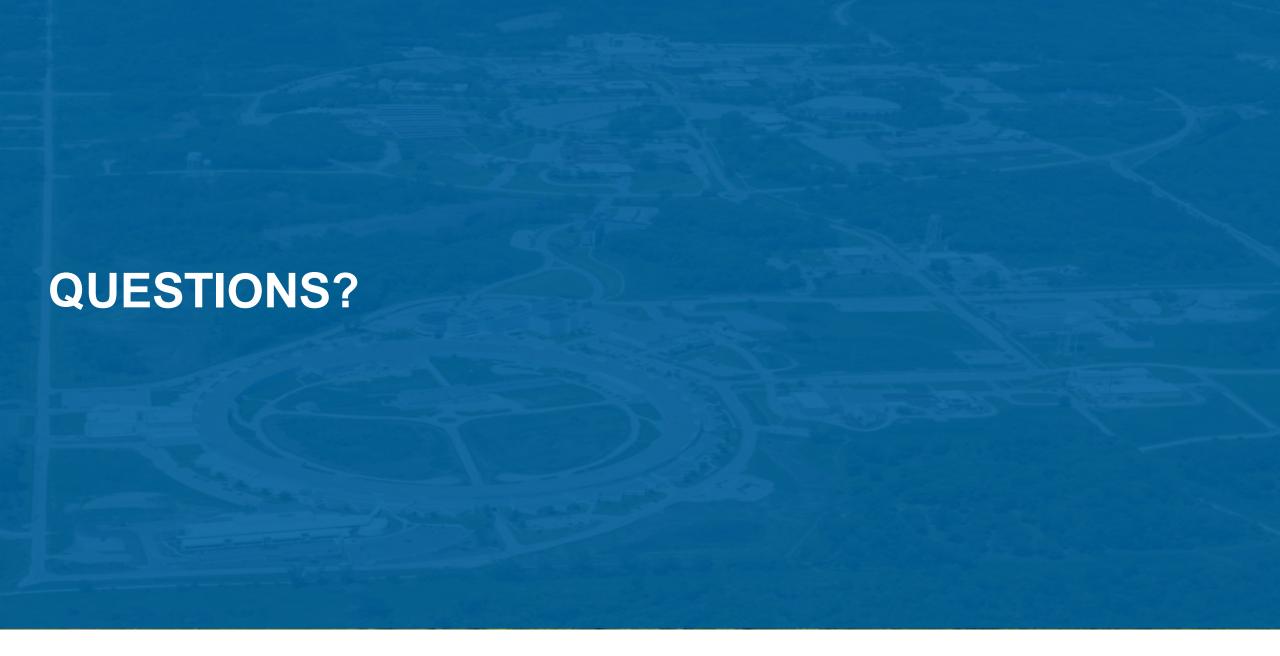
- Expand current workflows and add new ones to include additional tools, both commercially available and developed by US Government funding.
 - -Eg. RoadRunner, SVTrip, Polaris
- Improve models with focus on medium and heavy duty (e.g. thermal models to include cooling system) and powertrain electrification (e.g., new architectures, specific MD/HD designs)

Any proposed future work is subject to change based on funding levels

SUMMARY

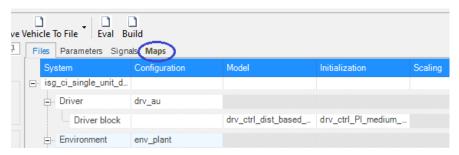
- Autonomie is used widely across government, industry & academic organizations.
 - Autonomie 2020 is now released.
 - AMBER expands Autonomie capabilities (e.g., large scale simulation...).
- New functionalities have been added to support
 - Editing 2D maps and other model parameters through the GUI
 - Definition of macros for reproducing configuration and file changes in vehicles
 - Defining large scale simulations studies through the GUI
 - New MD & HD sizing processes with inputs from 21CTP

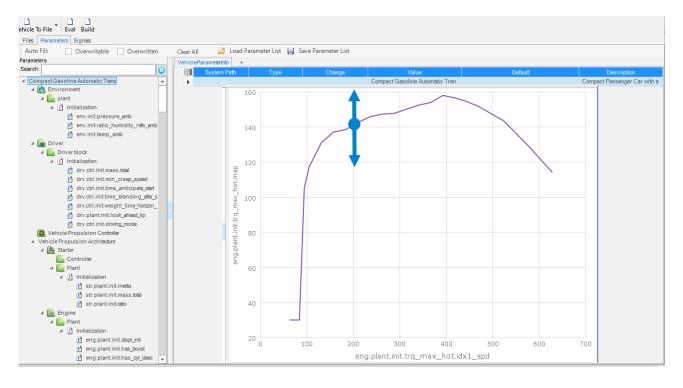






EDIT PERFORMANCE AND CONTROLLER CALIBRATION MAPS IN THE UI - A LONG TIME USER REQUEST





- OEMs and DOE studies benefit from having parameterized maps
- Works with
 - Parametric studies
 - Optimization routines
- Control Designer workflow becomes possible

1D Maps can now be modified just like scalar quantities



ADDITIONAL VEHICLE SYSTEM SIMULATION IMPROVEMENTS IN AUTONOMIE

New powertrains

- Light Duty: Hybrid with dual clutch transmission (DCT) & integrated motor with an optional motor on rear axle (similar to hybrid version of Honda Jazz & Acura MDX).
- Heavy duty electrified powertrain examples with 2 or more gears are under development.

Model improvements

- Improved shifting algorithms for HD vehicles (e.g., gear skipping)
- HD control improvements for handling extreme grades, launch and creep situations.
- Customizable cost and mass calculation functions for each component in AMBER.
- Added the contribution of major aerodynamic improvement devices for HD Tractors
 - E.g. Boat tails, side skits, fairing, gap reducers etc. based on published information
- Fully tunable, compiled vehicle models. APIs are developed for compiling and running the compiled models.



POWERTRAIN SPECIFIC IMPROVEMENTS (CLASS 6 DELIVERY)

Improvements are dependent on drive cycles.

- This data set for Class 6 vans have significant highway component.
 - HEVs do not show a big improvement over Conv for this data set.
 - PHEVs & BEVs show larger improvement in mpgde.
 - This includes both CD&CS operation of PHEVs.
 More than half of the cycles are drivable in all electric mode.
- Components are sized to meet the daily driving requirements.
 - Sizing logic was updated based on feedback from 21CTP*

